

RZ/A2M Group

Iris Detection sample program

Introduction

This document describes the contents of the Iris Detection sample program.

Target Device

RZ/A2M

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1. Overview

This application note explains the sample program which detects an iris using the DRP (Dynamically Reconfigurable Processor) and the CPU.

This sample program crops and outputs any detected iris image, taken from an image captured by a camera, according to the ISO/IEC 19794-6:2011*1 standard format.

This sample program has the following features.

- 1. Robust iris detection using the ISP*2 which avoids influence from surrounding brightness conditions.
- 2. No need to capture at a close distance; an iris can be detected from an image of the entire face.
- Realtime iris detection using the DRP (Dynamically Reconfigurable Processor) mounted on the RZ/A2M.
- 4. Output iris image conforms to the requirements of the ISO/IEC 19794-6:2011 standard.

Note: 1. ISO/IEC 19794-6:2011 specifies iris image interchange formats for biometric enrolment, verification and identification systems.

2. This is the SimpleIsp function of DRP Library. For details, refer to 4.2 Simple ISP.

The following Figure 1.1 outlines the process of this sample program.

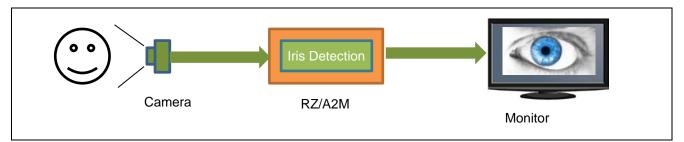


Figure 1.1 System overview of iris detection sample program

The assumed use-case of this sample program is an authentication system using cloud connection.

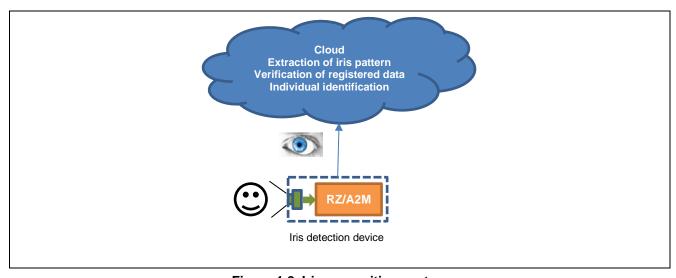


Figure 1.2 Iris recognition system

2. Operation Confirmation Conditions

Figure 2.1 shows the environment for checking the operation of this sample program. Refer to the release notes for DIP SW and jumper settings. For the display contents of the monitor, refer to Section 4.1.1 Specification of Input.

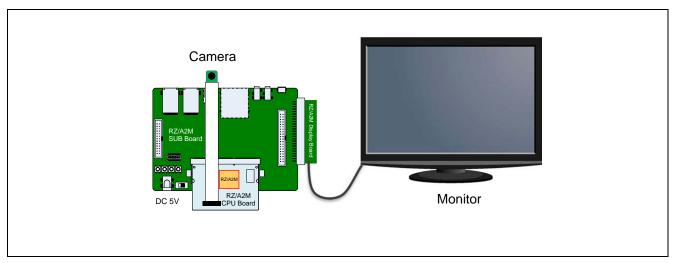


Figure 2.1 Operation check conditions

For this sample program, the cameras shown in Table 2.1 can be used. There is no difference in the connection method for each camera. It is also not necessary to change the source code.

No.1 is included in the RZ/A2M Evaluation Board Kit, so you can use it immediately after purchasing the RZ/A2M Evaluation Board Kit. No. 2 is most suitable for iris detection in darkness compared to No.1. No.3 can detect the iris at a distance of about 20 cm from the camera to the face. Compared to No.3, No.4 is best suited for detecting irises in the dark.

Table 2.1 List of available cameras

No.	Camera	Manufacturer	Distance between the camera and face	Note
1	Raspberry Pi Camera V2	Raspberry Pi Foundation	About 10 to 12 cm	Included with RZ/A2M Evaluation Board Kit
2	Raspberry Pi NoIR Camera V2	Raspberry Pi Foundation	About 10 to 12 cm	No infrared cut-off filter
3	B0102-V2 IMX219 Camera module with CS lens 2718	Arducam	About 20 cm	-
4	B0153 IMX219 Camera module with CS lens 2718	Arducam	About 20 cm	No infrared cut-off filter

The sample code of this application has been verified using the following conditions.

Table 2.2 Operation Confirmation Conditions

Item	Contents
Microcomputer	RZ/A2M
Operating frequency*1 [MHz]	CPU Clock (Iφ): 528MHz
	Image Processing Clock (Gφ): 264MHz
	Internal Bus Clock (Βφ): 132MHz
	Peripheral Clock 1 (P1φ): 66MHz
	Peripheral Clock 0 (P0φ): 33MHz
	QSPI0_SPCLK: 66MHz
	CKIO: 132MHz
Operating voltage	Power supply voltage (I/O): 3.3 V
	Power supply voltage (either 1.8V or 3.3V I/O (PVcc SPI)): 3.3V
	Power supply voltage (internal): 1.2 V
Integrated development	e2 studio
environment	(Refer to the release notes for e2 studio version.)
C compiler	GNU Arm Embedded Toolchain 6-2017-q2-update
	Compiler options (except directory path)
	Release:
	-mcpu=cortex-a9 -march=armv7-a -marm
	-mlittle-endian -mfloat-abi=hard -mfpu=neon -mno-unaligned-access
	-O2 -ffunction-sections -fdata-sections -Wunused -Wuninitialized
	-Wall -Wextra -Wmissing-declarations -Wconversion -Wpointer-arith
	-Wpadded -Wshadow -Wlogical-op -Waggregate-return -Wfloat-equal
	-Wnull-dereference -Wmaybe-uninitialized -g3 -Wstack-usage=100
	-fabi-version=0
	Hardware Debug:
	-mcpu=cortex-a9 -march=armv7-a -marm
	-mlittle-endian -mfloat-abi=hard -mfpu=neon -mno-unaligned-access
	-Og -ffunction-sections -fdata-sections -Wunused -Wuninitialized
	-Wall -Wextra -Wmissing-declarations -Wconversion -Wpointer-arith
	-Wpadded -Wshadow -Wlogical-op -Waggregate-return -Wfloat-equal
	-Wnull-dereference -Wmaybe-uninitialized -g3 -Wstack-usage=100
	-fabi-version=0
Operation mode	Boot mode 3
Board	(Serial Flash boot 3.3V) RZ/A2M CPU board RTK7921053C00000BE
board	RZ/A2M CPO board RTK7921033C00000BE
	Display Output Board RTK79210XXB00010BE
Camera	Camera for Raspberry Pi using IMX 219 CMOS sensor
Monitor	Full-WXGA (1366 x 768) monitor compatible with resolution
Device (functionality to be used	Serial flash memory allocated to SPI multi-I/O bus
on the board)	space (channel 0)
. ,	Manufacturer: Macronix Inc.
	Model Name: MX25L51245GXD
	HyperRAM [™] ² (Connected to HyperRAM ™ space)
	Manufacturer: Cypress Inc.
	Model Name: S27KS0641DPBHI020

Note: 1. The operating frequency used in clock mode 1 (Clock input of 24MHz from EXTAL pin).

2. HyperRAM [™] is a registered trademark of Cypress Semiconductor Corporation.

3. Folder Structure

For the folder structure, refer to the release note for the RZ/A2M Group IRIS Package(R01AN4584).

The following open source software is bundled with this sample program.

Table 3.1 List of open source software packaged

Name	Description
FreeRTOS	It is open source software distributed under the MIT license.
	Regarding the MIT license,
	Please refer to https://opensource.org/licenses/mit-license.php.
	FreeRTOS is a real-time operation system kernel for embedded
	microcomputers. In this sample program, Kernel v10.0.0 is used. For the
	location of the FreeRTOS source code, refer to the folder structure.

4. Sample Program

This section describes the iris processing, the specification of input and output, and the memory footprint.

Iris processing consists of three functions: "Simple ISP", "Circle Detection", and "Cropping Image".

Please refer to Section 4.2 Simple ISP ~ 4.4 Cropping Image for details of each function.

- 1. Simple ISP: Controls camera exposure and suppresses noise for improved image quality and enhanced accuracy of iris detection.
- 2. Circle Detection: Detects circles in the image processed by the Simple ISP.
- 3. Cropping Image: Crops and outputs an image from the Circle Detection result which conforms to the requirements of ISO/IEC 19794-6:2011.

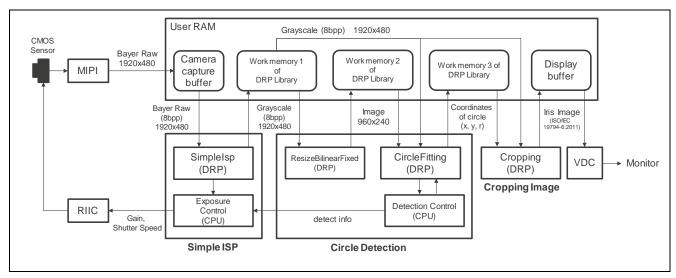


Figure 4.1 System block of iris detection sample program

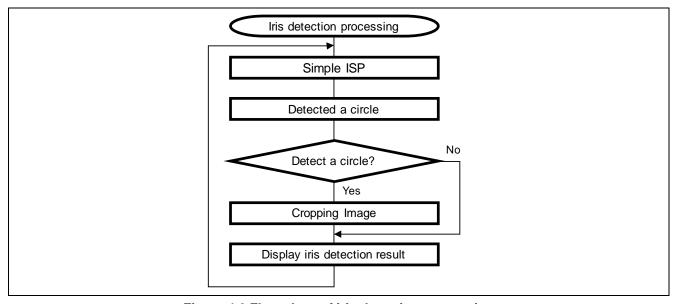


Figure 4.2 Flow chart of iris detection processing

4.1 **Specification of Input / Output**

4.1.1 **Specification of Input**

The input specification is shown in Table 4.1 Camera settings.

The Auto Exposure (AE) can be turned on/off by pushing SW3 on the Sub board.

Table 4.1 Camera settings

Input image format	Bayer format 8[bit per pixel]
Image capture size	1920×480
Capture frame rate	Capture frame rate will fluctuate, by ON/OFF of 4.2.1Auto Exposure Correction (AE). ON: 12~24fps*1 OFF: 20fps*2

Note 1. The set value is 24 fps. However, it fluctuates between 12 and 24 fps due to changes in shutter

4.1.2 **Specification of Output**

This sample program outputs an iris image which conforms to the requirements of ISO/IEC 19794-6:2011. This image is then output to a monitor.

The output format for the monitor is shown Table 4.2.

Table 4.2 Monitor output specification

Image resolution	1366×768
Image display frame rate	60 fps

An example of monitor output is shown Figure 4.3.

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^{2.} The set value is 24 fps. However, because the shutter speed is 1/20 second, it is 20 fps.

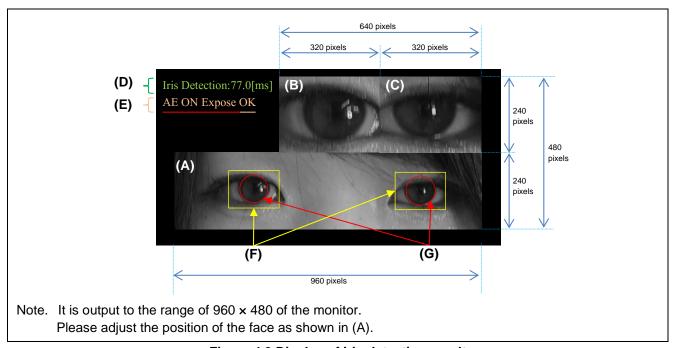


Figure 4.3 Display of iris detection result

- (A) Displays a resized image of the face captured by the camera.
- (B) Displays the left eye, cropped to meet the ISO/IEC 19794-6:2011 format requirements, when the iris of both eyes is detected.
- (C) Displays the right eye, cropped to meet the ISO/IEC 19794-6:2011 format requirements, when the iris of both eyes is detected.
- (D) Display the time taken for the whole iris detection process (from AE to cropping the image).
- (E) Display on/off status of AE and the brightness.
- (F) Displays a square frame of the cropped image according to ISO/IEC 19794-6:2011.
- (G) Displays a circular frame around the detected iris.

4.2 Simple ISP

Simple ISP controls camera exposure and suppresses noise for improved image quality and enhanced iris detection accuracy.

The image data is converted to grayscale and output, because color information is not necessary for iris detection.

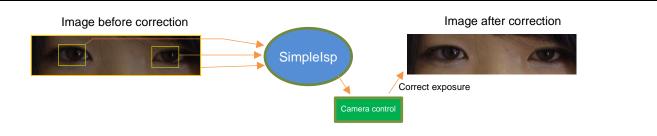
This function uses SimpleIsp of DRP Library. Please refer to "DRP Library user's manual (R01US0367)" for details of the SimpleIsp.

The explanation for this section is continued in the sample program source code "r_bcd_main.c", onwards from the comment "/* Function : Simple ISP(AE, Bayer to grayscale conversion, Noise reduction) */".

4.2.1 Auto Exposure Correction (AE)

Auto Exposure correction (AE) controls the exposure of the camera referring to the brightness output from SimpleIsp.

The CPU handles calculations of the correction value and camera control. A flowchart describing the camera control process is shown in Figure 4.5, Figure 4.6 and Figure 4.7.



Note: Calculation of the correction value depends on the previous iris detection result. If an iris is detected, it integrates the brightness of the range of the left eye and the right eye of the image where the previous iris was detected. If an iris is not detected, it integrates the brightness of the whole screen only.

Calculate average luminance from lightness

Is the average luminance greater than the target luminance value (A)?

Yes

Camera operation setting (Bright)

Yes

Camera operation setting (Dark)

Yes

Figure 4.4 Lightness integrating process

Note: The target brightness value is $\pm 10\%$ of the brightness value (100) suitable for iris detection with Table 2.1 camera. (A = 90, B = 110)

Figure 4.5 AE processing flow

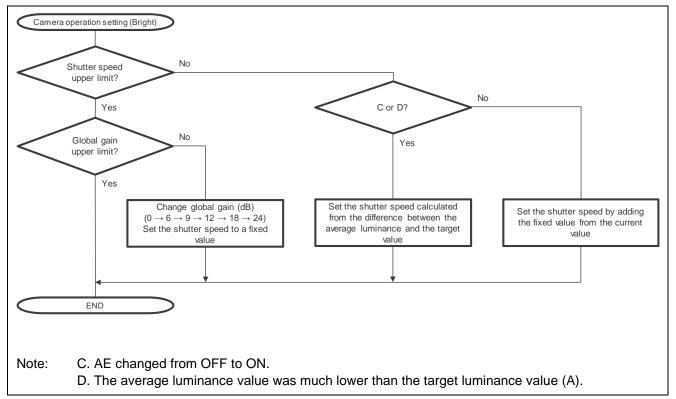


Figure 4.6 Camera operation setting (Bright) flowchart

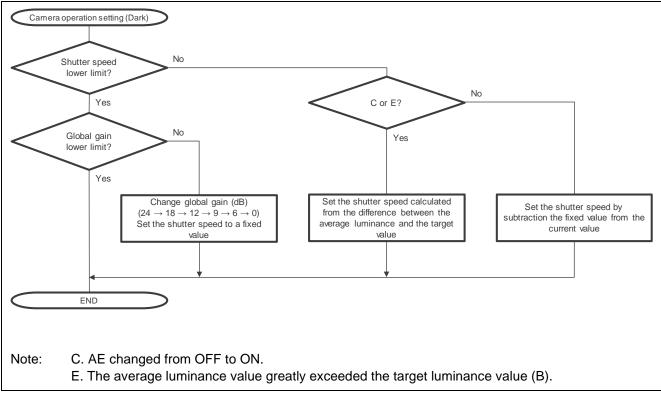


Figure 4.7 Camera operation setting (Dark) flowchart

4.2.2 Convert Format to Grayscale

Convert from Bayer Raw input to Grayscale using the SimpleIsp.

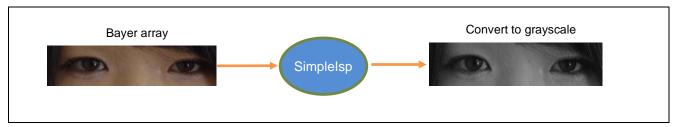


Figure 4.8 Conversion processing from Bayer array to grayscale

4.2.3 **Suppress Noise**

Suppress noise from converted grayscale image using Median filter.

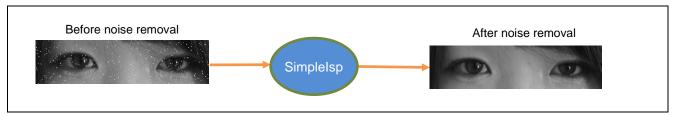


Figure 4.9 Noise Removal Processing

4.3 Circle Detection

For shortening detection time, the Circle Detection function consists of a Rough Detection step that detects the iris position roughly and a Fine Detection step that detects the iris accurately.

4.3.1 Rough Detection

The Rough Detection function detects a circle from a resized small size image. The resized small size image is only used for Rough Detection function.

This function uses the ResizeBilinearFixed function from the DRP Library. Please refer to "DRP Library user's manual (R01US0367)" for details of the ResizeBilinearFixed function.

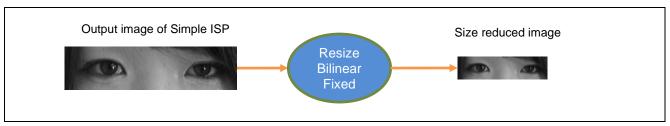


Figure 4.10 Processing to reduce image size

Detects an iris from the narrowed down pink square area that is assumed to include an eye in the resized image. The square area is fixed.

This function uses the CircleFitting function in the DRP Library. Please refer to "DRP Library user's manual (R01US0367)" for details of the CircleFitting function.

Further explanation on this section is described onwards from the comment " /* Function : Rough circle detection */" in the sample program source code "r_bcd_main.c".

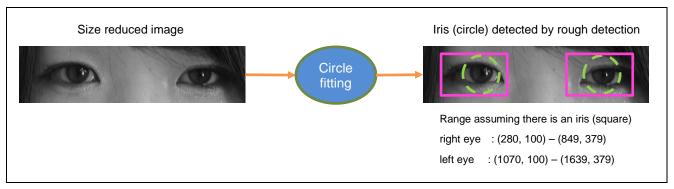


Figure 4.11 Rough detection processing

4.3.2 Fine Detection

Searches the circle accurately from the image detected by the Rough Detection function using CircleFitting and get accurate iris position.

This function uses CircleFitting of DRP Library. Please refer "DRP Library user's manual (R01US0367)" for detail of CircleFitting.

A process of explanation on this section is described in comment " /* Function : Fine circle detection */" of sample program source code "r_bcd_main.c".

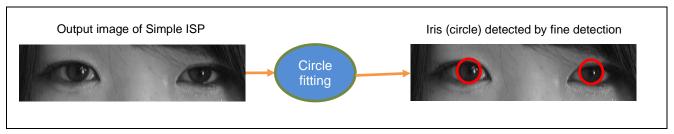


Figure 4.12 Fine Detection processing

4.4 Cropping Image

Crop from image detected by 4.3.2 Fine Detection, and output data that is conformed to the requirement of ISO/IEC 19794-6:2011.

A process of explanation on this section is described in comment " /* Function : Cropping */" of sample program source code "r_bcd_main.c".

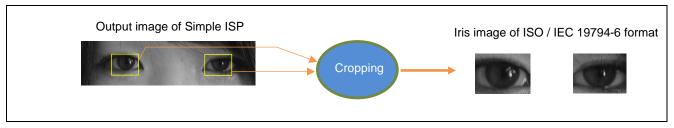


Figure 4.13 Cropping Image

4.5 Memory footprint

For the memory footprint, refer to the release note for the RZ/A2M Group IRIS Package(R01AN4584).

5. **DRP Library**

This sample program detects the iris using the DRP Library shown in Table 5.1. Refer to the DRP Library user's manual (R01US0367) for the DRP Library specifications.

Table 5.1 List of functions of the DRP Library to be used

Function name	Use
SimpleIsp	Calculation of correction value used for AE, conversion to gray scale, noise removal.
	Used in 4.2 Simple ISP.
ResizeBilinearFixed	Reducing the image.
	Used in 4.3.1 Rough Detection.
CircleFitting	Detection of iris.
	Used in 4.3.1 Rough Detection and 4.3.2 Fine Detection.
Cropping	Cropping Image.
	Used in 4.4 Cropping Image.

6. Reference Documents

User's Manual: Software

RZ/A2M Group DRP Driver User's Manual (R01US0355)

The latest version can be downloaded from the Renesas Electronics website.

RZ/A2M Group DRP Library User's Manual (R01US0367)

The latest version can be downloaded from the Renesas Electronics website.

User's Manual: Hardware

RZ/A2M Group User's Manual: Hardware

The latest version can be downloaded from the Renesas Electronics website.

RTK7921053C00000BE (RZ/A2M CPU board) User's Manual

The latest version can be downloaded from the Renesas Electronics website.

RTK79210XXB00000BE (RZ/A2M SUB board) User's Manual

The latest version can be downloaded from the Renesas Electronics website.

ARM Architecture Reference Manual ARMv7-A and ARMv7-R edition Issue C

The latest version can be downloaded from the ARM website.

Arm Cortex[™]-A9 Technical Reference Manual Revision: r4p1

The latest version can be downloaded from the ARM website.

Arm Generic Interrupt Controller Architecture Specification - Architecture version2.0

The latest version can be downloaded from the ARM website.

Arm CoreLink™ Level 2 Cache Controller L2C-310 Technical Reference Manual Revision: r3p3

The latest version can be downloaded from the ARM website.

Technical Update/Technical News

The latest information can be downloaded from the Renesas Electronics website.

User's Manual: Development Tools

Integrated development environment e2studio User's Manual can be downloaded from the Renesas

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website.

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Revision History

		Descript	ion
Rev.	Date	Page	Summary
1.00	Sep 28,2018	-	First edition issued
1.01	Apr 15,2019	4	Table 2.2: Integrated development environment version updated. Board name modified. Compiler options added.
		5	Figure 3.1 Folder Structure, updated.
1.10	May 17,2019	4	Table 2.2 Remove compiler option "-mthumb-interwork"
		5	Figure 3.1 Folder Structure, updated.
1.11	Sep 30, 2019	4	Table 2.2: Integrated development environment updated.
1.12	Dec 17, 2019	5	Figure 3.1 Folder Structure, deleted.
		16	4.5 Memory footprint, deleted.

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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