

# **RL78/G13**

R01AN2589EJ0200 Rev. 2.00 July 01, 2015

# Timer Array Unit (PWM Output) CC-RL

# Introduction

This application note describes the PWM output function of the timer array unit (TAU). This unit changes the PWM output duty ratio and inverts the LED indication at 500 ms intervals.

# **Target Device**

RL78/G13

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

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# 1. Specifications

This application note describes the PWM output function which is realized using channel 0 as the master and channel 1 as the slave in simultaneous channel operation mode. The brightness of the LEDs is controlled by connecting the PWM output to LED1 (for PWM output). Timing signals with fixed cycle time (500 ms) are created by counting the number of timer interrupts (INTTM00) generated by channel 0. Using these timing signals, the duty ratio of the PWM output is changed and the output of LED2 (for updating) is inverted.

Table 1.1 shows the Required Peripheral Function and Its Use. Figure 1.1 presents an Overview of PWM Output Operation. Table 1.2 shows the Relation between PWM Output Duty Ratios and LED Brightnesses. Figure 1.2 is a Simplified Timing Chart for PWM Output Operation.

Table 1.1 Required Peripheral Function and Its Use

Peripheral function	Use		
Timer array unit 0	This unit is used to realize the PWM function by operating channel 0 and channel 1 together and deliver a PWM output from the TO01 pin.		

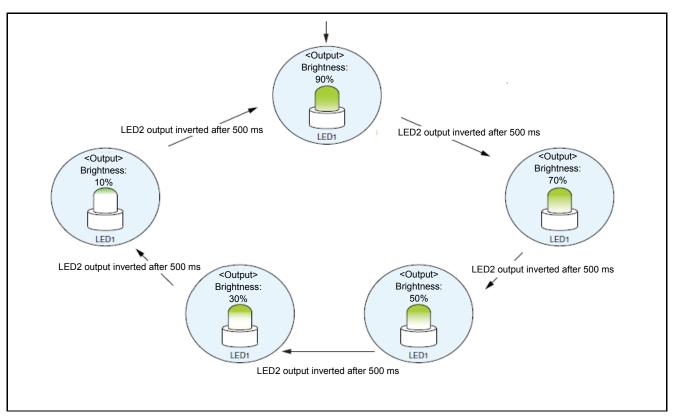


Figure 1.1 Overview of PWM Output Operation

Table 1.2 Relation between PWM Output Duty Ratios and LED Brightnesses

Duty ratio	LED1 brightness
10%	90%
30%	70%
50%	50%
70%	30%
90%	10%

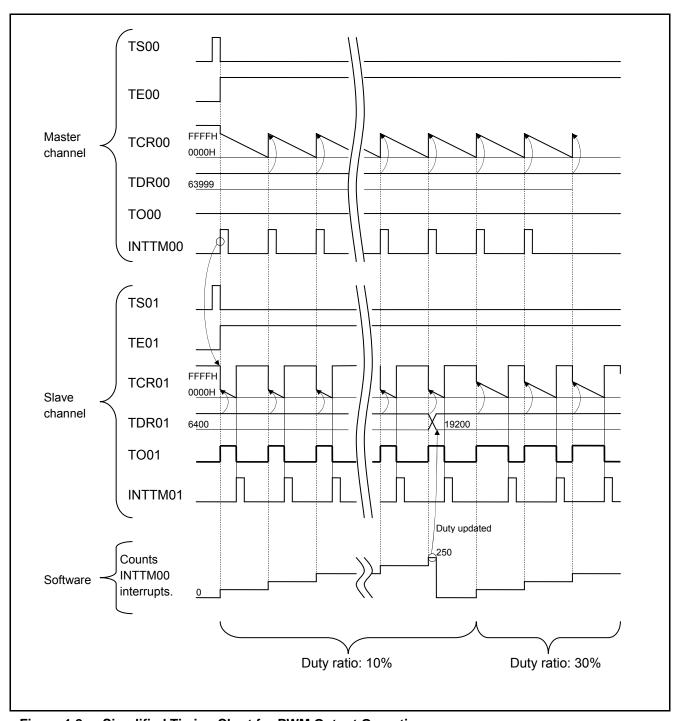


Figure 1.2 Simplified Timing Chart for PWM Output Operation

# 2. Operation Check Conditions

The sample code described in this application note has been checked under the conditions listed in the table below.

**Table 2.1 Operation Check Conditions** 

Item	Description
Microcontroller used	RL78/G13 (R5F100LEA)
Operating frequency	High-speed on-chip oscillator (HOCO) clock: 32 MHz
	CPU/peripheral hardware clock: 32 MHz
Operating voltage	5.0 V (Operation is possible over a voltage range of 2.9 V to 5.5 V.)
	LVD operation ( $V_{LV_{\rm D}}$ ): Reset mode which uses 2.81 V (2.76 V to 2.87 V)
Integrated development	CS+ for CC V3.01.00 from Renesas Electronics Corp.
environment (CS+)	
C compiler (CS+)	CC-RL V1.01.00 from Renesas Electronics Corp.
Integrated development	e <sup>2</sup> studio V4.0.0.26 from Renesas Electronics Corp.
environment (e <sup>2</sup> studio)	
C compiler (e <sup>2</sup> studio)	CC-RL V1.01.00 from Renesas Electronics Corp.

# 3. Related Application Note

The application note that is related to this application note is listed below for reference.

• RL78/G13 Initialization (R01AN2575E) Application Note

# **Description of the Hardware**

#### 4.1 **Hardware Configuration Example**

Figure 4.1 shows an example of the Hardware Configuration used for this application note.

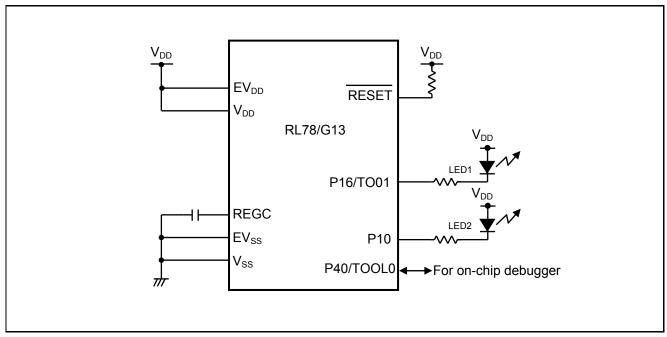


Figure 4.1 **Hardware Configuration** 

- Caution: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to  $V_{DD}$ or  $V_{SS}$  via a resistor).
  - 2. Connect any pins whose name begins with EV<sub>SS</sub> to V<sub>SS</sub> and any pins whose name begins with EV<sub>DD</sub> to V<sub>DD</sub>, respectively.
  - 3.  $V_{DD}$  must be held at not lower than the reset release voltage ( $V_{LVD}$ ) that is specified as LVD.

#### 4.2 List of Pins to be Used

Table 4.1 lists the Pins to be Used and Their Functions.

Pins to be Used and Their Functions Table 4.1

Pin Name	1/0	Description
P16/TO01	Output	PWM output port
P10	Output	Output port for LED indications

# 5. Description of the Software

# 5.1 Operation Outline

The sample program covered in this application note implements PWM by operating channel 0 and channel 1 together, and delivers a PWM output from P16/TO01.

Also, this program detects 250 timer interrupts (INTTM00) with 2 ms cycle time which are generated by channel 0. Then, it changes the PWM output duty ratio and inverts the LED indication at 500 ms intervals.

(1) Initialize the TAU.

<Conditions for setting>

- Set the P16/TO01 pin to a PWM output.
- Set TAU0 channel 0 to 2-ms cycle interval timer mode.
- Set TAU0 channel 1 to one-count mode.
- Initialize the duty ratio of the PWM output to 10 %.
- Use timer interrupts (INTTM00) from timer channel 0.
- (2) Operation starts when both the operation enable trigger bits for TAU0's channel 0 and channel 1 are set to 1 simultaneously. The sample program executes a HALT instruction to wait for a timer interrupt (INTTM00) from channel 0.
- (3) After the start of timer operation, channel 0 generates a timer interrupt (INTTM00) at 2 ms intervals.
- (4) When the HALT mode is canceled by a timer interrupt (INTTM00) from channel 0, the sample program starts counting the number of INTTM00 interrupts generated. After channel 0 has generated 250 timer interrupts (i.e., after 500 ms), the sample program updates the channel 1 count value and changes the duty ratio. This duty ratio is increased from 10% to 90% (10% → 30% → 50% → 70% → 90%). It is incremented by 20% each time the number of channel 0 timer interrupts (INTTM00) generated reaches 250. (Thus, it is incremented at 500 ms intervals). It is reset to 10% after it becomes 90%.
- (5) After processing timer interrupts (INTTM00) from channel 0, the sample program executes another HALT instruction and waits for the next timer interrupt (INTTM00) from channel 0.

# 5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

**Table 5.1 Option Byte Settings** 

Address Value		Description
000C0H/010C0H	01101110B	Disables the watchdog timer.
		(Stops counting after the release from the reset state.)
000C1H/010C1H	01111111B	LVD reset mode which uses 2.81 V (2.76 V to 2.87 V)
000C2H/010C2H	11101000B	HS mode, HOCO: 32 MHz
000C3H/010C3H	10000100B	Enables the on-chip debugger.

# 5.3 List of Constant

Table 5.2 lists the constant that is used in this sample program.

Table 5.2 Constant for the Sample Program

Constant	Setting	Description
_1900_TAU_TDR01_VALUE	0x1900U	TDR01 setting for a 10% duty ratio

# 5.4 List of Functions

Table 5.3 lists the Functions that are used in this sample program.

Table 5.3 Functions

Function	Outline		
R_TAU0_Channel0_Start	TAU0 channel 0 start processing		
r_tau0_channel0_interrupt	TAU0 channel 0 timer interrupt processing		

#### 5.5 **Function Specifications**

Shown below are the functions that are used in this sample program.

[Function Name] R_TAU0_Channel0_Start					
Synopsis	TAU0 channel 0 start processing				
Header	#include "r_cg_macrodriver.h"				
	#include "r_cg_timer.h"				
	#include "r_cg_userdefine.h"				
Declaration	void R_TAU0_Channel0_Start(void)				
Explanation	This function unmasks TAU0 channel 0 interrupts and starts count operation.				
Arguments	None				
Return value	None				
Remarks	None				

[Function Name] r	_tau0_channel0_interrupt
Synopsis	Channel 0 timer interru

rupt processing

Header r\_cg\_timer.h

Declaration static void \_\_near r\_tau0\_channel0\_interrupt(void)

This function counts the number of INTTM00 interrupts generated. Each time the **Explanation** 

count reaches 250, it updates the duty ratio of a PWM output. (Thus, it updates the

duty ratio at 500 ms intervals.)

None **Arguments** Return value None None **Remarks** 

# 5.6 Flowcharts

Figure 5.1 shows the Overall Flow of the sample program described in this application note.

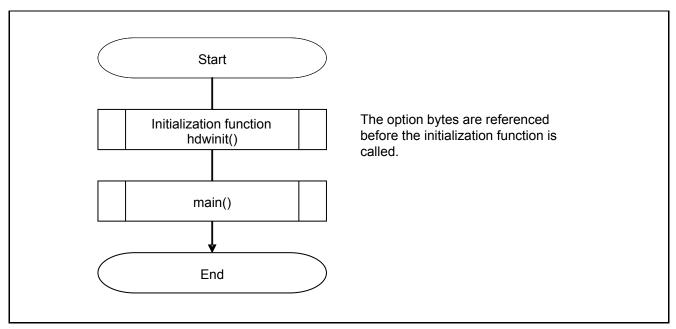


Figure 5.1 Overall Flow

Note: Startup routine is executed before and after the initialization function.

# 5.6.1 Initialization Function

Figure 5.2 shows the flowchart for the Initialization Function.

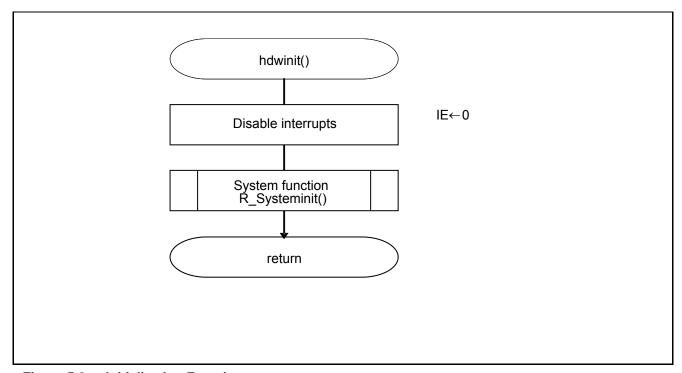


Figure 5.2 Initialization Function

# 5.6.2 System Function

Figure 5.3 shows the flowchart for the System Function.

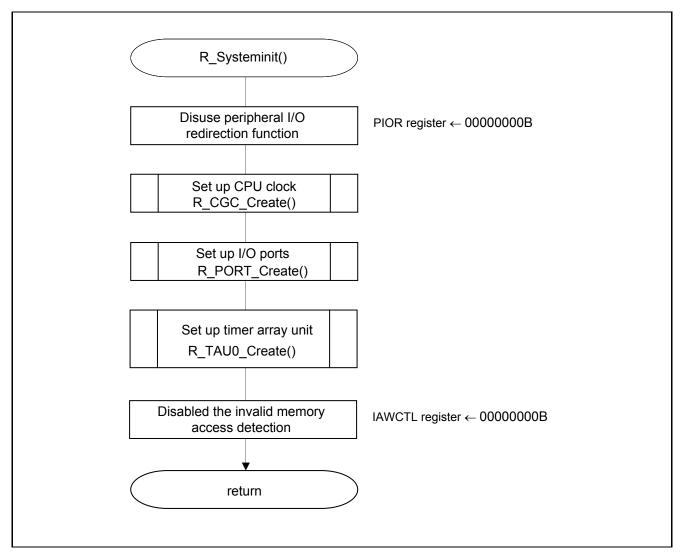


Figure 5.3 System Function

# 5.6.3 I/O Port Setup

Figure 5.4 shows the flowchart for setting up the I/O ports.

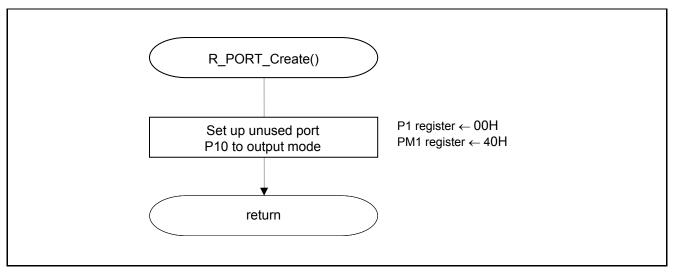


Figure 5.4 I/O Port Setup

Note: Refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575E) for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to  $V_{DD}$  or  $V_{SS}$  via a separate resistor.

Setting up the LED pin to indicate updating of the duty ratio

• Port mode register (PM1)

Select I/O mode for PM10.

Symbol: PM1

7	6	5	4	3	2	1	0
PM17	PM16	PM15	PM14	PM13	PM12	PM11	PM10
Х	Х	Х	Х	Х	Х	Х	0

Bit 0

PM10	PM10 I/O mode selection			
0	Output mode (output buffer on)			
1	Input mode (output buffer off)			

# 5.6.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.

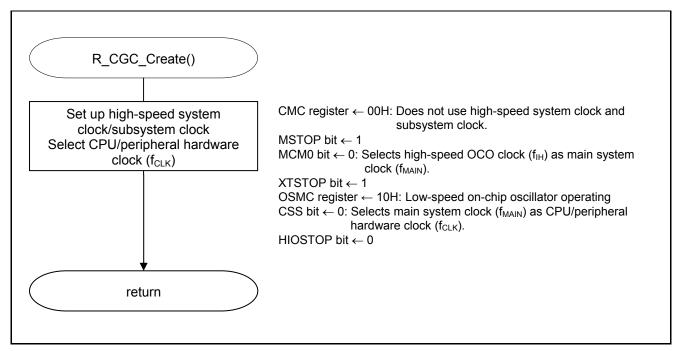


Figure 5.5 CPU Clock Setup

Caution: For details on the procedure for setting up the CPU clock (R\_CGC\_Create ()), refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575E).

# 5.6.5 Timer Array Unit Setup

Figure 5.6 and 5.7 show the flowchart for setting up the timer array unit.

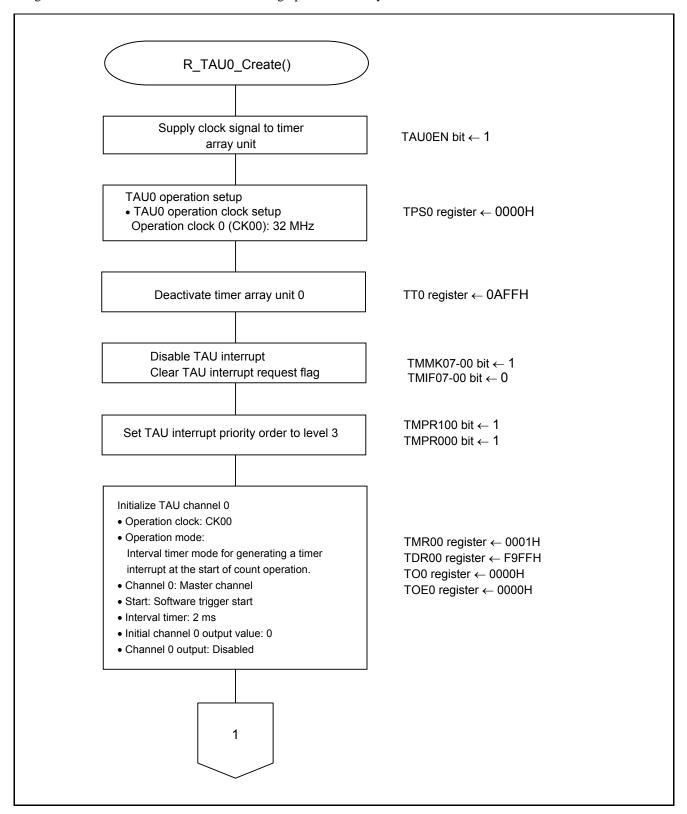


Figure 5.6 Timer Array Unit Setup (1/2)

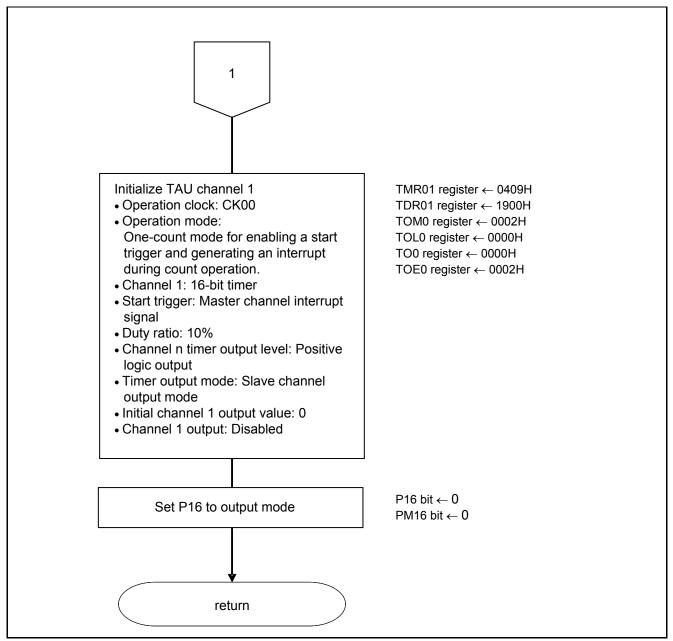


Figure 5.7 Timer Array Unit Setup (2/2)

Starting clock signal supply to the timer array unit  $\boldsymbol{0}$ 

• Peripheral enable register 0 (PER0) Start clock signal supply to the timer array unit 0.

Symbol: PER0

7	6	5	4	3	2	1	0
RTCEN	IICA1EN	ADCEN	IICA0EN	SAU1EN	SAU0EN	TAU1EN	TAU0EN
Х	Х	Х	Х	Х	Х	Х	1

# Bit 0

TAU0EN	Control of timer array unit 0 input clock supply							
0	Stops input clock supply.							
1	Enables input clock supply.							

Configuring the timer clock frequency

• Timer clock select register 0 (TPS0) Select an operation clock for timer array unit 0.

Symbol: TPS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	PRS 031	PRS 030	0	0	PRS	PRS	PRS	PRS 012			PRS 003		PRS 001	PRS 000
ŀ	Х	Х	X	Х	Х	Х	X	X	Х	X	Х	Х	0	0	0	0

Bits 3 to 0

DDC	DDC	DDC	DDC		Operation clock (CK00) selection									
PRS 003	PRS 002	PRS 001	PRS 000		f <sub>CLK</sub> = 2 MHz	f <sub>CLK</sub> = 5 MHz	f <sub>CLK</sub> = 10 MHz	f <sub>CLK</sub> = 20 MHz	f <sub>CLK</sub> = 32 MHz					
0	0	0	0	f <sub>CLK</sub>	2 MHz	5 MHz	10 MHz	20 MHz	32 MHz					
0	0	0	1	f <sub>CLK</sub> /2	1 MHz	2.5 MHz	5 MHz	10 MHz	16 MHz					
0	0	1	0	f <sub>CLK</sub> /2 <sup>2</sup>	500 kHz	1.25 MHz	2.5 MHz	5 MHz	8 MHz					
0	0	1	1	f <sub>CLK</sub> /2 <sup>3</sup>	250 kHz	625 kHz	1.25 MHz	2.5 MHz	4 MHz					
0	1	0	0	f <sub>CLK</sub> /2 <sup>4</sup>	125 kHz	312.5 kHz	625 kHz	1.25 MHz	2 MHz					
0	1	0	1	f <sub>CLK</sub> /2 <sup>5</sup>	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	1 MHz					
0	1	1	0	f <sub>CLK</sub> /2 <sup>6</sup>	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	500 kHz					
0	1	1	1	f <sub>CLK</sub> /2 <sup>7</sup>	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	250 kHz					
1	0	0	0	f <sub>CLK</sub> /2 <sup>8</sup>	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	125 kHz					
1	0	0	1	f <sub>CLK</sub> /2 <sup>9</sup>	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	62.5 kHz					
1	0	1	0	f <sub>CLK</sub> /2 <sup>10</sup>	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	31.25 kHz					
1	0	1	1	f <sub>CLK</sub> /2 <sup>11</sup>	976 Hz	2.44 kHz	4.88 kHz	9.76 kHz	15.63 kHz					
1	1	0	0	f <sub>CLK</sub> /2 <sup>12</sup>	488 Hz	1.22 kHz	2.44 kHz	4.88 kHz	7.81 kHz					
1	1	0	1	f <sub>CLK</sub> /2 <sup>13</sup>	244 Hz	610 Hz	1.22 kHz	2.44 kHz	3.91 kHz					
1	1	1	0	f <sub>CLK</sub> /2 <sup>14</sup>	122 Hz	305 Hz	610 Hz	1.22 kHz	1.95 kHz					
1	1	1	1	f <sub>CLK</sub> /2 <sup>15</sup>	61 Hz	153 Hz	305 Hz	610 Hz	976 Hz					

Setting up the channel 0 operation mode

• Timer mode register 00 (TMR00)

Select an operation clock ( $f_{MCK}$ ).

Select a count clock.

Select a start trigger and capture trigger.

Select a valid edge for timer input.

Set up the operation mode.

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1

#### Bits 15 and 14

CKS001	CKS000	Selection of operation clock (f <sub>MCK</sub> ) of channel 0
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

### Bit 12

CCS00	Selection of count clock (f <sub>TCLK</sub> ) of channel 0
0	Operation clock (f <sub>MCK</sub> ) specified by the CKSmn0 and CKSmn1 bits
1	Valid edge of input signal input from the TImn pin

# Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1

# Bits 10 to 8

STS002	STS001	STS000	Setting of start trigger or capture trigger of channel 0
0	0	0	Only software trigger start is valid (other trigger sources are unselected).
0	0	1	Valid edge of the TI00 pin input is used as both the start trigger and capture trigger.
0	1	0	Both the edges of the TI00 pin input are used as a start trigger and a capture trigger.
1	0	0	Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).
Othe	er than abo	ove	Setting prohibited

# Bits 7 and 6

CIS001	CIS000	Selection of TI00 pin input valid edge							
0	0	Falling edge							
0	1	Rising edge							
1	0	Both edges (when low-level width is measured)							
I	0	Start trigger: Falling edge, Capture trigger: Rising edge							
4	1	Both edges (when high-level width is measured)							
I	Start trigger: Rising edge, Capture trigger: Falling edge								

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1

Bits 3 to 0

MD 003	MD 002	MD 001	MD 000	Operation mode of channel 0	Related function	TCR counting operation				
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down				
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up				
0	1	1	0	Event counter mode	External event counter	Counting down				
1	0	0	1/0	One-count mode	Delay counter / One-shot pulse output / PWM output (slave)	Counting down				
1 1 0 0 Capture & one-count mo		-	Measurement of high-/low-level width of input signal	Counting up						
Oth	er tha	an ab	ove	Setting prohibited	Setting prohibited					

The MD000 bit operation varies depending on the operation mode (see the table below)

The ME ood of operation varies depe	numg on	the operation mode (see the table below)
Operation mode (Value set by the MD003 to MD001 bits) (see table above)	MD000	TCR counting operation
<ul><li>Interval timer mode (0, 0, 0)</li><li>Capture mode (0, 1, 0)</li></ul>	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
Capture & one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time interrupt is not generated, either.
Other than above		Setting prohibited

Setting up the channel 1 operation mode

• Timer mode register 01 (TMR01)

Select an operation clock (f<sub>MCK</sub>).

Select a count clock.

Select the 16/8-bit timer.

Select a start trigger and capture trigger.

Select a valid edge for timer input.

Set up the operation mode.

# Symbol: TMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CK	S CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
01	1 010	ı	01	T01	012	011	010	11	10			13	12	11	10
0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

# Bits 15 and 14

CKS011	CKS010	Channel 1 operation clock (f <sub>MCK</sub> ) selection
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

### Bit 12

CCS01	Selection of count clock (f <sub>TCLK</sub> ) of channel 1							
0 Operation clock (f <sub>MCK</sub> ) specified with the CKS010 and CKS011 bits								
1	Valid edge of the input signal from the TI01 pin							

### Bit 11

SPLIT01	Selection of 8 or 16-bit timer operation for channel 1
0	Operates as 16-bit timer (Operates in independent channel operation function or as slave channel in simultaneous channel operation function.)
1	Operates as 8-bit timer.

# Symbol: TMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
011	010		01	T01	012	011	010	11	10			13	12	11	10
0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

# Bits 10 to 8

STS012	STS011	STS010	Setting of start trigger or capture trigger of channel 1						
0	0	0	Only software trigger start is valid (other trigger sources are unselected).						
0	0	1	Valid edge of the Tl01 pin input is used as both the start trigger and capture trigger.						
0	1	0	Both the edges of the TI01 pin input are used as a start trigger and a capture trigger.						
1	0	0	Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).						
Othe	ers than al	oove	Setting prohibited						

# Bits 7 and 6

CIS011	CIS010	Selection of TI01 pin input valid edge
0	0	Falling edge
0	1	Rising edge
1	0	Both edges (when low-level width is measured)
I	U	Start trigger: Falling edge, Capture trigger: Rising edge
1	1	Both edges (when high-level width is measured)
I	I	Start trigger: Rising edge, Capture trigger: Falling edge

# Symbol: TMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
011	010		01	T01	012	011	010	11	10			13	12	11	10
0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

# Bits 3 to 0

MD0 13	MD0 12	MD 011		- I	Related function	TCR counting operation						
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down						
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up						
0	1	1	0	Event counter mode	External event counter	Counting down						
1	0	0	1/0	One-count mode	Delay counter / One-shot pulse output / PWM output (slave)	Counting down						
1	1	1 0 Capture & Measurement of high-/low-level width of input signal		Counting up								
Oth	er tha	n abo	ove	Setting prohibited								

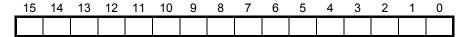
The MD010 bit operation varies depending on the operation mode (see the table below)

Operation mode (Value set by the MD013 to MD011 bits) (see table above)	MD010	TCR counting operation
<ul><li>Interval timer mode (0, 0, 0)</li><li>Capture mode (0, 1, 0)</li></ul>	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
Capture & one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time interrupt is not generated, either.
Other than above		Setting prohibited

Configuring the PWM output pulse cycle time

• Timer data register 00 (TDR00) Configure the PWM output pulse cycle time.

Symbol: TDR00



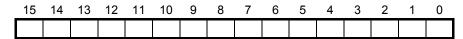
Pulse cycle time = (TDR00 setting + 1) x Count clock cycle time 2 [ms] = (1/32[MHz]) x (TDR00 setting + 1)

⇒ TDR00 setting = 63999

Configuring the PWM output duty ratio

• Timer data register 01 (TDR01) Configure the PWM output duty ratio.

Symbol: TDR01



Duty ratio =  $(TDR01 \text{ setting})/(TDR00 \text{ setting} + 1) \times 100$  $10 [\%] = (TDR01 \text{ setting})/(63999 + 1) \times 100$ 

⇒ TDR01 setting = 6400

Setting up the timer output mode

• Timer output mode register 0 (TOM0) Set up the timer output mode for each channel.

Symbol: TOM0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	TOM 07	TOM 06	TOM 05	TOM 04	TOM 03	TOM 02	TOM 01	0
ĺ	0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	1	0

Bit 1

TOM01	Channel 1 timer output mode control
()	Master channel output mode. (Output is toggled with the timer interrupt request signal (INTTM01).)
1	Slave channel output mode. (Output is set with the master channel's timer interrupt request signal (INTTM01) and reset with the slave channel's timer interrupt request signal (INTTM0p).)

Configuring the output level for the timer output pin

• Timer output level register 0 (TOL0)

Configure the output level for the timer output pin for each channel.

Symbol: TOL0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	TOL 07	TOL 06	TOL 05	TOL 04	TOL 03	TOL 02	TOL 01	0
Ì	0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	0	0

#### Bit 1

TOL01 Channel 1 timer output level control						
0	0 Positive logic output (active-high)					
1	Negative logic output (active-low)					

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Configuring the output value for the timer output pin

• Timer output register 0 (TO0) Configure the output value for the timer output pin for each channel.

Symbol: TO0

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0	TO07	TO06	TO05	TO04	TO03	TO02	TO01	TO00
0	0	0	0	0	0	0	0	х	Х	Х	Х	Х	Х	0	х

#### Bit 1

TO01	Channel 1 timer output
0	Timer output value is 0
1	Timer output value is 1

# Enabling the timer output

• Timer output enable register 0 (TOE0) Enable/disable the timer output for each channel.

Symbol: TOE0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	TOE							
	U	0	O	O	0	0	U		07	06	05	04	03	02	01	00
I	0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	1	0

# Bit 1

Timer output enable/disable of channel 1
The TO01 operation stopped by count operation (timer channel output bit).
Writing to the TO01 bit is enabled.
The TO01 pin functions as data output, and it outputs the level set to the TO01
bit.
The output level of the TO01 pin can be manipulated be software.
The TO01 operation enabled by count operation (timer channel output bit).
Writing to the TO01 bit is disabled (writing is ignored).
The TO01 pin functions as timer output, and the TOE01 bit is set or reset
depending on the timer operation.
The TO01 pin outputs the square-wave or PWM depending on the timer operation.

# Bit 0

TOE00	Timer output enable/disable of channel 0
0	The TO00 operation stopped by count operation (timer channel output bit). Writing to the TO00 bit is enabled.  The TO00 pin functions as data output, and it outputs the level set to the TO00 bit.
	The output level of the TO00 pin can be manipulated be software.
	The TO00 operation enabled by count operation (timer channel output bit).
	Writing to the TO00 bit is disabled (writing is ignored).
1	The TO00 pin functions as timer output, and the TOE00 bit is set or reset
	depending on the timer operation.
	The TO00 pin outputs the square-wave or PWM depending on the timer
	operation.

Setting up the PWM output pin

• Port mode register (PM1) Select the PM16 I/O mode.

# Symbol: PM1

7	6	5	4	3	2	1	0
PM17	PM16	PM15	PM14	PM13	PM12	PM11	PM10
Х	0	Х	Х	Х	Х	Х	Х

# Bit 6

PM16	PM16 I/O mode selection					
0 Output mode (output buffer on)						
1	Input mode (output buffer off)					

# 5.6.6 Main Processing

Figure 5.8 shows the flowchart for Main Processing.

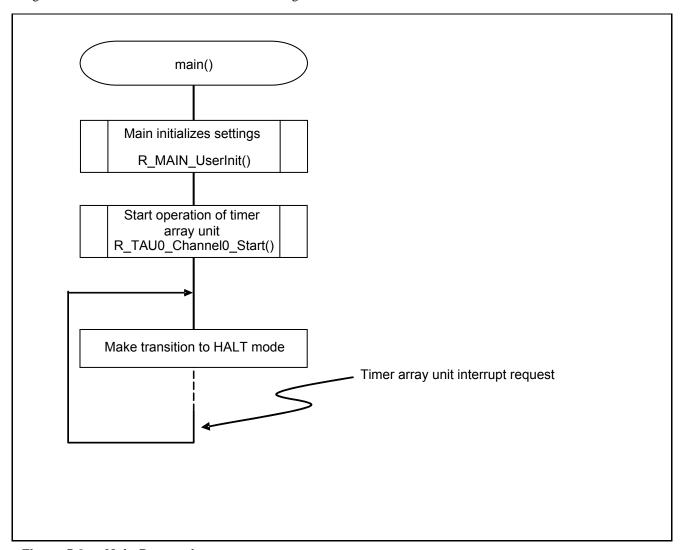


Figure 5.8 Main Processing

# 5.6.7 Main initializes settings

Figure 5.9 shows the flowchart for the main initializes settings.

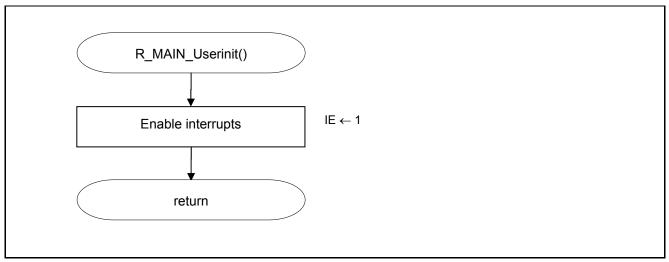


Figure 5.9 Main initializes settings

# 5.6.8 Timer Array Unit Startup

Figure 5.10 shows the flowchart for starting the operation of the timer array unit.

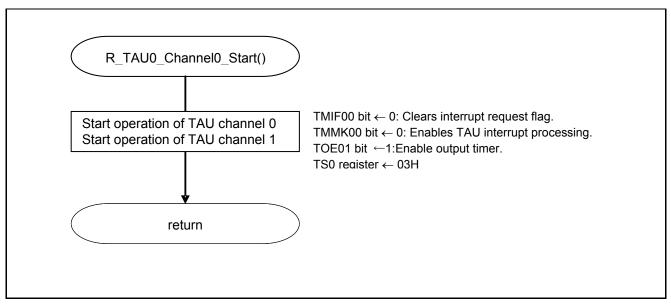


Figure 5.10 Timer Array Unit Startup

Configuring the timer count end interrupts

- Interrupt request flag register (IF1L) Clear the interrupt request flag.
- Interrupt mask flag register (MK1L) Mask interrupts.

# Symbol: IF1L

	7	6	5	4	3	2	1	0
I	TMIF03	TMIF02	TMIF01	TMIF00	IICAIF0	SREIF1	SRIF1	STIF1
						TMIF03H	CSIIF11	CSIIF10
							IICIF11	IICIF10
Ī	Х	Х	Х	0	Х	Х	Х	Х

# Bit 4

TMIF00	Interrupt request flag
0	No interrupt request signal is generated
	Interrupt request is generated, interrupt request status

# Symbol: MK1L

7	6	5	4	3	2	1	0
TMMK03	TMMK02	TMMK01	TMMK00	IICAMK0	SREMK1	SRMK1	STMK1
					TMMK03H	CSIMK11	CSIMK10
						IICMK11	IICMK10
Х	Х	Х	0	Х	Х	Х	Х

### Bit 4

TMMK00	Interrupt processing control				
0	Enables interrupt processing.				
1	Disables interrupt processing.				

# Configuring the timer startup

• Timer channel start register 0 (TS0) Enable count operation of channel 0 and channel 1.

# Symbol: TS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	TSH 03	0	TSH 01	0	TS0 8	TS0 6	TS0 5	TS0 4	TS0 3	TS0 2	TS0 1	TS0 0
1	0	0	0	0	Х	0	Х	0	Х	Х	Х	Х	Х	Х	1	1

### Bit 1

TS01	Operation enable (start) trigger of channel 1				
0	No trigger operation				
	The TE01 bit is set to 1 and the count operation becomes enabled.				
1	The TCR01 register count operation start in the count operation enabled				
	state varies depending on each operation mode.				

### Bit 0

TS00	Operation enable (start) trigger of channel 0			
0	No trigger operation			
1	The TE00 bit is set to 1 and the count operation becomes enabled.  The TCR00 register count operation start in the count operation enabled state varies depending on each operation mode.			

# 5.6.9 INTTM0 Interrupt Processing

Figure 5.11 shows the flowchart for INTTM0 interrupt processing.

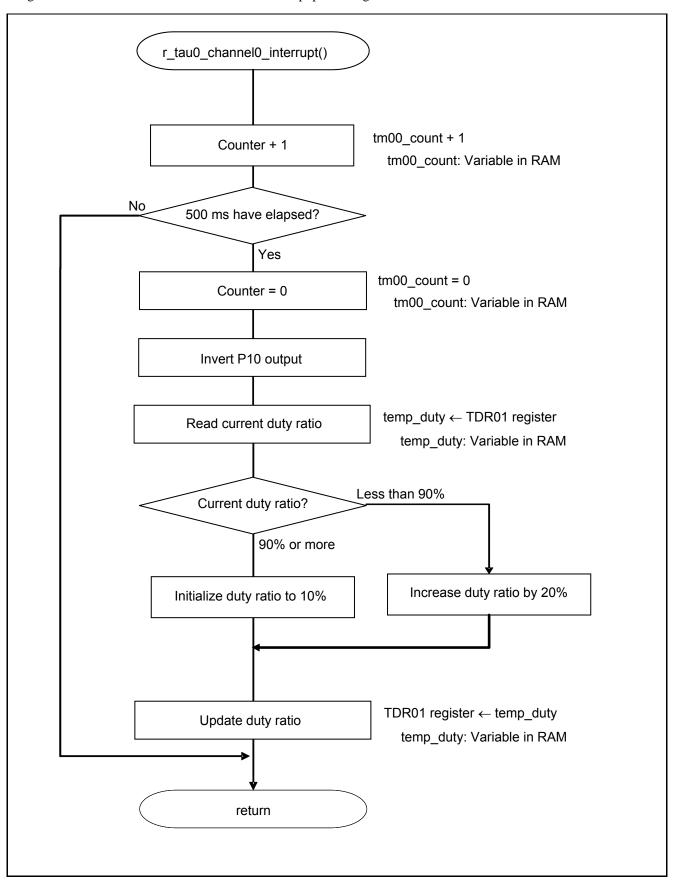


Figure 5.11 INTTM0 Interrupt Service Routine

# 6. Sample Code

The sample code is available on the Renesas Electronics Website.

# 7. Documents for Reference

User's Manual:

RL78/G13 User's Manual: Hardware (R01UH0146E) RL78 Family User's Manual: Software (R01US0015E)

The latest version can be downloaded from the Renesas Electronics website.

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REVISION HISTORY	RL78/G13 Timer Array Unit (PWM Output) CC-RL
------------------	----------------------------------------------

Rev.	Date	Description				
Nev.	Date	Page	Summary			
1.00	Jun. 01, 2015	_	First edition issued			
2.00	July 01, 2015	5	Table2.1: Added e <sup>2</sup> studio			

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The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

# 1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

# 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
  In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.
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Access to reserved addresses is prohibited.

The reserved addresses are provided for the possible future expansion of functions. Do not access
these addresses; the correct operation of LSI is not guaranteed if they are accessed.

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