

NEC

User's Manual

16-bit 78K0R ZigBee™ PRO Premium Development Kit

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- Availability of related technical literature
- Development environment specifications (for example, specifications for third-party tools and components, host computers, power plugs, AC supply voltages, and so forth)
- Network requirements

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Chapter 1 78K0R ZigBee™ PRO Premium Development Kit

The *78K0R ZigBee™ Premium Development Kit* is the NEC Electronics 16-bit starter kit specifically designed for the development of wireless networking applications. The above platform can be used to design and develop a broad range of wireless networks from simple peer to peer to full mesh networking incorporating all of the features of a fully compliant ZigBee™ network.

The development kit contains the TK-78K0R/KG3+UZ evaluation board, which includes the 78K0R/KG3, a 16-bit single-chip microcontroller of NEC Electronics, and the UZ2400 RF board of Uniband Electronic Corporation.

1.1 Features of the TK-78K0R/KG3+UZ

Features of the TK-78K0R/KG3+UZ CPU board are as follows.

- The evaluation board uses the NEC Electronics 16-bit single chip microcontroller (μPD78F1168GC).
- All of ROM, RAM and circumference circuit are efficiently built in one chip on a single board.
- High-speed operation has been achieved with 20MHz clock.
- Sub-clock 32.768 kHz standard equipment.
- 512 kB FLASH memory and 30 kB RAM memory are built into CPU chip.
- Hardware is ready to accommodate 2.4GHz transceiver chip UZ2400 (Accordance with IEEE 802.15.4/ZigBee™ Specifications for Low Rate Wireless Personal Area Networks) made by Uniband Electronic Corporation.
(<http://www.ubec.com.tw/index.html>)
- Attached antenna Titanis made by Gigaant
(<http://www.gigaant.com>)
- A maximum of 40 I/O ports are equipped for expanded use, with an on-board temperature sensor for applications development.
(S-8120C made by SII)
(<http://www.sii.co.jp>)
- Debugging using on-chip debug function can be done.
- The board itself is quite and easy to handle: the CPU board size is 60 mm × 90 mm and the CPU board size with the RF transceiver is 60 mm × 102 mm.

Note Please inquire direct to the parts maker about specification of UZ2400 RF board, antenna and temperature sensor.

1.2 Package Content

The *78K0R ZigBee™ Premium Development Kit* consists of four TK-78K0R/KG3+UZ development board and one 78K0R_UZ_Stick which is configured to act as Air Sniffer hardware. Also supplied is the unlimited security

dongle for the 78K0R ZigBee™ Stack and ZigBee™ Software Developers Kit (ZigBee™ SDK tools).

The following software is also supplied on the accompanying CDROM.

- IAR Embedded Workbench Kickstart edition 16 kB code size limited
- IEEE 802.15.4 MAC libraries
- Different sample application programs for the 78K0R/KG3+UZ board
- Sample program for the Air Sniffer application for 78K0R_UZ_Stick

1.3 System Requirements

Host PC A PC supporting Windows 2000 or Windows XP for the IAR Systems Embedded Workbench Kickstart edition and the *78K0R ZigBee™ PRO Premium Development Kit*.

Pentium 200 MHz minimum, 128 MB of RAM, 256 colour display (1024 x 768), mouse, CD ROM drive and 200 MB of disk space are required to install the tool packages.

Host Interface USB interface that enables communication based on USB (Version 1.1 or later)

Package Contents Please verify that you have received all of the parts listed in the package contents list attached to the *78K0R ZigBee™ PRO Premium Development Kit*. If any parts are missing or seem to be damaged please contact the dealer from whom you received your *78K0R ZigBee™ PRO Premium Development Kit*.

Note Updates for the IAR Embedded workbench for 78K0R, documentation and/or utilities for the *78K0R ZigBee™ PRO Premium Development Kit* if available maybe downloaded from the NEC Electronics web pages at: <http://www.eu.necel.com/updates>

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1.4 Complementary ZigBee™ Development Platform and Hardware

Other evaluation boards and hardware available to develop a ZigBee™ network from NEC Electronics:

- ZigBee™ Starter Kit
 - 2 x 8-bit ZigBee™ node boards TK-78K0/KF2+UZ
 - IEEE 802.15.4 MAC libraries
 - Sample programs
 - IAR Embedded Workbench Kickstart Version
 - Flash programmer for 78K0
 - **Article code 78K0-ZIGBEE-SK**

- ZigBee™ Premium Development Kit for 78K0
 - 4 x 8-bit ZigBee™ node boards TK-78K0/KF2+UZ
 - 8-bit USB ZigBee™ node programmed as Air Sniffer
 - IEEE 802.15.4 MAC libraries
 - ZigBee™ Stack
 - Unlimited ZigBee™ license for the 78K0 family
 - GUI Tools (SDK)
 - Sample programs
 - IAR Embedded Workbench Kickstart Version
 - Flash programmer for 78K0
 - **Article code 78K0-ZIGBEE-PREM**
- ZigBee™ Premium Development Kit for V850
 - 1 x 32-bit ZigBee™ node boards TK-850/SG2+UZ
 - 8-bit USB ZigBee™ node programmed as Air Sniffer
 - IEEE 802.15.4 MAC libraries
 - ZigBee™ Stack
 - Unlimited ZigBee™ license for the V850 family
 - GUI Tools (SDK)
 - TCP/IP Libraries & Web Server
 - Sample programs
 - IAR Embedded Workbench Kickstart Version
 - Flash programmer for V850
 - **Article code V850-ZIGBEE-GATE**
- ZigBee™ PRO Premium Development Kit for V850
 - 1 x 32-bit ZigBee™ node boards TK-850/SG2+UZ
 - 8-bit USB ZigBee™ node programmed as Air Sniffer
 - IEEE 802.15.4 MAC libraries
 - ZigBee™ Stack
 - Unlimited ZigBee™ license for the V850 family
 - GUI Tools (SDK)
 - TCP/IP Libraries & Web Server
 - Sample programs
 - IAR Embedded Workbench Kickstart Version
 - Flash programmer for V850
 - **Article code V850-ZIGBEEPRO-GATE**

Additional single boards or modules can be purchased in case the customer needs additional hardware for Premium or Gateway kits:

- TK-78K0/KF2+UZ-EE
- 78K0_UZ_Stick-EE
- TK-78K0R/KG3+UZ-EE
- 78K0R_UZ_Stick-EE
- TK-850/SG2+UZ-EE

Chapter 2 Sample Applications

With the 78K0R ZigBee™ Premium Development Kit, three different sample programs are offered:

- RF Test program
- MAC Sample program 1: Text Chat
- MAC Sample program 2: LED Control

The “Text Chat” and the “LED Control” sample programs uses the MAC stack provided in this evaluation kit.

The TK-78K0R/KG3+UZ boards are pre-programmed with the MAC Sample Program 2, so for a quick start please go the associated section "2.3 MAC Sample Program 2: LED Control" .

2.1 RF Test Program

The RF test program is a simple program that allows various RF parameters to be configured and test signals generated. The features found in this program can be used to provide the software support functions needed for various test requirements.

In the sample provided a simple terminal program like “HyperTerminal” is required to select the relevant mode of operation. For all “HyperTerminal” sessions, please use the following settings and relevant serial port.

Table 2-1 "HyperTerminal" port settings

Baud rate	19200
Data bits	8
Parity	NONE
Stop bits	1
Flow control	NONE
Local echo	OFF
Line feed	NO

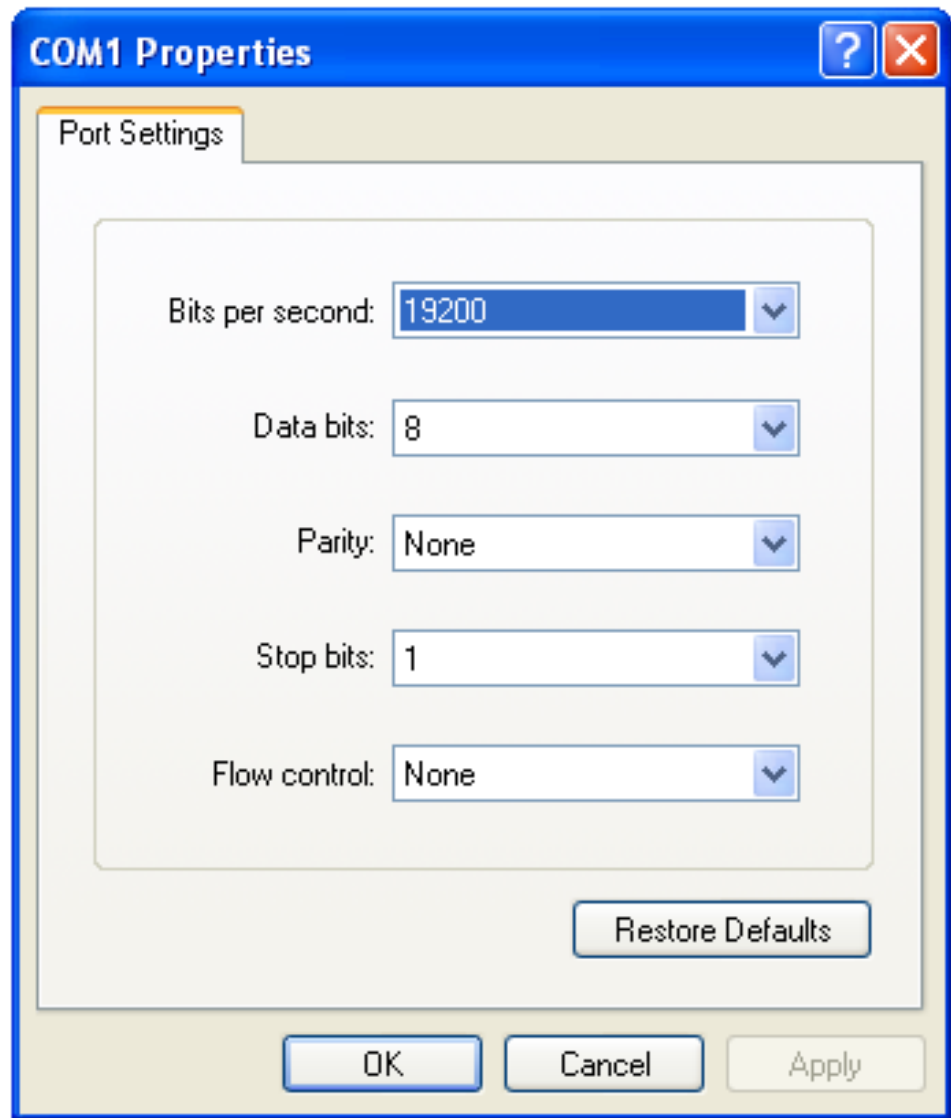


Figure 2-1 "HyperTerminal" settings

2.1.1 Procedure for One-to-One Transmit/Receive Test

Two TK-78K0R/KG3+UZ boards are needed for this test. Both boards need to be programmed with the file *TK-78K0RKG3+UZ RF test* sample program (to have more information about how to program the board, go to the section "6.1 Loading a project and programming the board")

You have to prepare two PCs, both with USB interface and hyper-terminal to control transmitter and receiver side.

The receiver sends back the test result to the transmitter where the test results are displayed.

The receiver could also work without PC, battery powered by a 9V Block.

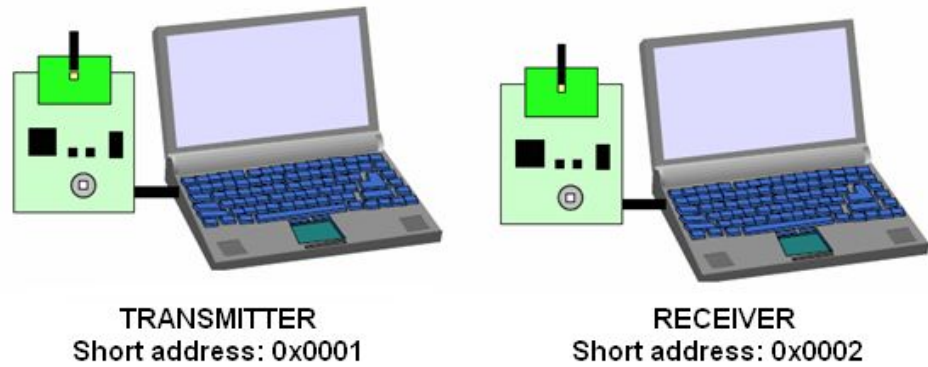


Figure 2-2 Transmitter and Receiver configuration

By switch settings, the boards can be set to transmitter or receiver mode, and the short address of each board can be selected. Please set the switches on the transmitter and the receiver board according to the tables below. Set one board as a transmitter with a short address of 0x0001 and one board as a receiver with a short address of 0x0002.

Table 2-2 Operation settings for RF Test Program

JP1		1-2 short (USB side)
SW5		UART side
SW1	Bit1	OFF
	Bit2	OFF
	Bit3	OFF
	Bit4	ON
	Bit5	ON
	Bit6	See table below for address choice
	Bit7	OFF
	Bit8	OFF for transmitter mode ON for receiver mode

Table 2-3 Address settings for RF Test Program

		Short Address			
		0001	0002	0003	0004
SW1	Bit6	OFF	ON	OFF	ON
	Bit7	OFF	OFF	ON	ON

Then connect each board to a PC with a USB cable, and open for each connection the “HyperTerminal” communication.

Before opening a “HyperTerminal” session, you need to identify the COM Port number of the USB port on your PC, in order to open and set the “HyperTerminal” with the relevant COM port. For the identification of the COM port, you can use [Control Panel] -> [System] -> [Hardware] -> [Device Manager] -> [Ports (COM & LPT)]. Then start “HyperTerminal” with settings listed in the section “2.1 RF Test Program” .

Now you will find the following opening menu on your PC screen. If not, please try the RESET button on the TK-78K0R/KG3+UZ board.

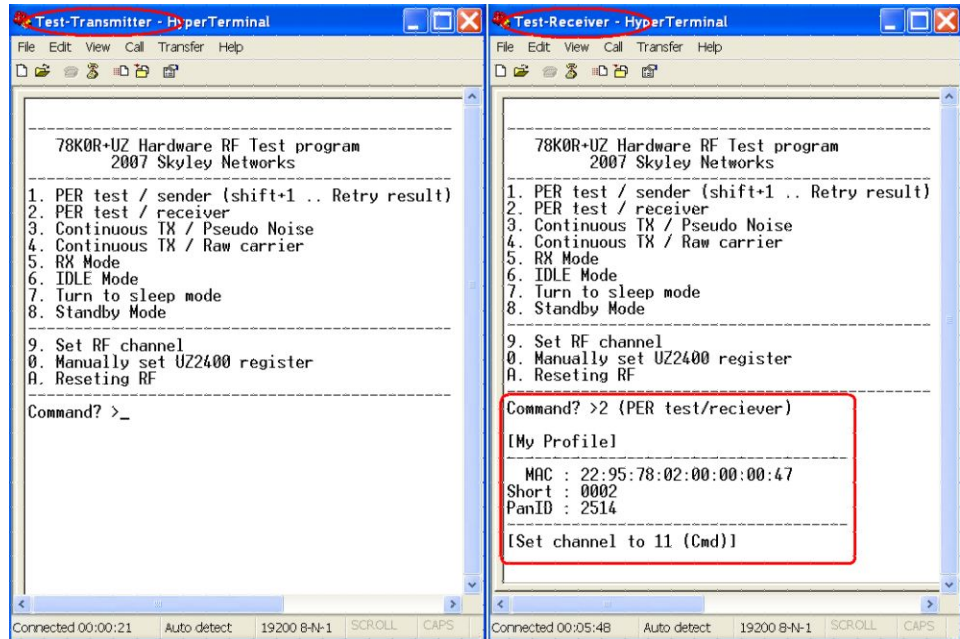


Figure 2-3 Multiple test menu for the transmitter/receiver board

As can be seen from the above, multiple test modes are available via simple single key operation.

2.1.2 Execution of the Transmit/Receive Test

To initiate the Packet Error Rate (PER) test, please press "1" in the menu of the transmitter board. You will see [My Profile] with the short address "0001". Then, you asked to enter the destination address of the PER test, as shown below.

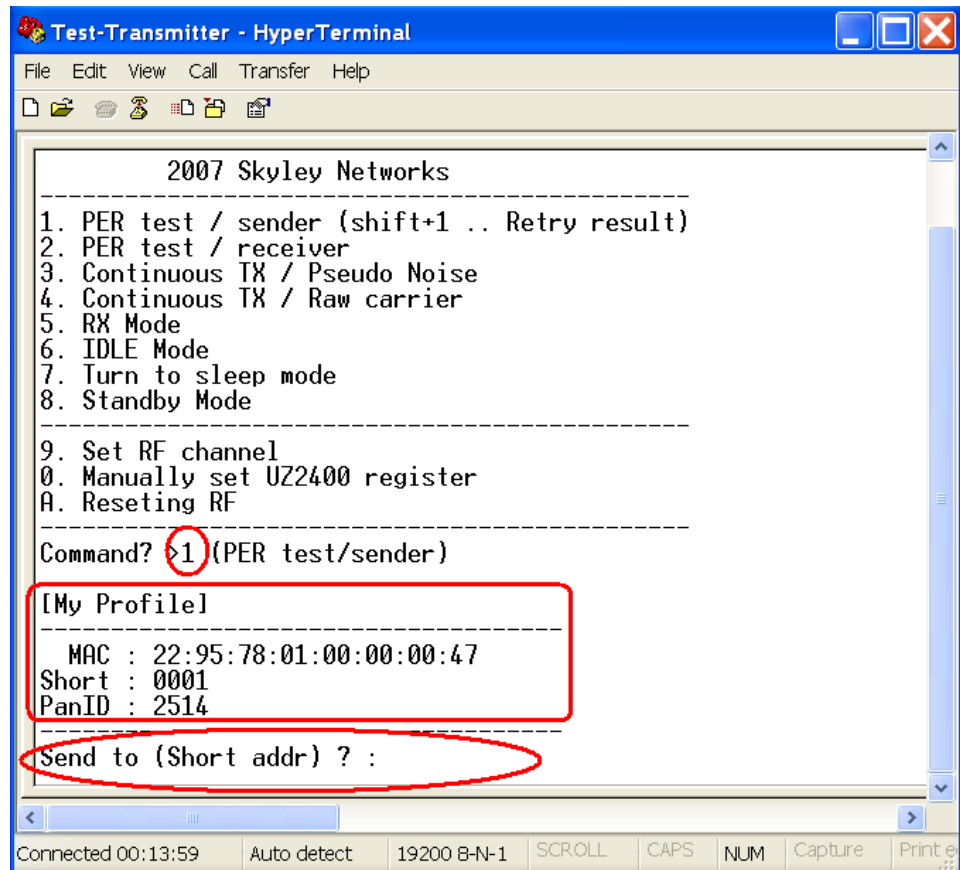


Figure 2-4 Initiate the PER test from the transmitter

Now, you may input "0002", if the address of your receiver board is set to "0002". Then, you will be asked how many packets you wish to consume in the PER test. You may input "1000".

Then, you will be asked the interval of packets in msec.

You may input "3".

Then, the PER test will be executed.

You will see:

- the number of packets sent, that is, 1000 as you selected,
- the number of the received packets,
- the calculated PER in %,
- the maximum and minimum RSSI values in the PER test.

Note PER = Packet Error Rate
RSSI = Received Signal Strength Indication

```

Test-Transmitter - HyperTerminal
File Edit View Call Transfer Help
-----
Command? 1 (PER test/sender)
[My Profile]
-----
MAC : 22:95:78:01:00:00:47
Short : 0001
PanID : 2514
-----
Send to (Short addr) ? 0002
Send count (dec) ? 1000
Interval (dec/msec) ? 3
[Set channel to 11 (Cmd)]
Prepare to send..OK
[Set channel to 11 (Current)]
Request to result..OK

[Results]
-----
From : 0001
To : 0002
-----
Sent : 1000
Recieved : 1000
PER : 0.0000%
RSSI : max FF / min FF
-----

[Set channel to 11 (Current)]
-----
Connected 00:02:25 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture

```

Figure 2-5 PER test results: PER/ RSSI indication

RSSI is expressed in the hexagonal value of 256 levels, which indicates the signal strength in the received signal. For more details of the RSSI value, please refer to the datasheet of the UZ2400 RF chip.

Please note the PER and the RSSI are measured at the receiver side.

The receiver does not send back the test packets, but only the test result.

2.1.3 Channel Setting

In the previous example, you may have noticed the RF channel used in this test is the Channel 11. The channels are specified by the IEEE 802.15.4 specification.

The channel 11 is assigned at 2405 MHz. You can change the channel in the PER test in 5MHz step to the maximum channel at 2480 MHz (Channel 26)

To do it, please press “9” in the command prompt. Then, please choose the channel by [+], [-], [A], [B], or [C]. In the example below, the Channel 23 (2465 MHz) was selected.

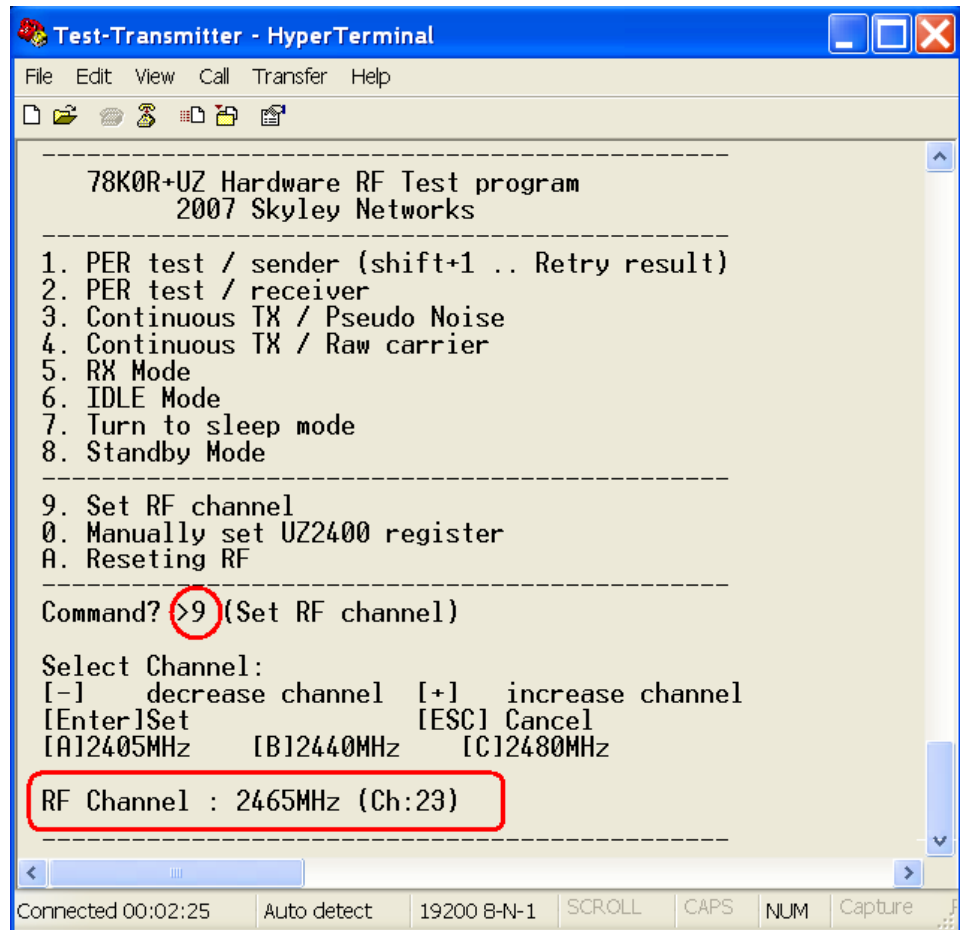


Figure 2-6 Modification of RF channel used

To execute the PER test at the channel 23, press [Enter] on your keyboard. Then choose "1" to initiate the PER test mode. Then you may input "1000" packets in "5" msec interval to see the following example. Please confirm the channel used is Channel 23 in the display. Please note the receiver will learn which channel is to be used for the test automatically.


```

Test-Transmitter - HyperTerminal
File Edit View Call Transfer Help
-----
Command? >1 (PER test/sender)

[My Profile]
-----
MAC : 22:95:78:01:00:00:47
Short : 0001
PanID : 2514
-----
Send to (Short addr) ? : 0002
Send count (dec) ? : 1000
Interval (dec/msec) ? : 5
[Set channel to 11 (Cmd)]
Prepare to send...OK
[Set channel to 23 (Current)]
Request to result...OK

[Results]
-----
From : 0001
To : 0002
-----
Sent : 1000
Recieved : 998
PER : 0.2000%
RSSI : max FF / min 53
-----
[Set channel to 23 (Current)]
-----
Connected 00:37:03 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture Print e...

```

Figure 2-7 PER test and results at Channel 23

2.1.4 Adjusting the Output Power

You may wish to control the output power in the PER test. To do so, please select “0” in the menu.

You will be asked the register number. Please input “203”.

Then you will see, “LREG[203] : 00 >”.

It means the current value at the register [203] is 0x00h, which means 0 dB. 0x00h is the reset default value.

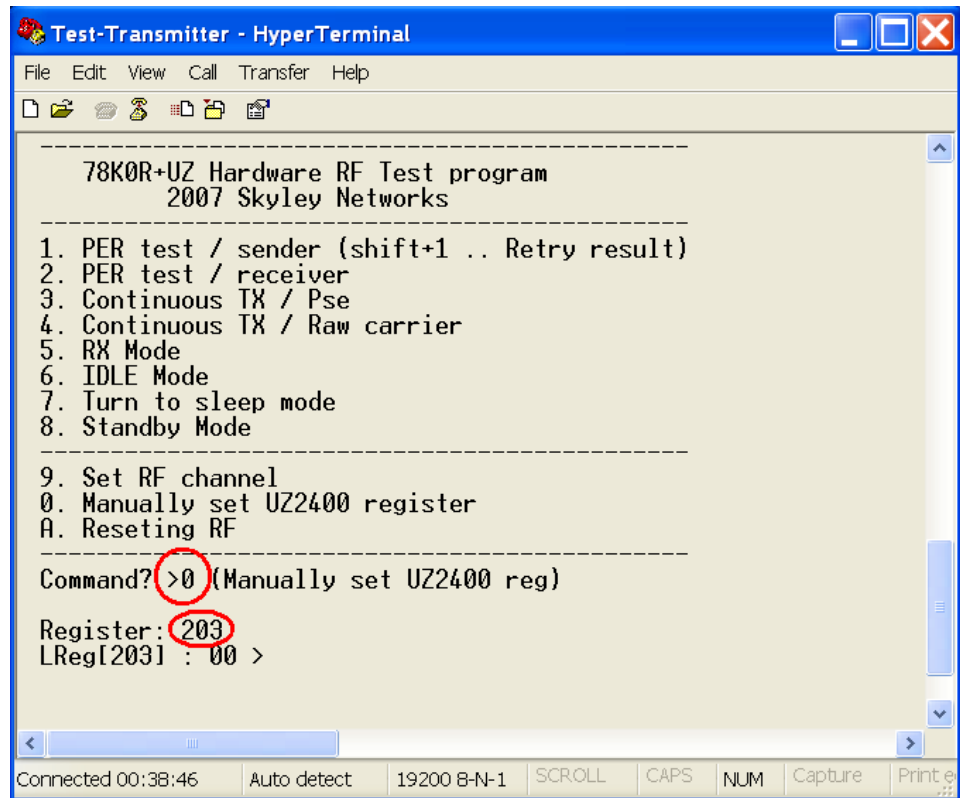


Figure 2-8 Menu “0” for adjusting output power

The output power register bits are defined as follows:

LREG[203]:

Bit [7:6] -> large scale tuning

00: 0 dB

01: -10 dB

10: -20 dB

11: -30 dB

Bit [5:3] -> small scale tuning

000: 0 dB

001: -1.25 dB

010: -2.5 dB

011: -3.75 dB

100: -5 dB

101: -6.25 dB

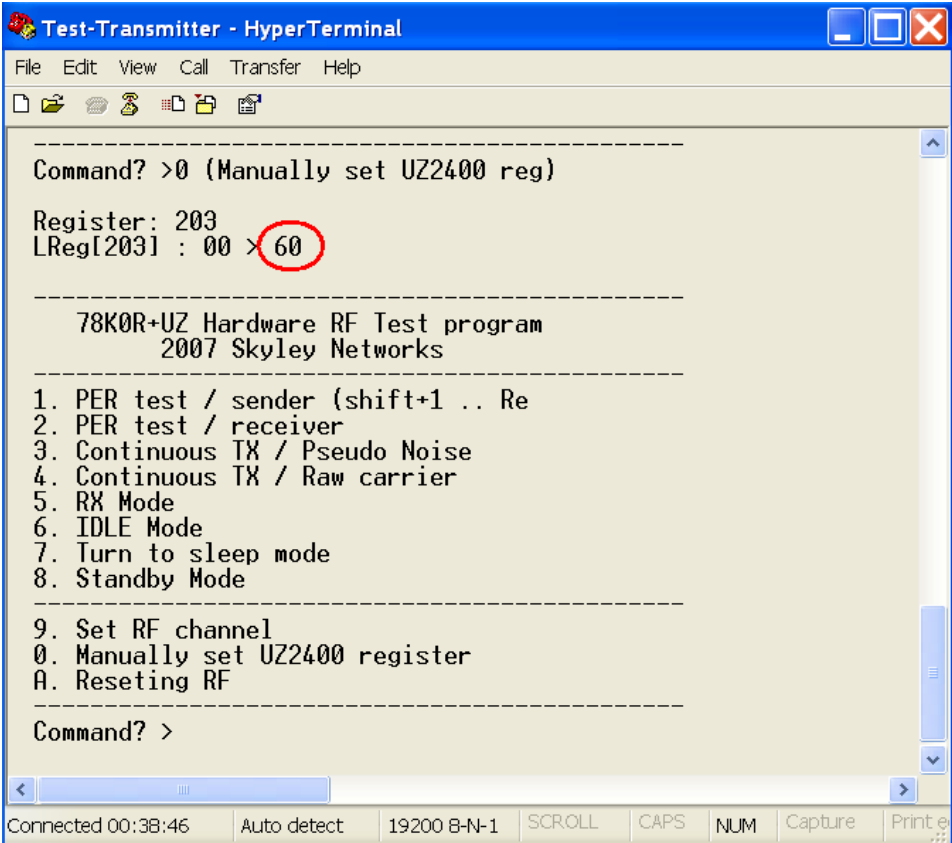
110: -7.5 dB

111: -8.75 dB

Bit [2:0] -> 000 (default value)

For instance, if you wish -15 dB (associated to the value 0110 0000 = 0x60h), please input “60”, as follows:

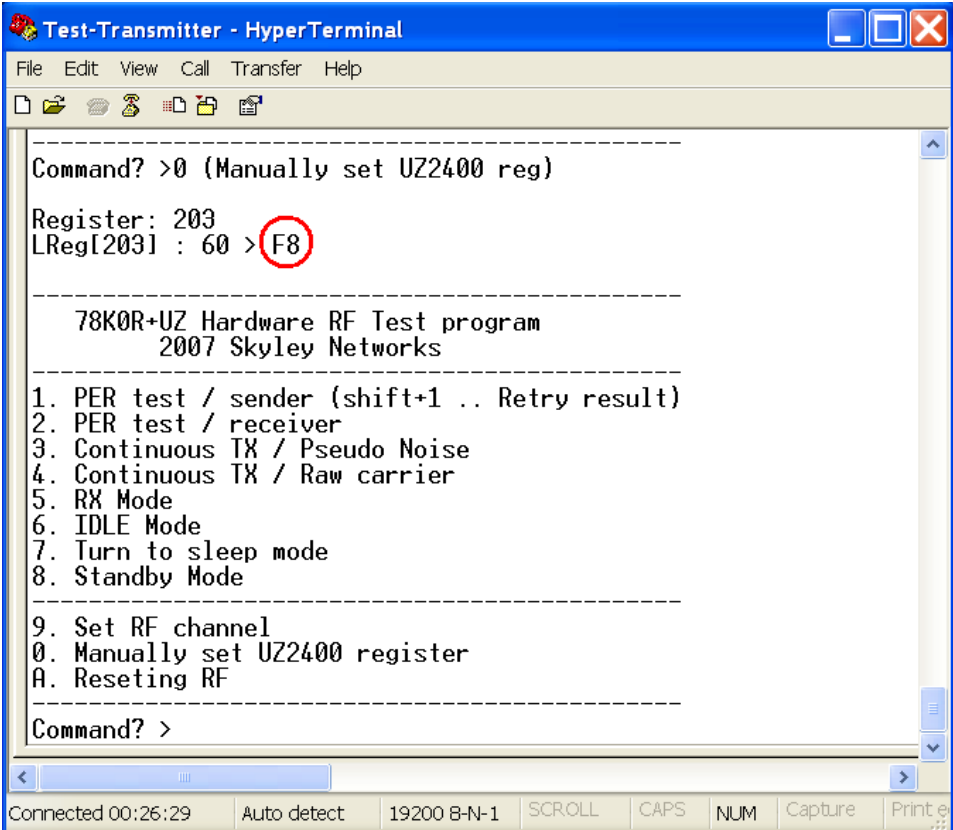
“LREG[203] : 00 > 60”



```
Test-Transmitter - HyperTerminal
File Edit View Call Transfer Help
-----
Command? >0 (Manually set UZ2400 reg)
Register: 203
LReg[203] : 00 > 60
-----
78K0R+UZ Hardware RF Test program
2007 Skyley Networks
-----
1. PER test / sender (shift+1 .. Re
2. PER test / receiver
3. Continuous TX / Pseudo Noise
4. Continuous TX / Raw carrier
5. RX Mode
6. IDLE Mode
7. Turn to sleep mode
8. Standby Mode
-----
9. Set RF channel
0. Manually set UZ2400 register
A. Reseting RF
-----
Command? >
-----
Connected 00:38:46 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture Print e...
```

Figure 2-9 Setting output power

Then, you could start the PER test again.
The minimum output power is set by "F8".



```
Test-Transmitter - HyperTerminal
File Edit View Call Transfer Help
-----
Command? >0 (Manually set UZ2400 reg)
Register: 203
LReg[203] : 60 > F8
-----
78K0R+UZ Hardware RF Test program
2007 Skyley Networks
-----
1. PER test / sender (shift+1 .. Retry result)
2. PER test / receiver
3. Continuous TX / Pseudo Noise
4. Continuous TX / Raw carrier
5. RX Mode
6. IDLE Mode
7. Turn to sleep mode
8. Standby Mode
-----
9. Set RF channel
0. Manually set UZ2400 register
A. Reseting RF
-----
Command? >
-----
Connected 00:26:29 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture Print e
```

Figure 2-10 Set minimum output power

Then, if you try an other PER test, with the minimum output power value, you may find larger PER value with smaller RSSI value in this case.

```

Test-Transmitter - HyperTerminal
File Edit View Call Transfer Help

Send to (Short addr) ? : 0002
Send count (dec) ? : 1000
Interval (dec/msec) ? : 5
[Set channel to 11 (Cmd)]
Prepare to send..OK
[Set channel to 23 (Current)]
Request to result..OK

[Results]
-----
From : 0001
To : 0002
-----
Sent : 1000
Recieved : 999
PER : 0.1000%
RSSI : max 99 / min 91
-----

[Set channel to 23 (Current)]

Connected 00:35:04 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capture

```

Figure 2-11 PER test and results at minimum output power

Please note this adjustment is applied only to the transmitter. The receiver always sends back the test results with the 0 dB output power (default) using the channel 11.

2.1.5 PER Test Receiver

The menu item "2" sets the board to receiver mode in the PER test. By using two PCs and two TK-78K0R/KG3+UZ boards, you can select Transmitter and Receiver board by menu items 1 and 2. If you connect only one TK-78K0R/KG3+UZ board to a PC, this will be the Transmitter one. If the Receiver board is battery powered, the receiver selection has to be done by SW1-Bit8 as described in the beginning of this chapter.

2.1.6 Continuous TX / Pseudo Noise

The menu item "3" initiates the modulated RF transmission. The data carried are pseudo random numbers. You can define the channel using the menu "9", and the output power using the menu "0".

2.1.7 Continuous TX / Raw carrier

The menu item "4" initiates the carrier transmission. The output power is 0 dB as a reset default. You can define the channel using the menu "9".

2.1.8 RX Mode

The menu item "5" initiates the receiver mode.

2.1.9 IDLE Mode

The menu item "6" sets the UZ2400 RF chip into the IDLE mode.

2.1.10 Sleep Mode

The menu item "7" sets the UZ2400 RF chip into the Deep Sleep mode.

2.1.11 Standby Mode

The menu item "8" sets the UZ2400 RF chip into the Standby mode.

2.1.12 Set RF Channel

The menu item "9" allows you to set the RF channel.

2.1.13 Manually Set UZ2400 Chip Register

The menu item "0" allows you to set the UZ2400 registers.
Please refer to the datasheet of the UZ2400 RF chip for the definition of registers.

2.1.14 Resetting RF

The menu item "A" allows you to reset the UZ2400 chip registers.

2.2 MAC Sample Program 1 - Text Chat

With this sample program, it is possible to configure two or more nodes for a wireless text chat application. This Sample Program is working on MAC level, constructing a network utilizing the IEEE 802.15.4 PHY/MAC standard.

In this MAC Sample Program 1, two or more nodes can form a star network (a star network has a central coordinator with several nodes connecting to the coordinator only).

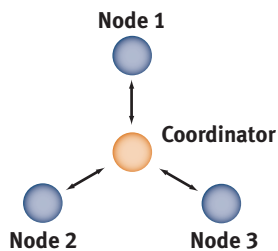


Figure 2-12 Star network configuration

The MAC Sample Program offers:

1. Designation of a network coordinator in a star configuration
2. Text chat between a coordinator and an end device

To use the MAC Sample Program 1, you need to prepare at least two PCs with USB interface and two TK-78K0R/KG3+UZ boards.

MAC Sample Program 1 is provided as C source codes with the MAC Library.

Text chat for one coordinator and up to 4 end devices is supported.

To demonstrate this program, you will again need a simple terminal emulation program like “HyperTerminal” connected to each node of the network.

2.2.1 Setting up the boards to your PC

Assumption here in this section is, you have minimum two, or maximum 5 TK-78K0R/KG3+UZ boards, in which the *TK-78K0RKG3+UZ MAC sample 1* is programmed with a unique MAC address.

If your boards are not programmed, you need to program each board using the source codes provided, setting a different MAC address for each board. For further details about programming the board and setting the MAC addresses, please read the section “6. IAR Sample Session” of the present manual.

Please set the following switch configuration on all of your boards

Table 2-4 Normal operation mode switch settings

JP1		1-2 short (USB side)
SW1	Bit 1	OFF
	Bit 2	OFF
	Bit 3	OFF
	Bit 4	ON
	Bit 5	ON

Then, please connect each TK-78K0R/KG3+UZ board to a different PC with the USB cable provided. You could connect more than one board to the same PC and you could start more than one “HyperTerminal” session for those COM ports (obviously if you have enough USB ports available). But it could be confusing to have different USB port used and different “HyperTerminal” sessions opened on the same PC.

Open for each board connected a “HyperTerminal” session.

Before opening a “HyperTerminal” session, you need to identify the COM Port number of the USB port on your PC, in order to open and set the “HyperTerminal”

with the relevant COM port. For the identification of the COM port, you can use [Control Panel] -> [System] -> [Hardware] -> [Device Manager] -> [Ports (COM & LPT)].

Then start "HyperTerminal" with settings listed in the section "2.1 RF Test Program" .

Now you will find the following opening menu on your PC screen. If not, please try the RESET button on the TK-78K0R/KG3+UZ board.

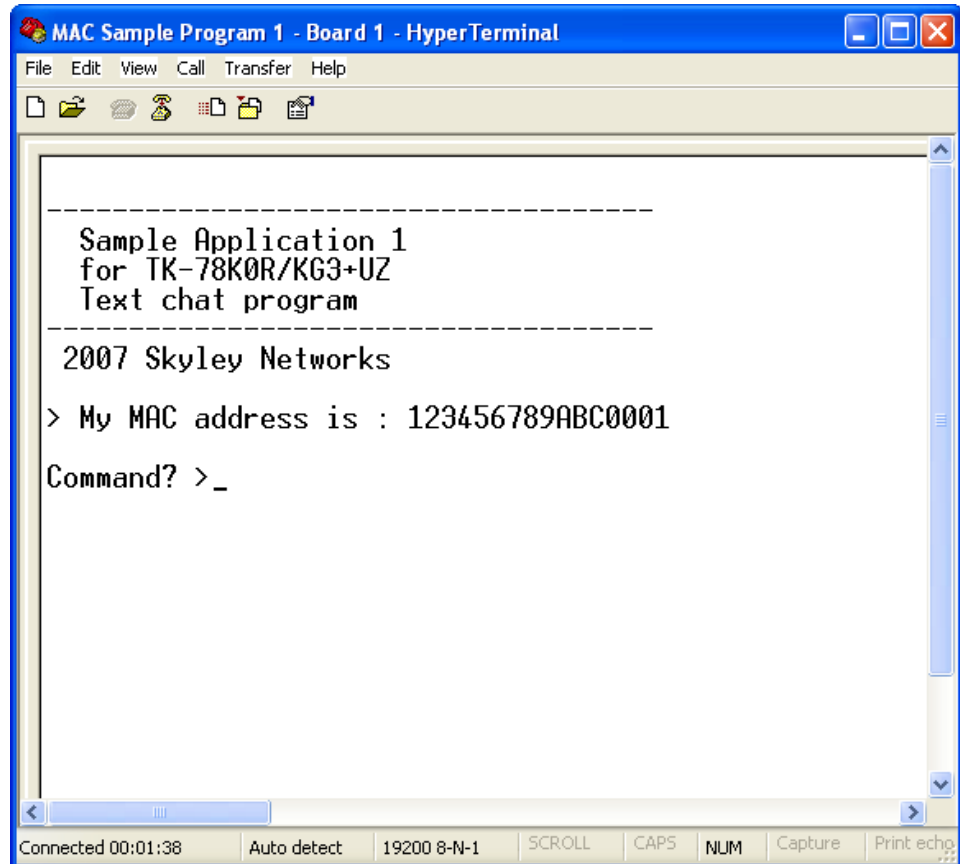


Figure 2-13 Board setup

Then, press Enter on your keyboard.


```

-----
Sample Application 1
for TK-78K0R/KG3+UZ
Text chat program
-----
2007 Skyley Networks

> My MAC address is : 123456789ABC0001

Command? >
[Help] -----
S: Send Message
M: MLME Associate test
C: Start Coordinator test
-----

Command? >

```

Figure 2-14 Opening menu

Please do exactly the same for all the boards and PCs you want to use.

2.2.2 Designation of a coordinator

Now, you must decide which board is a coordinator.
Go to the PC of the coordinator board and to the “HyperTerminal” window associated, and press “C”.

```

[Help] -----
S: Send Message
M: MLME Associate test
C: Start Coordinator test
-----

Command? >C

> MLME-START.request
> MLME-START.confirm
> Status:00

Command? >

```

Figure 2-15 Coordinator selection

Now the coordinator has started its operation.

2.2.3 Network Association

For other PCs with other boards, please press “M” on the “HyperTerminal” window associated.

```

[Help] -----
S: Send Message
M: MLME Associate test
C: Start Coordinator test
-----

Command? >M

> MLME-ASSOCIATE.request
> MLME-ASSOCIATE.confirm
> Associated ShortAddr:4321 ←
>                               Status:00

Command? >

```

Figure 2-16 Network association of an end device

Now, this particular board was associated to the network as an end device with the short address of 4321. Please repeat this step for your third, fourth, and possibly fifth board.

On the coordinator side, you will find the following message, if the association is successful.

```

Command? >C

> MLME-START.request
> MLME-START.confirm
> Status:00

Command? >
> MLME-ASSOCIATE.indication
> from 123456789ABC0002 associated to 4321

```

Figure 2-17 Network association message at the coordinator

2.2.4 Text Chat

Now the network is prepared for you to start text chat between an end device and the coordinator.

At first, you may start with the coordinator.

Press “S” in the “HyperTerminal” window associated, then input the short address of an end device (“4321” in this example) then input your text message, up to 102 bytes (“Hello!” in this example).

```
Command? >
> MLME-ASSOCIATE.indication
> from 123456789ABC0002 associated to 4321

[Help] -----
S: Send Message
-----

Command? >S

> MCPS-DATA.request
> Send to (short address) ? 4321
> Message ? Hello!

Command? >
```

Figure 2-18 Text chat at coordinator device

You will find the following message on the end device, 4321.
The sender's short address is "1975", and the PAN ID is 2420 in this example.

```
Command? >
> MCPS-DATA.indication
> from 1975/2420
Hello!
```

Figure 2-19 Text chat at end device

Now, you can reply from the end device "4321" to the coordinator "1975" by inputting "S", then "1975", and your reply text.

2.3 MAC Sample Program 2 - LED Control

The MAC Sample program 2 is developed to provide with another simple example to construct a star network utilizing the IEEE 802.15.4 PHY/MAC standard.

The TK-78K0R/KG3+UZ boards of your *78K0R ZigBee™ Premium Development Kit* will come pre-programmed with this sample program.

This LED Control sample program can run with minimum 2 and maximum 5 nodes. This sample program can run stand alone without PC.

Optional, it is also possible to connect “Hyper Terminal” to the development boards and view the association and data transfer as text messages.

The MAC Sample Program 2 is provided in the form of the C source codes with the MAC library.

2.3.1 Setting up the boards

To begin the demonstration, you need to have minimum two TK-78K0R/KG3+UZ boards, in which the TK-78K0R/KG3+UZ MAC sample 2 is programmed (it is already done in the preprogrammed boards provided in the *78K0R ZigBee™ Premium Development Kit*).

If your boards are not programmed, you need to program each board using the source codes provided. For further details about programming the board, please read the section "6. IAR Sample Session" of the present manual.

When your boards are programmed, that is to say ready for the demonstration, please set the following switch configuration to all your boards.

Table 2-5 Operation mode switch settings

JP1		1-2 short (USB side)
SW1	Bit1	OFF
	Bit2	OFF
	Bit3	OFF
	Bit4	ON
	Bit5	ON

2.3.2 Starting up a Coordinator

Once you have chosen which board will be the coordinator, you could connect this board to your PC (with one of the USB cables provided).

To enable this board to be the Coordinator, it is necessary to set dip switch SW1-Bit8 to the ON position. It is necessary to reset the unit as the SW1-Bit8 is only read following a reset. Note that the coordinator will take the default MAC address of the program.

You must only enable one board to be the Coordinator on the network. All other modules must be End Devices, so please ensure that all of the other boards have SW1-Bit8 set to the OFF position.

2.3.3 Starting up End Devices

You could now connect all the other boards, that is to say the End Devices; as you could see just after it could be necessary to hold the SW2 in a different position.

To ensure that each End Device joins the network reliably, it is necessary to associate on to the network with a different network address for each End Device. This is achieved by the following process:

Press the reset switch (SW5) and any of the switch positions of the directional switch (SW2).

Release the reset switch (SW5).

Wait one second and then release the directional switch (SW2).

The nodes will then associate to the Coordinator and form a star network.

The following table shows how the addresses are allocated depending upon the selection of SW2 following a reset.

Table 2-6 SW2 address selection

SW2 UP Position Selected	Default Address + 1
SW2 CENTER Position Selected	Default Address + 2
SW2 LEFT Position Selected	Default Address + 3
SW2 RIGHT Position Selected	Default Address + 4
SW2 DOWN Position Selected	Default Address + 5
SW2 DEFAULT Position Selected	Default Address + 6

Note Please make sure SW2 is always active in a different position following a reset, in order to avoid that end devices will try and associate using the same address.

2.3.4 Operation

The coordinator generates beacon at channel 11 of 2405 MHz.

An end device makes a network association. If successful, LED4 on the board is ON.

When an End device and the Coordinator are successfully associated, pressing SW3 on the End Device will cause LED2 to blink on the Coordinator and pressing SW4 on the End Device will cause LED3 to blink on the Coordinator.

The number of times of blink depends on the sequence the End Device joined in the network. For instance, if an End Device is the third End Device for the network, the LED will blink three times.

Table 2-7 Correspondence between End Device action and Coordinator

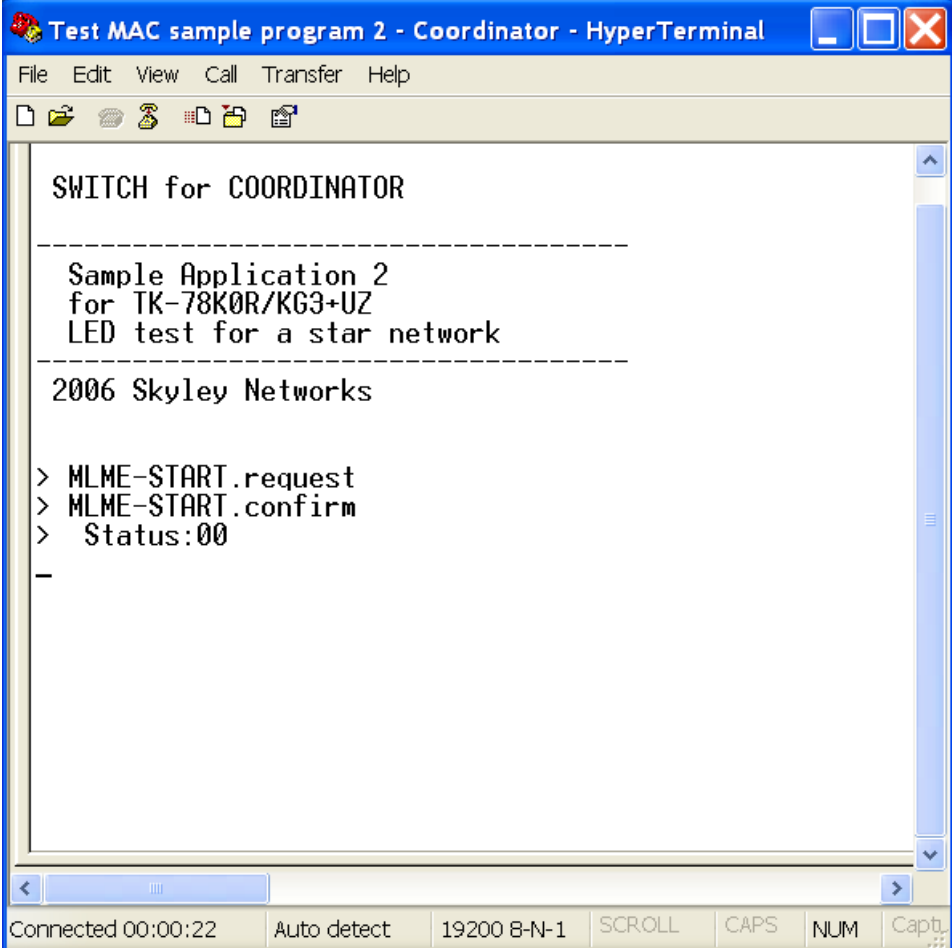
LED on Coordinator	SW on End Device
LED2	SW3
LED3	SW4

2.3.5 Using Terminal Program

It is also possible to connect “HyperTerminal” to the development boards and view the association and data transfer as text messages.

If you connect the HyperTerminal with your Coordinator and push the reset button on the Coordinator board, the following opening message will appear.

If not, please check COM port setting of your USB connection.

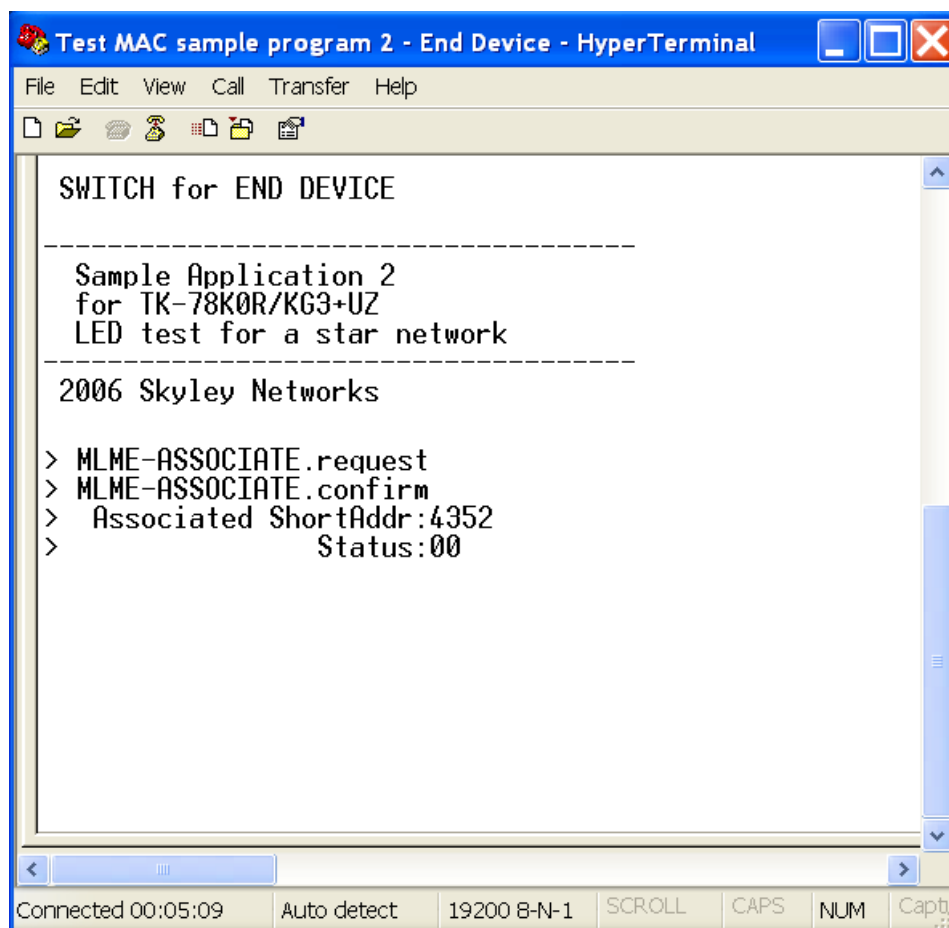


```
Test MAC sample program 2 - Coordinator - HyperTerminal
File Edit View Call Transfer Help
SWITCH for COORDINATOR
-----
Sample Application 2
for TK-78K0R/KG3+UZ
LED test for a star network
-----
2006 Skyley Networks
> MLME-START.request
> MLME-START.confirm
> Status:00
-
Connected 00:00:22 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capt...
```

Figure 2-20 Coordinator startup

Now the coordinator has started up successfully.

If you start up End Devices, as described in the section "2.3.3 Starting up an end devices", pressing reset and keeping the directional switch on the UP position, the following messages will appear on the HyperTerminal.

A screenshot of a HyperTerminal window titled "Test MAC sample program 2 - End Device - HyperTerminal". The window has a menu bar with "File", "Edit", "View", "Call", "Transfer", and "Help". Below the menu bar is a toolbar with icons for file operations. The main text area contains the following output:

```
SWITCH for END DEVICE  
-----  
Sample Application 2  
for TK-78K0R/KG3+UZ  
LED test for a star network  
-----  
2006 Skyley Networks  
  
> MLME-ASSOCIATE.request  
> MLME-ASSOCIATE.confirm  
> Associated ShortAddr:4352  
> Status:00
```

At the bottom of the window, there is a status bar with the following information: "Connected 00:05:09", "Auto detect", "19200 8-N-1", "SCROLL", "CAPS", "NUM", and "Capt...".

Figure 2-21 Short address assignment End Device 1

A short address of "4352" was assigned to the board.
A short address is assigned sequentially, independent from the long address.
You see the following message on the coordinator side.

```

Test MAC sample program 2 - Coordinator - HyperTerminal
File Edit View Call Transfer Help
[Icons]
SWITCH for COORDINATOR
-----
Sample Application 2
for TK-78K0R/KG3+UZ
LED test for a star network
-----
2006 Skyley Networks

> MLME-START.request
> MLME-START.confirm
> Status:00

> MLME-ASSOCIATE.indication
> from 123456789ABC0002 associated to 4352

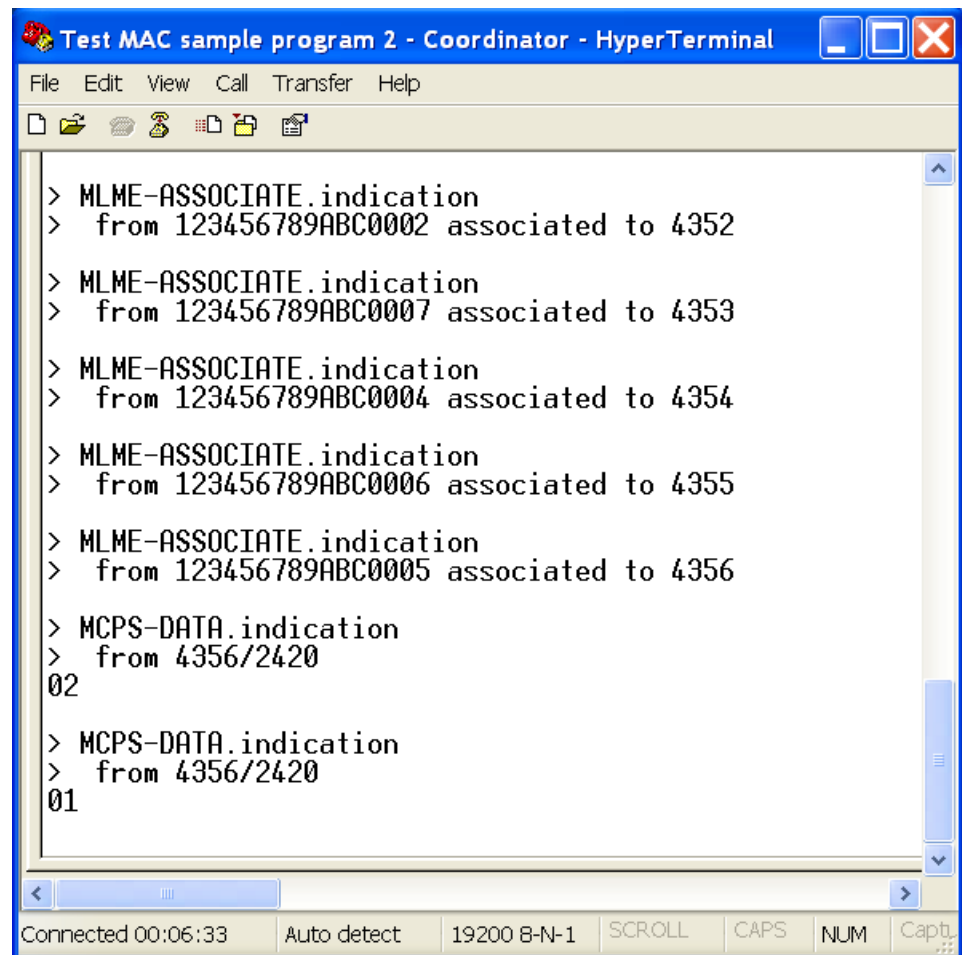
Connected 00:04:36 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capt...

```

Figure 2-22 Association successful from the Coordinator side

The following example shows the association of the fifth End Device “4356”. Then the SW4 on this fifth End Device was pushed and then the switch SW3. You will see the LED2 on the Coordinator will blink 5 times, and then LED3 will blink 5 times too.

The default PAN ID of this network is “2420”.



```
> MLME-ASSOCIATE.indication
> from 123456789ABC0002 associated to 4352

> MLME-ASSOCIATE.indication
> from 123456789ABC0007 associated to 4353

> MLME-ASSOCIATE.indication
> from 123456789ABC0004 associated to 4354

> MLME-ASSOCIATE.indication
> from 123456789ABC0006 associated to 4355

> MLME-ASSOCIATE.indication
> from 123456789ABC0005 associated to 4356

> MCPS-DATA.indication
> from 4356/2420
02

> MCPS-DATA.indication
> from 4356/2420
01
```

Connected 00:06:33 Auto detect 19200 8-N-1 SCROLL CAPS NUM Capt...

Figure 2-23 Signal Sent to Coordinator

Chapter 3 Hardware specification TK-78K0R/KG3+UZ

Table 3-1 General hardware features (TK-78K0R/KG3+UZ)

Item	Details	
CPU	Part number	μPD78F1168GC
	Clock	Main = 20 MHz
		Subclock = 32.768 kHz
	Internal flash memory	512 kB
	Internal RAM	30 kB
	Operation voltage	5 V (supply from USB)
		9 V (Supply from a battery, minimum 6.5 V)
USB interface	Mini USB x 1 channel	
RF board	UZ2400 RF Board	
Temperature sensor	Temperature sensor x 1	
LED	LED 1 = Power LED 2 - 4 = Multipurpose	
Multipurpose input	4 directional switch with center push x 1 Push switch x 2	
Reset Switch	Push switch x 1	
OCD/MiniCube interface	Connector mounted	
On board Flash memory writing	Possible via MiniCube Interface	

3.1 Terminal list

Following are the terminal tables of CN1, CN3 and CN4 of the TK-78K0R/KG3+UZ CPU board.

Table 3-2 Connector CN1 terminal list (TK-78K0R/KG3+UZ)

CN1	Signal name	Terminal CPU name at connection destination	Notes
1	P142	P142/SCK20/SCL20	
2	P141	P141/PCLBUZ1/INTP7	
3	P140	P140/PCLBUZ0/INTP6	
4	P47	P47/INTP2	
5	P46	P46/INTP1/TI05/TO05	
6	P45	P45/SO01	
7	P44	P44/SI01	
8	P42	P42/TI04/TO04	
9	T_RESET		Connected to reset circuit
10	P120	P120/INTP0/EXLVI	
11	GND	GND	

CN1	Signal name	Terminal CPU name at connection destination	Notes
12	GND	GND	
13	VDD	VDD	
14	VDD	VDD	
15	P22	P22/ANI2	
16	P21	P21/ANI1	
17	P20	P20/ANI0	
18	P63	P63	
19	P64	P64/RD	
20	P65	P65/WR0	
21	P66	P66/WR1	
22	P77	P77/EX23/KR7/INTP11	
23	P06	P06/WAIT	
24	P05	P05/CLKOUT	
25	GND	GND	
26	P30	P30.INTP3/RTC1HZ	
27	P27	P27/ANI7	
28	P54	P54/EX12	
29	P55	P55/EX13	
30	P17	P17/EX31/TI02/TO02	
31	P15	P15/EX29/RTCDIV/RTCCL	
32	P12	P12/EX26/SO00/TxD0	
33	P11	P11/EX25/SI00/RxD0	
34	P10	P10/EX24/SCK00	
35	VDD	VDD	
36	P110	P110/ANO0	
37	P111	P111/ANO1	
38	VDD	VDD	
39	GND	GND	
40	P153	P153/ANI11	
41	P152	P152/ANI10	
42	P151	P151/ANI9	
43	P150	P150/ANI8	
44	P25	P25/ANI5	
45	P24	P24/ANI4	
46	P23	P23/ANI3	
47	P131	P131/TI06/TO06	
48	P145	P145/TI07/TO07	
49	P144	P144/SO20/TxD2	
50	P143	P143/SI20/RxD2/SDA20	



Figure 3-1 Connector CN1 pin configuration (TK-78K0R/KG3+UZ)

Table 3-3 Connector CN3 terminal list

CN3	Signal name	Terminal CPU name at connection destination	Notes
1	GND	GND	
2			N.C.
3	VREG_EN	P50/EX8	Output from CPU
4			N.C.
5	RESn	P51/EX9	Output from CPU
6	FIFO	P52/EX10	Input to CPU
7			N.C.
8	FIFOP	P31/TI03/TO03/INTP4	Input to CPU
9			N.C.
10	CCA	P53/EX11	Input to CPU
11			N.C.
12	SFD	P16/EX30/TI01/TO01/INTP5	Input to CPU
13			N.C.
14	CSn	P43/SCK01	Output from CPU
15			N.C.
16	SCLK	P04/SCK10/SCL10	Output from CPU
17			N.C.
18	SI	P02/SO10/TxD1	Output from CPU
19	GND	GND	
20	SO	P03/SI10/RxD1/SDA10	Input to CPU

Table 3-4 Connector CN4 terminal list

CN4	Signal name	Terminal CPU name at connection destination	Notes
1	TP5		
2	GND	GND	
3	TP5		
4	GND	GND	
5	TP5		
6	GND	GND	
7	3.3V		
8	GND	GND	
9	3.3V		
10	GND	GND	
11	TP4		
12	GND	GND	
13	TP3		

CN4	Signal name	Terminal CPU name at connection destination	Notes
14	GND	GND	
15			N.C.
16	GND	GND	
17			N.C.
18	GND	GND	
19			N.C.
20	GND	GND	



Figure 3-2 Connector CN3 (left) and CN4 (right) pin configuration

3.2 Switches

3.2.1 SW1

Bit1, 2, 3, 4 and 5 of SW1 are dip switches for Operation Mode setting. Bit6, 7 and 8 of SW1 are connected to general purpose ports P80, P81 and P82 for multipurpose input.



Figure 3-3 Dip Switches SW1 (TK-78K0R/KG3+UZ)

3.2.1.1 On-chip debug Mode with the IAR TK-interface

For using the on chip debug function via the TK interface of IAR, use the following settings.

Table 3-5 On-chip debug mode settings for the TK-78K0R/KG3+UZ

SW1	Bit 1	ON/OFF ^{Note1}
	Bit 2	ON
	Bit 3	ON
	Bit 4	OFF
	Bit 5	OFF

- Notes**
1. * ON: The microcontroller stays being reset until TK interface is started.
* OFF: The microcontroller runs the programs stored in the flash memory as soon as it gets power supply.
 2. If you use IAR TK interface for debugging, it uses P40 and P41 for communicating with host machine. Therefore, you cannot use P40 and P41 as general purpose serial communication at the same time.

To run the programs stored in built-in flash memory (without using the TK interface of IAR), please use following settings and re-supply USB power (or make a hardware reset).

You can use the On-chip debug function via the Minicube 2 and not by using IAR TK-interface. In this case refer to the following section with the table 3-7.

Table 3-6 Normal Operation Mode for the TK-78K0R/KG3+UZ (Serial communication via USB connector not available)

SW1	Bit 1	OFF
	Bit 2	OFF
	Bit 3	OFF
	Bit 4	OFF
	Bit 5	OFF

Note In this case, the serial communication via P40 and P41 will still not be available, because these ports are not connected to the USB connector (SW1-bit 4 and 5 are OFF).

3.2.1.2 Normal Operation Mode and Minicube2 Use

Please change to the following settings when you execute the program normally, or when you use the MiniCube2 for programming or On-chip debug session. Obviously in this case the serial communication via the USB port is available for the application.

Table 3-7 Normal Operation Mode for the TK-78K0R/KG3+UZ (Serial communication via USB connector enabled)

SW1	Bit 1	OFF
	Bit 2	OFF
	Bit 3	OFF
	Bit 4	ON
	Bit 5	ON

3.2.1.3 General purpose setting port

Bit 6, 7 and 8 of SW1 are general purpose setting ports. The port state is “Low” (because it is connected to GND) when the switch is ON. The port state is “High” (because it is connected to a 10kΩ pull-up resistor) when the switch is OFF.

Table 3-8 Switch SW1.bit6-8 terminal list (TK-78K0R/KG3+UZ)

SW1	Signal name	Terminal CPU name at connection destination
Bit 6	P80	P80/EX0
Bit 7	P81	P81/EX1
Bit 8	P82	P82/EX2

3.2.2 SW2

SW2 is a four directional switch with centre push. If it is directed or pushed, the input is set to GND. Otherwise the circuit is open. Therefore please set the on-chip pull-up resistors (PU7) during initializing routine of your program code. (For more detail, please refer to the User’s manual of the μ PD78F1168 CPU.)

Table 3-9 Directional switch SW2 terminal list (TK-78K0R/KG3+UZ)

SW2	Signal name	Terminal CPU name at connection destination	Notes
1	P72	P72/EX18/KR2	UP
2	P73	P73/EX19/KR3	CENTER PUSH
3	P74	P74/EX20/KR4/INTP8	LEFT
4	P75	P75/EX21/KR5/INTP9	RIGHT
5	GND	GND	
6	P76	P76/EX22/KR6/INTP10	DOWN

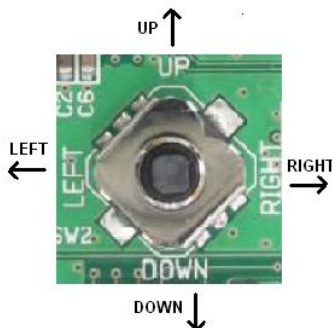


Figure 3-4 Directional switch SW2 (TK-78K0R/KG3+UZ)

3.2.3 SW3, SW4

SW3 and SW4 are push switches. They are connected to pull-up resistors, and their outputs go “Low”, when they are pushed.

Table 3-10 SW3 and SW4 terminal list

Switch	Signal name	Terminal CPU name at connection destination
SW3	P70	P70/EX16/KR0
SW4	P71	P71/EX17/KR1

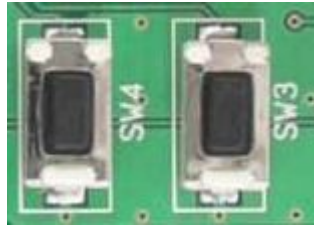


Figure 3-5 Switches SW3 (right) and SW4 (left)

3.2.4 SW5

SW5 is the reset switch. The TK-78K0R/KG3+UZ board is reset when SW5 is pushed.



Figure 3-6 Switch SW5

3.3 Jumper JP1

This jumper switches the power supply of the board.

Table 3-11 JP1 connection

JP1	1-2pin short	Supply power from USB connected to USB1
	2-3pin short	Supply power from batteries connected to CN2

3.4 LEDs

3.4.1 LED1

The “Power LED” LED1 is activated when the power supply is turned on.



Figure 3-7 LED1 as Power LED (TK-78K0R/KG3+UZ)

3.4.2 LED2, LED3 and LED4

LED2, 3 and 4 are available for applications. To turn on a LED, set the output port to “Low”.

Table 3-12 LED 2, 3 and 4 terminal list (TK-78K0R/KG3+UZ)

LED	Signal name	Terminal CPU name at connection destination
LED2	P62	P62
LED3	P61	P61/SDA0
LED4	P60	P60/SCL0



Figure 3-8 LED 2, 3 and 4 (TK-78K0R/KG3+UZ)

3.5 FP1

The connector FP1 allows connecting the Minicube2 On-Chip debug emulator to the TK-78K0R/KG3+UZ board in order to use On-Chip debug function of the 78K0R/KG3 device. Please note, Minicube2 is a separate product from NEC Electronics and it is not included in this 78K0R ZigBee™ Premium Development Kit.



Figure 3-9 MiniCube connector FP1

3.6 Power Supply

There are two choices to supply power to the board, USB or a 6LR614 9V battery via CN2. Please refer to the following table for the jumper setting.

Table 3-13 JP1 Setting for the power supply source

JP1	USB Power	USB (1-2pin short)
	Battery	CN2 (2-3pin short)

Please replace the battery with a new one, if the voltage level goes down to 4.8V. Below the voltage level of 4.8V, functions of the board are not guaranteed. The battery voltage can be checked at the port as shown below.

Table 3-14 9V battery checking

Signal name	Terminal CPU name at connection destination	Notes
BT_MONI	P26/ANI6	33.8% of the battery is available at the input of power supply ANI6 For instance, If the battery level 9V: The level of the BT_MONI = 0.338×9.0 = 3.042 V If the battery level is 6.5V: The level of the BT_MONI = 0.338×4.8 = 1.622 V

3.7 Universal Area

The kit has the universal area. Users can use this to develop custom circuit.



Figure 3-10 Universal test area

3.8 Soldering Bridges

Additional configuration of the TK-78K0R/KG3+UZ board can be done by the soldering bridges. With using the soldering bridge to cut the circuit, users can customize the circuit.

To open, use cutter to cut the dent part. To short, put solder on the pad.

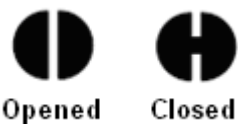


Figure 3-11 Soldering bridge configuration

Table 3-15 Soldering bridge connection

Soldering bridge name	Configuration	Connection
P150~P153	Closed (default)	1MΩ Pull-down
	Opened	Associated pin on CN1 is used

3.9 Temperature Sensor

The TK-78K0R/KG3+UZ board has a temperature sensor for measuring the ambient temperature of the PWB board. It is connected to the analogue input pin P27/ANI7 of the microcontroller.

- Temperature sensor S-8120C (Made by SII)
- Power supply of sensor: +3.3 V
- Linear output voltage : -8.20mV/°C (from -20°C to 80°C)

Please refer to the datasheet for details.

3.10 Design Data and Parts Layout

3.10.1 Parts Layout

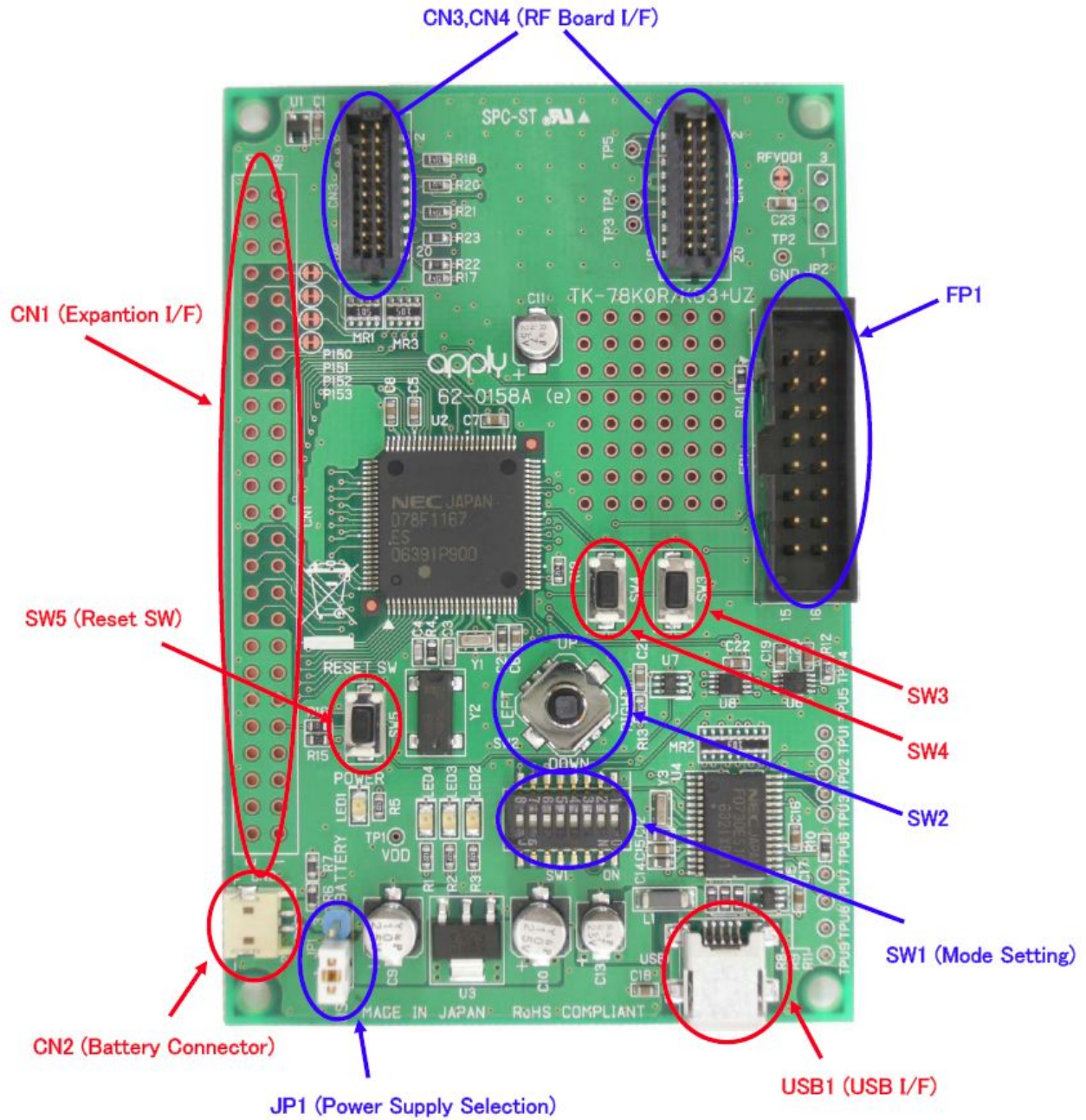


Figure 3-12 Hardware overview of the TK-78K0R/KG3+UZ board

3.10.2 RF Board Connection Figure_K0R

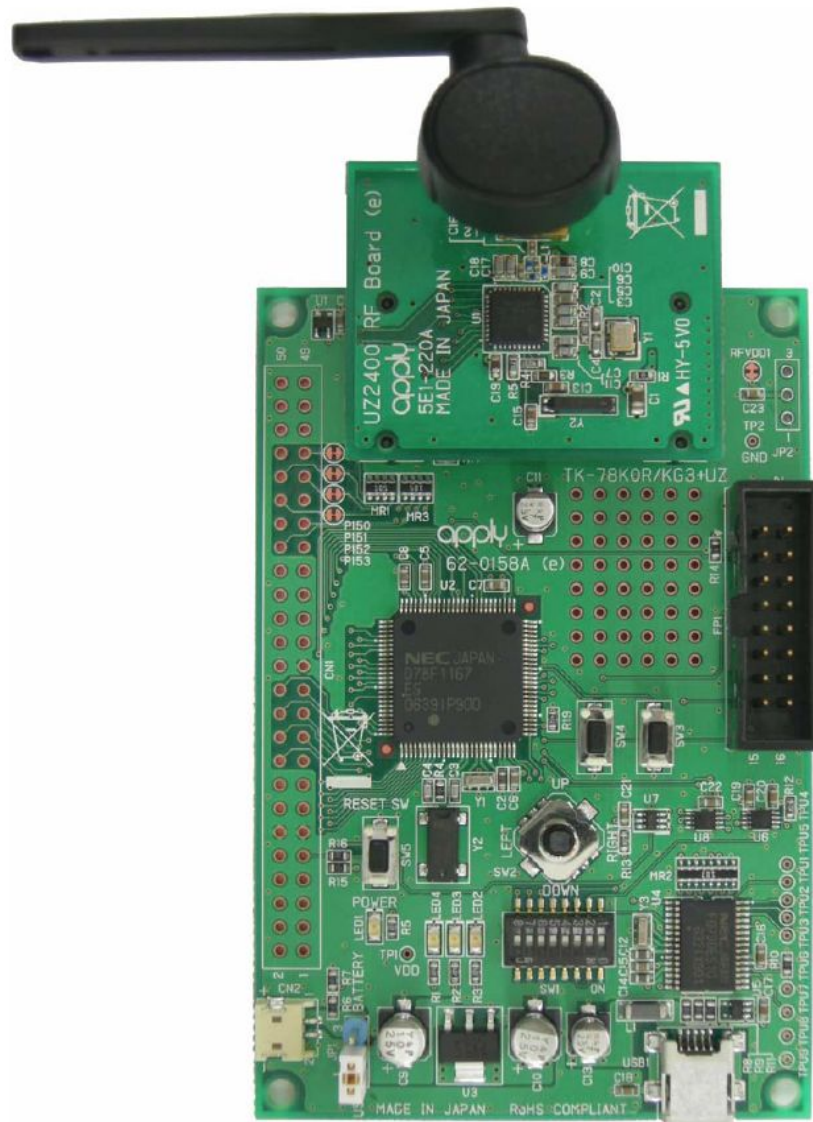


Figure 3-13 Overview of the connection of the RF board (TK-78K0R/KG3+UZ)

Chapter 4 Hardware specification

78K0R_UZ_Stick

The 78K0R_UZ_Stick is an additional module based on the NEC 78K0R/KE3 microcontroller. This module can be used as either a network node or a dedicated hardware module for interfacing to the Air Sniffer application (part of the ZigBee™ SDK) depending upon the flash program loaded on to the module.

4.1 Main Features

Features of the 78K0R_UZ_Stick include:

- The board uses the NEC Electronics 16-bit single chip microcontroller (μ PD78F1146).
- Hardware is compliant with IEEE 802.15.4/ZigBee™ wireless personal area network.
- Object code of IEEE 802.15.4 PHY/MAC is included in the kit and possible to utilize as a library.
- 256 kB of Flash memory, available on chip in the 78K0R/KE3 microcontroller
- The board contents a 2.4GHz transceiver chip UZ2400 (Accordance with IEEE 802.15.4 ZigBee™ Specifications for Low Rate Wireless Personal Area Networks) made by Uniband Electronic Corporation. (<http://www.ubec.com.tw/index.html>)
- Board includes an antenna made by Gigaant and a temperature sensor (S-8120 CNB) made by Seiko (<http://www.gigaant.com> and <http://www.sii.co.jp>)
- Enable to connect an On-Chip Debug Emulator MINICUBE (QB-78K0MINI or QB-MINI2). An optional additional adaptor (SICA10I2P) is required.
- USB connection can be utilized not only for debugging sessions (using the IAR TK interface), but also for user applications and power supply.
- Real time clock is available on the board.
- Power source can be selectable between USB or battery by a switch.
- Three orange LEDs are available on board for applications, in addition to one green LED for power indication.
- The size of the module is 82 x 23 mm.

Note Please inquire direct to the parts maker about specification of UZ2400 RF board, antenna and temperature sensor.

Table 4-1 General hardware features (78K0R_UZ_Stick)

Item		Details
CPU	Part number	μ PD78F1146GB
	Clock	Main = 20 MHz
		Subclock = 32.768 kHz
	Internal flash memory	256 kB
	Internal RAM	12 kB

Item		Details
	Operation voltage	5 V (supply from USB) 4.75 - 10 V (Supply from a battery)
USB interface		USB connector type A
RF board		UZ2400 RF Board
Temperature sensor		Temperature sensor x 1
LED		Green LED = Power Orange LED 1 - 3 = Multipurpose
OCD/MiniCube interface		MINICUBE2 connector (CN1)

4.2 Block Diagram

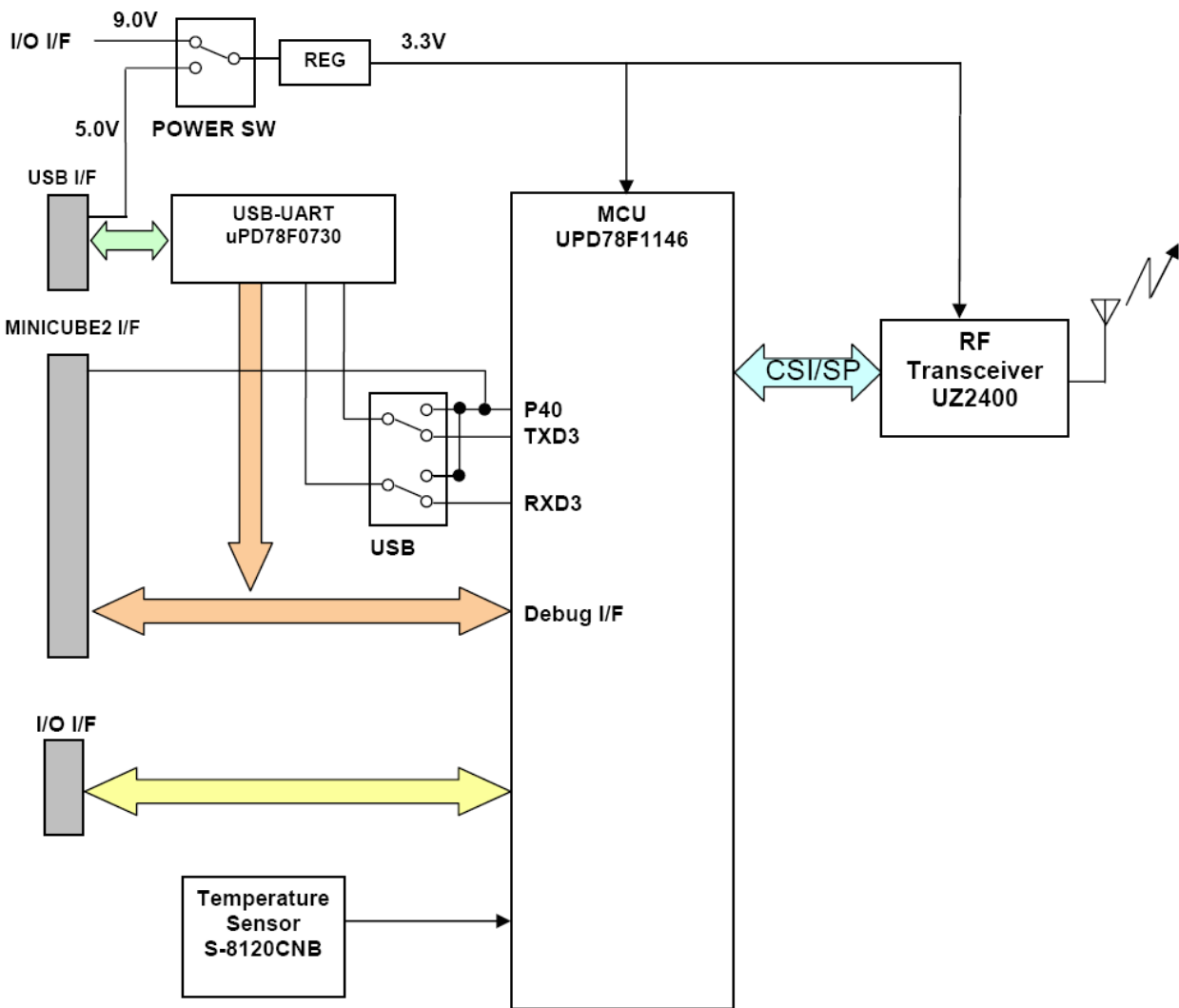


Figure 4-1 78K0R_UZ_Stick block diagram

4.3 Interface Connection

4.3.1 CN1 - Minicube Connector

CN1 is the Minicube2 connector. You need to use the conversion connector SICA1612P when you use the Minicube2.

Table 4-2 Connector CN1 terminal list (78K0R_UZ_Stick)

CN1	Signal name	Terminal CPU name at connection destination	Notes
1	GND	P142/SCK20/SCL20	
2	RESET_OUT	RESET	
3	RXD	P40/TOOL0	
4	VDD	VDD	
5	TXD	P40/TOOL0	
6	N.C.	N.C.	
7	N.C.	N.C.	
8	N.C.	N.C.	
9	N.C.	N.C.	
10	N.C.	N.C.	
11	N.C.	N.C.	
12	N.C.	N.C.	
13	N.C.	N.C.	
14	FLMD0	FLMD0	
15	RESET_IN	N.C.	Reset trigger signal
16	CLK_IN	P41/TOOL1	
17	N.C.	N.C.	
18	N.C.	N.C.	
19	N.C.	N.C.	
20	N.C.	N.C.	

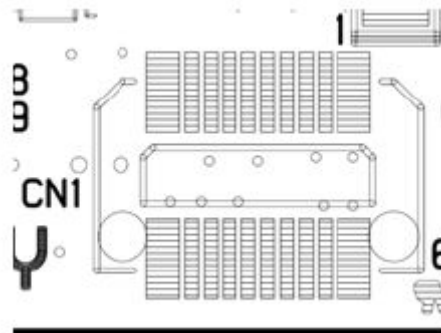


Figure 4-2 Location of CN1 - Top view (78K0R_UZ_Stick)

4.3.2 CN2 - Expansion Connector

The expansion connector provides one serial I/O port, UART or CSI, one interrupt input port, and three analogue input ports. It also provides with a connection to a 6LR614 9V battery.

Table 4-3 Connector CN2 terminal list (78K0R_UZ_Stick)

CN2	Signal name	Terminal CPU name at connection destination	Notes
1	GND	GND	
2	VBAT	N.C.	From battery
3	P10	P10/SO00/TxD0	
4	P11	P11/SI00/RxD0	
5	P141	P141/PCLBUZ1/INTP7	
6	P10	P10/SCK00	
7	P25	P25/ANI5	
8	P23.	P23/ANI3	
9	P24	P24/ANI4	
10	GND	GNDN.C.	

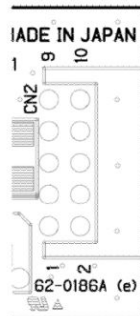


Figure 4-3 Location of CN2 - Top view (78K0R_UZ_Stick)

4.4 Switches and LEDs

4.4.1 SW1 - Power

Switch SW1 is used for the selection of power source : USB power or battery power (via CN2)

Table 4-4 Power supply setting of SW1 (78K0R_UZ_Stick)

USB Power	USB
CN2 connector: expansion for battery interface	BAT



Figure 4-4 Top view of SW1 (78K0R_UZ_Stick)

- Notes**
1. The 78K0R_UZ_Stick module is equipped with a voltage regulator, which regulates the source of 4.75 -10.0 V to 3.3V.

- The power consumption of the module largely depends on the status of the driver of the USB interface. One example of measured consumed current is, 60 mA in case USB is not connected, while 80 mA while USB is connected.

4.4.2 SW2 - USB Interface

SW1 is used for selecting the USB interface use: Debugging interface or general serial communication.

When it is set to “SER”, it enables the serial communication UART connect to the 78K0R_UZ_Stick to the USB interface after switch setting.

Table 4-5 USB interface setting of SW2 (78K0R_UZ_Stick)

Normal mode (or Minicube2 use)	SER
Debug mode (USB interface used for TK interface of IAR)	DBG



Figure 4-5 Top view of SW2 (78K0R_UZ_Stick)

4.4.3 LED1 - Power Indication

LED1 is a green LED to indicate the availability of power

Table 4-6 LED1 status (78K0R_UZ_Stick)

Status	LED
Power ON	Green
Power OFF	Off

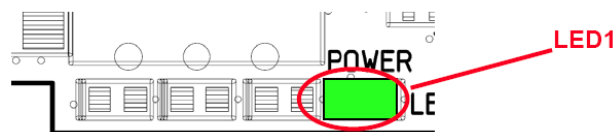


Figure 4-6 Top view of LED1 layout (78K0R_UZ_Stick)

4.4.4 LED2, LED3 and LED4

LED2, LED3 and LED4 are available for applications. They emit orange by setting respectively the output pins P62, P61 and P60 of the microcontroller to “Low”.

Table 4-7 LED2, LED3 and LED4 terminal list (78K0R_UZ_Stick)

LED	Name	MCU pin	Port Level
LED2	P62	P62	LOW for orange

LED	Name	MCU pin	Port Level
			HIGH for OFF
LED3	P61	P61/SDA0	LOW for orange
			HIGH for OFF
LED4	P60	P60/SCL0	LOW for orange
			HIGH for OFF

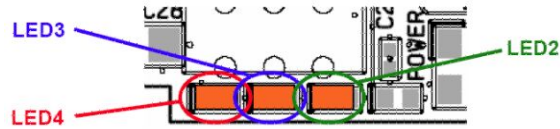


Figure 4-7 Top view of LED2, LED3 and LED4 layout (78K0R_UZ_Stick)

4.5 Design Data and Parts Layout

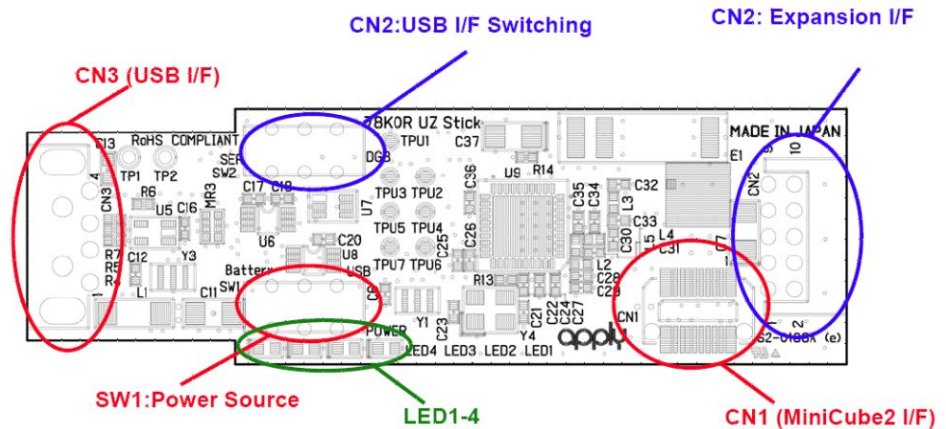


Figure 4-8 Top view of 78K0R_UZ_Stick layout

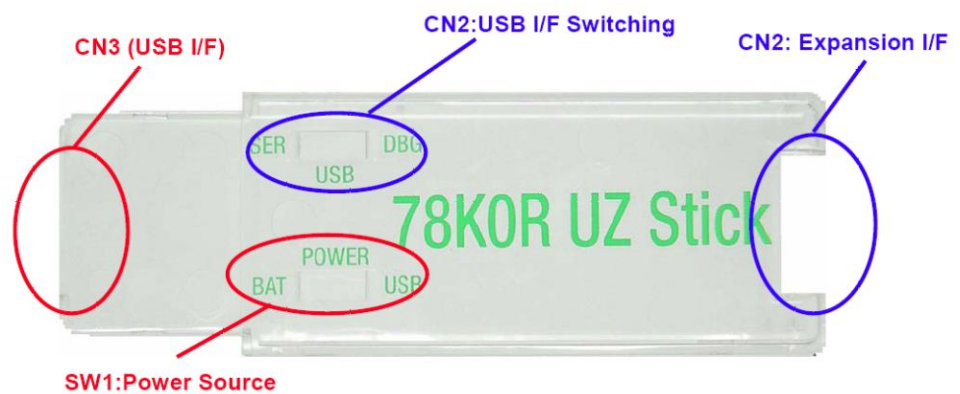


Figure 4-9 Top view of 78K0R_UZ_Stick

Chapter 5 78K0R ZigBee™ PRO Premium Development Kit, Installation and Operation

The IAR Embedded Workbench including the C-SPY debugger allows the user to build and download application programs to the *78K0R ZigBee™ PRO Premium Development Kit*. As the communication interface between the PC host system and the *78K0R ZigBee™ PRO Premium Development Kit* board is USB, a USB interface line is needed. Before you can download and run a program, relevant software and hardware must be installed properly.

CDROM contents:

- IAR Embedded Workbench for 78K0 Kickstart version
- IEEE 802.15.4 MAC library
- Sample Programs
- Documentation

5.1 Hardware Installation

After unpacking *78K0R ZigBee™ PRO Premium Development Kit*, connect one of the boards to your host computer using one provided USB interface cable. When one of the *78K0R ZigBee™ PRO Premium Development Kit* boards is connected, the USB driver needs to be installed on the host machine. Please refer to the specific section "*5.3 USB Driver Installation*".

5.2 Software Installation

The *78K0R ZigBee™ PRO Premium Development Kit* package comes with the following software demo packages:

- IAR Systems Embedded Workbench for 78K0/78K0S/78K0R including C compiler, assembler, linker, librarian and IAR C-SPY debugger / simulator
- Sample programs

5.2.1 IAR Systems Embedded Workbench Installation

The IAR Systems Embedded Workbench must be installed on your PC. For detailed installation hints, refer to the following chapters and to the corresponding documentation of the IAR Embedded Workbench.

To install the IAR Systems Embedded Workbench for 78K0/78K0S/78K0R including C-SPY debugger / simulator, select the *AUTORUN* program in the directory *<CD>VAR* of the CDROM. The setup dialogues will guide you through the installation process.

5.2.2 Sample Program Installation

To install the sample/demonstration programs for the *78K0R ZigBee[™] PRO Premium Development Kit* board select the SETUP program in the directory <CD>\78K0R SamplePrograms\ of the CDROM. The setup dialogue will guide you through the installation process.

5.3 USB Driver Installation

In order to use the *78K0R ZigBee[™] PRO Premium Development Kit* board for On-Chip debugging, the USB driver needs to be installed on the host machine.

Install the drivers according to the following procedure:

- Installation on Windows 2000: section "5.3.1 Installation on Windows 2000"
- Installation on Windows XP: section "5.3.2 Installation on Windows XP"

Note The USB driver is part of the IAR Embedded Workbench software package. Therefore please install the IAR Embedded Workbench first.

5.3.1 Installation on Windows 2000

When the *78K0R ZigBee[™] PRO Premium Development Kit* is connected with the host machine, the board is recognized by Plug and Play, and the wizard for finding new hardware is started. Click "Next >".



Figure 5-1 Found New Hardware Wizard (Windows 2000)

The window below is displayed. So, check that "Search for a suitable driver ..." is selected, then click "Next >".



Figure 5-2 Search Method (Windows 2000)

Check the "Specify a location" check box only, then click "Next >".

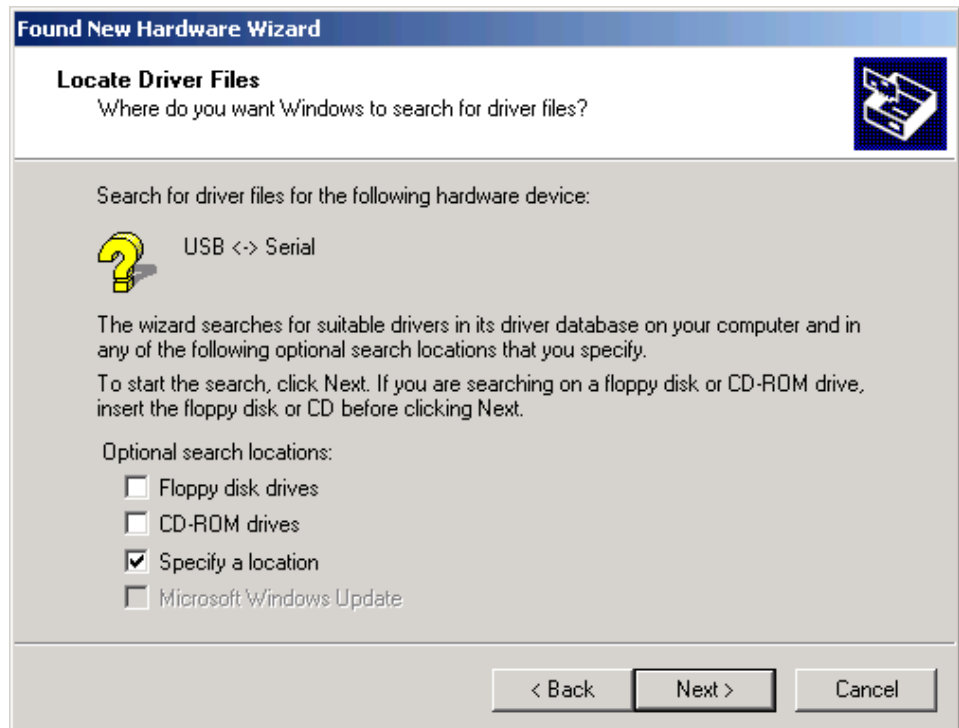


Figure 5-3 Driver File Location (Windows 2000)

Locate to the folder "C:\Program Files\IAR Systems\Embedded Workbench 4.0\78K\config\nec\ie_pc_driver\MINICUBE".

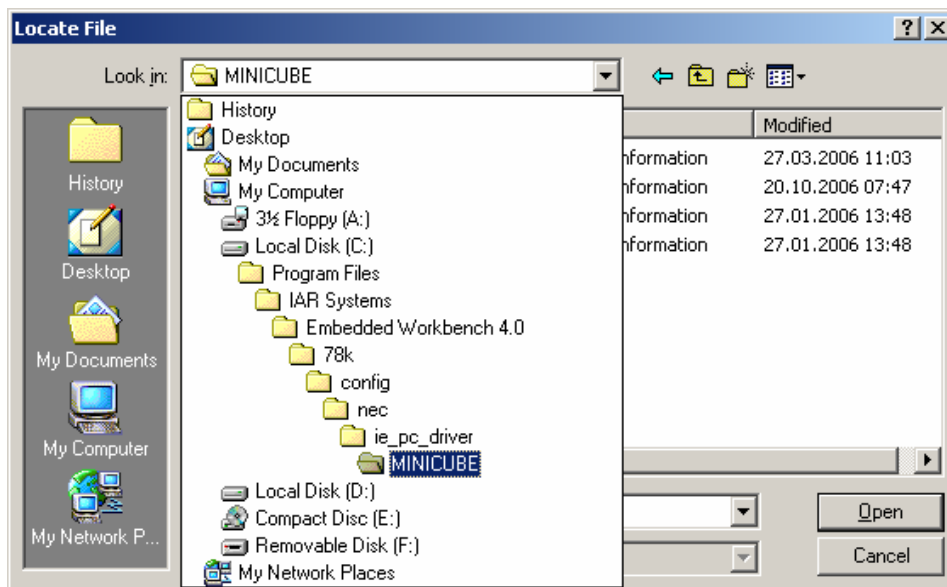


Figure 5-4 Address specification 1 (Windows 2000)

Remark If the installation destination folder is changed at the time of IAR Embedded Workbench installation, enter “<new-folder>\78K\config\nec\ie_pc_driver\MINICUBE”.

The setup information file “MQB2ALL.inf” is automatic selected, then click “Open” to proceed within driver installation.

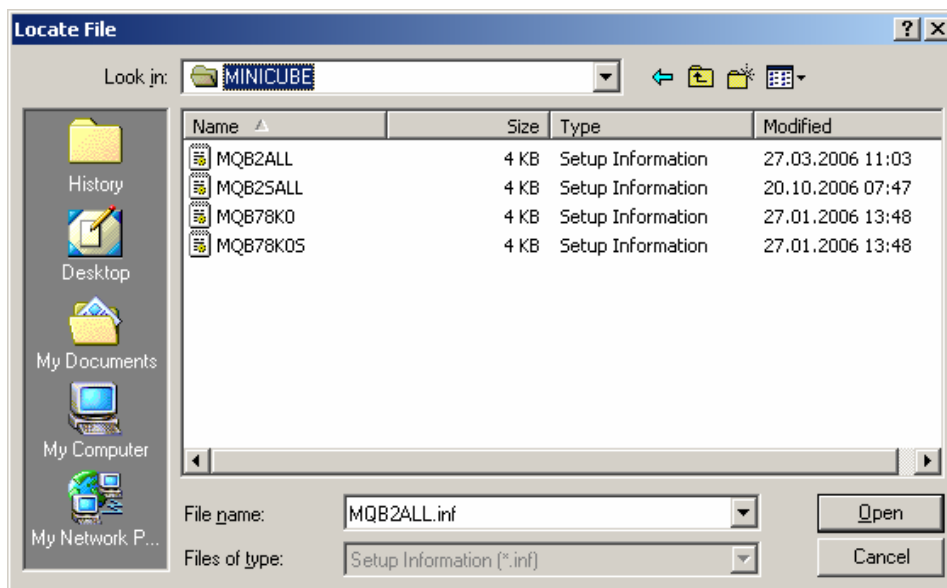


Figure 5-5 Address specification 2 (Windows 2000)

After the location of the USB driver has been specified click “OK” to proceed.

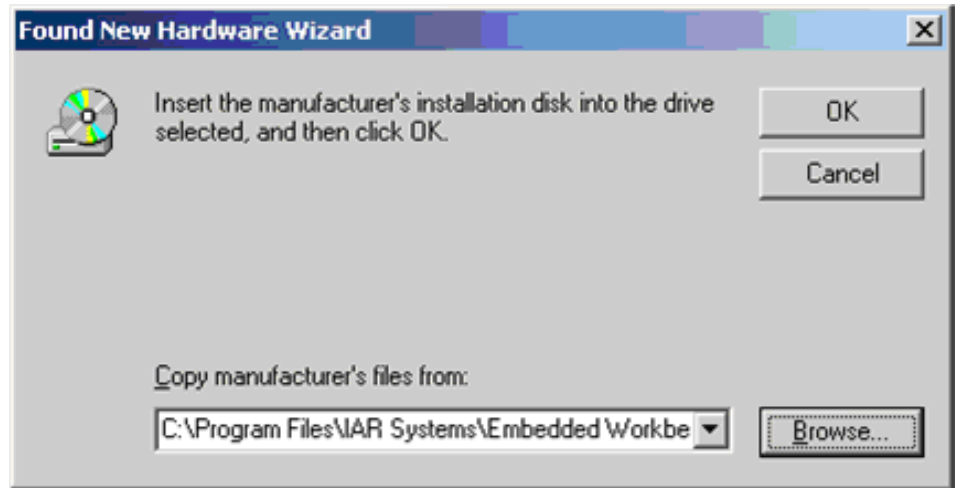


Figure 5-6 Address specification 3 (Windows 2000)

Click "Next >".

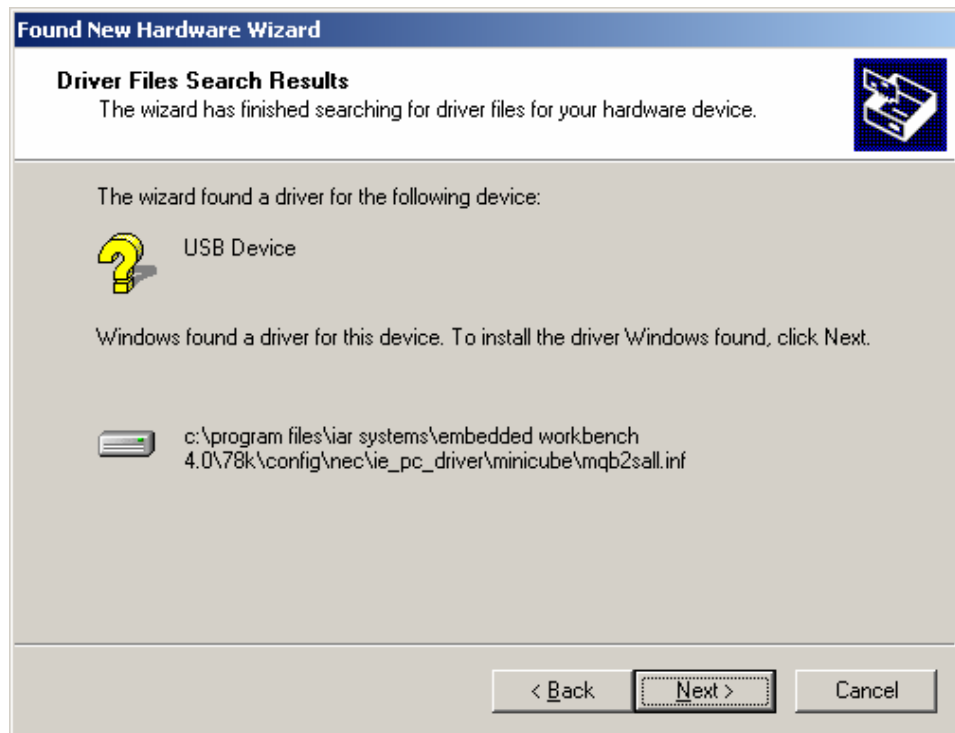


Figure 5-7 Driver File Search (Windows 2000)

Click "Finish" to complete the installation of the USB driver.

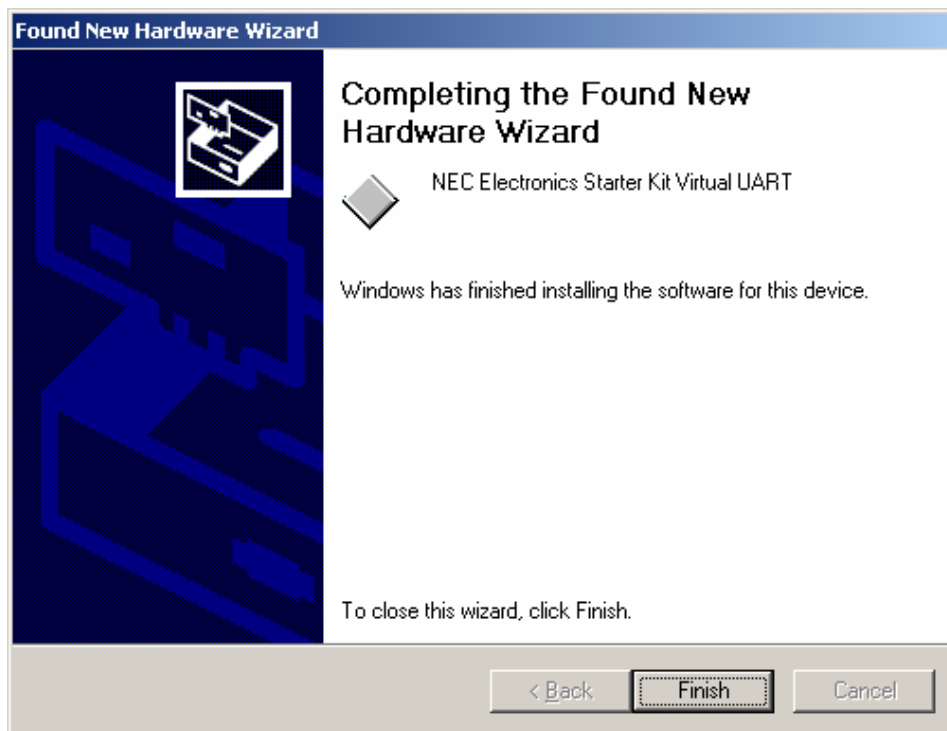


Figure 5-8 USB Driver Installation Completion (Windows 2000)

5.3.2 Installation on Windows XP

When the 78K0R ZigBee™ PRO Premium Development Kit board is connected with the host machine, the board is recognized by Plug and Play, and the wizard for finding new hardware is started. Check that "Install from a list or specific ..." is selected, then click "Next >".



Figure 5-9 Found New Hardware Wizard 1 (Windows XP)

Check that “*Install from a list or specific location (Advanced)*” is selected, then click “Next >”.

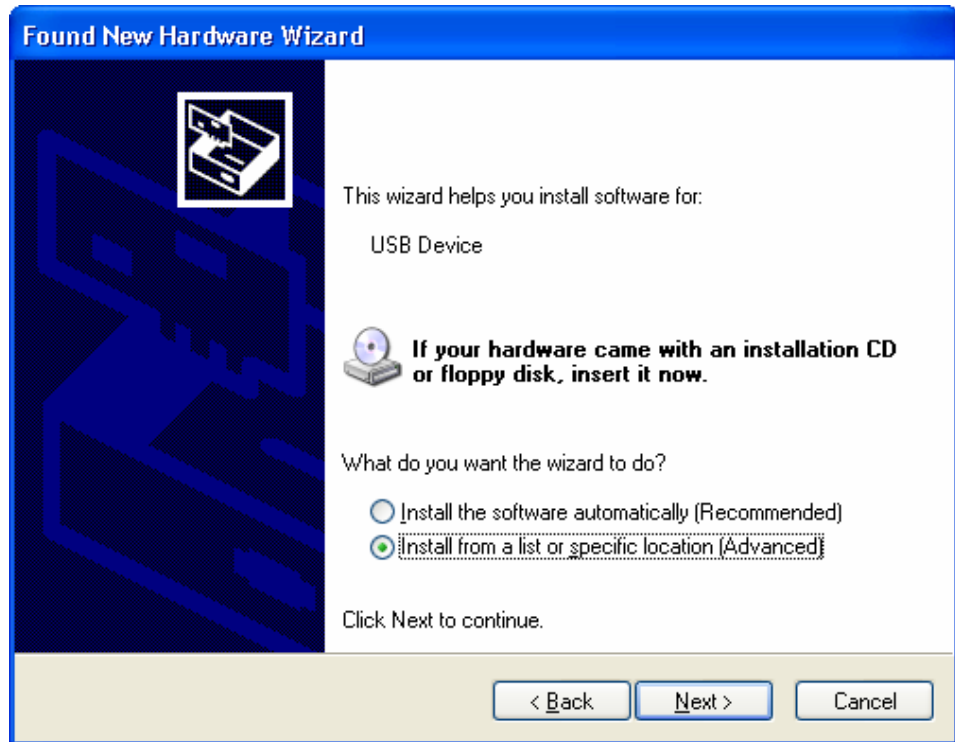


Figure 5-10 Found New Hardware Wizard 2 (Windows XP)

Check that “*Search for the best driver in these locations.*” is selected. Select the “*Include this location in the search:*” check box and then click “*Browse*”. Enter “*C:\Program Files\VAR Systems\Embedded Workbench 4.0\78K\config\nec\ie_pc_driver\MINICUBE*” in the address bar. After the USB driver has been specified click “Next >”.

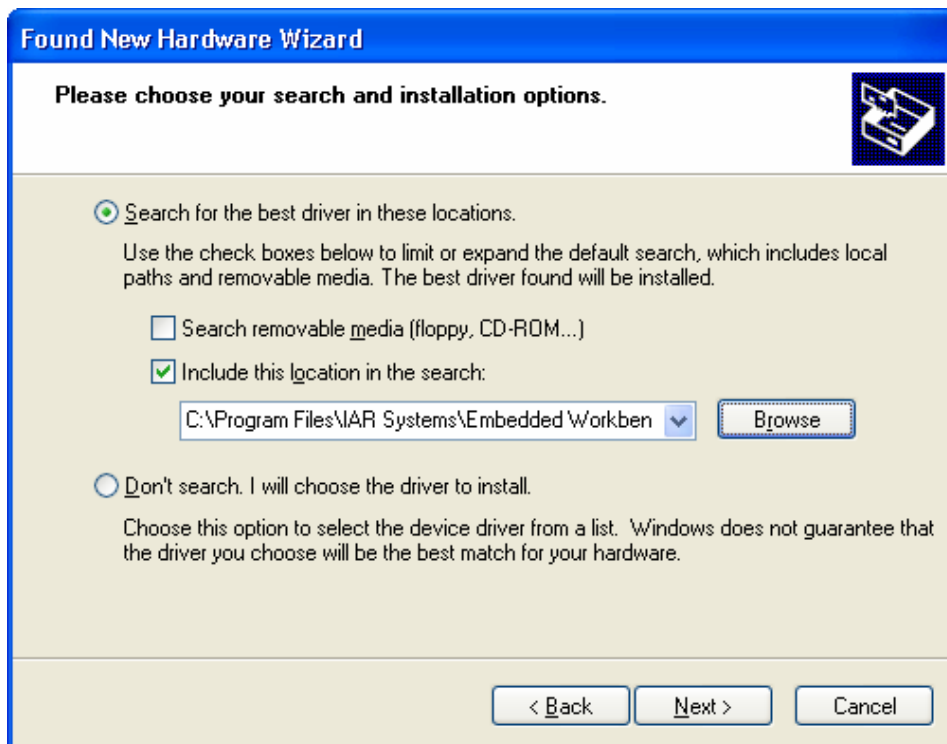


Figure 5-11 Search location specification (Windows XP)

As shown below, “has not passed Windows Logo testing to verify its compatibility with Windows XP.” is displayed. Click “Continue Anyway”.



Figure 5-12 Windows XP Logo Testing (Windows XP)

When the window below is displayed, the installation of the USB driver is completed. Click “Finish”.

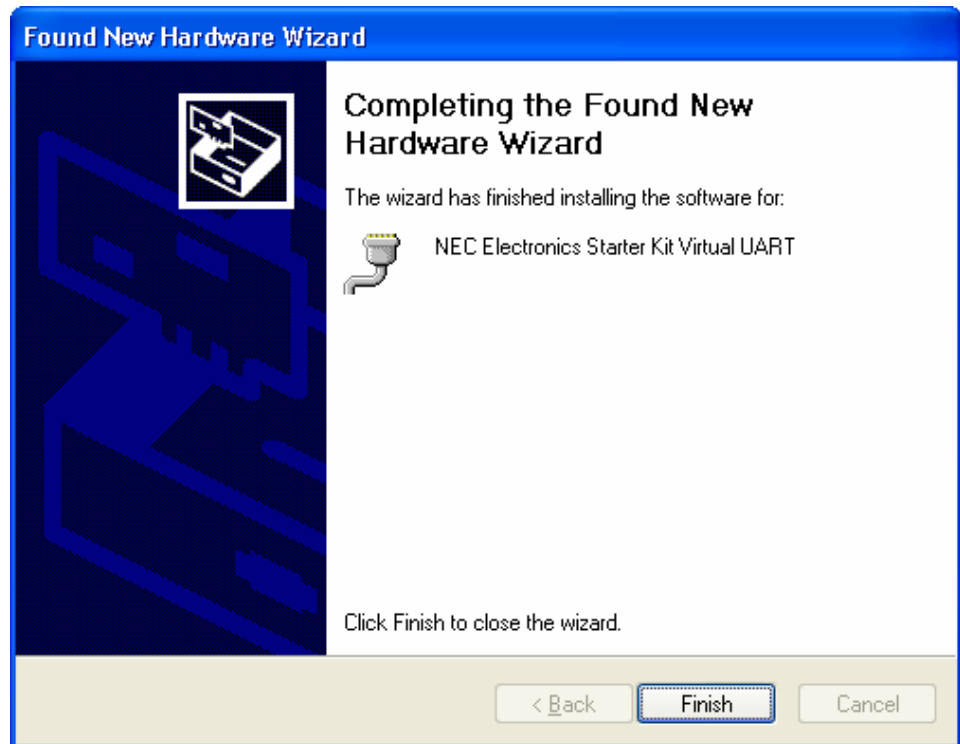


Figure 5-13 USB Serial Port Driver Installation Completion (Windows XP)

5.3.3 Confirmation of USB Driver Installation

After installing the USB driver, check that the driver has been installed normally, according to the procedure below. When using the *78K0R ZigBee™ PRO Premium Development Kit* board in combination with IAR C-SPY Debugger the “NEC Electronics Starter Kit Virtual UART” should be present in the “*Device Manager*” tab, like in the figure below.

To check that the drivers are installed normally in the “*Device Manager*”, go to Windows [Start] Menu -> [Control Panel] -> [System] -> [Hardware] -> [Device Manager] -> [Ports (COM & LPT)].

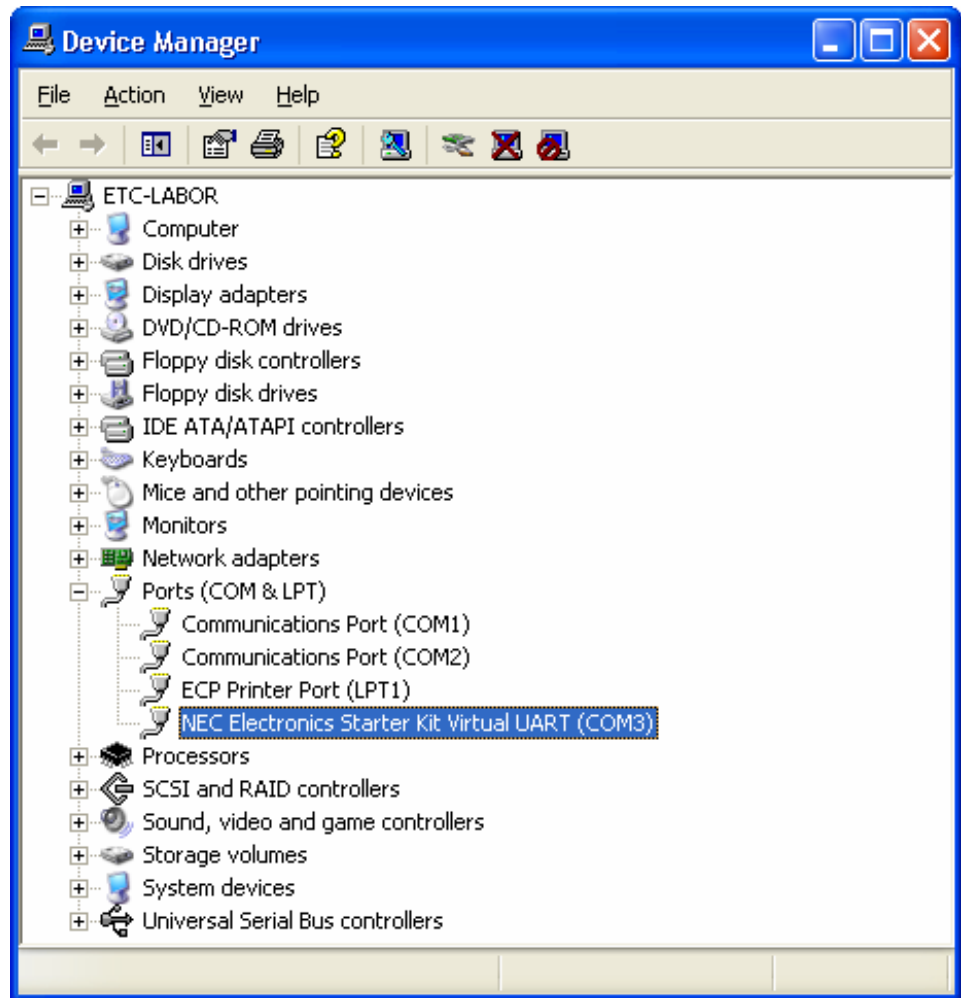


Figure 5-14 Checking the driver installations in the «Device Manager»

Chapter 6 IAR Sample Session

6.1 Loading a Project and Programming the Board

When everything is set up correctly the IAR Embedded Workbench can be started. To do so, start the Embedded Workbench from Windows [Start] menu -> [All programs] -> [IAR Systems] -> [IAR Embedded Workbench Kickstart for NEC 78K] -> [IAR Embedded Workbench]. The following screen appears:

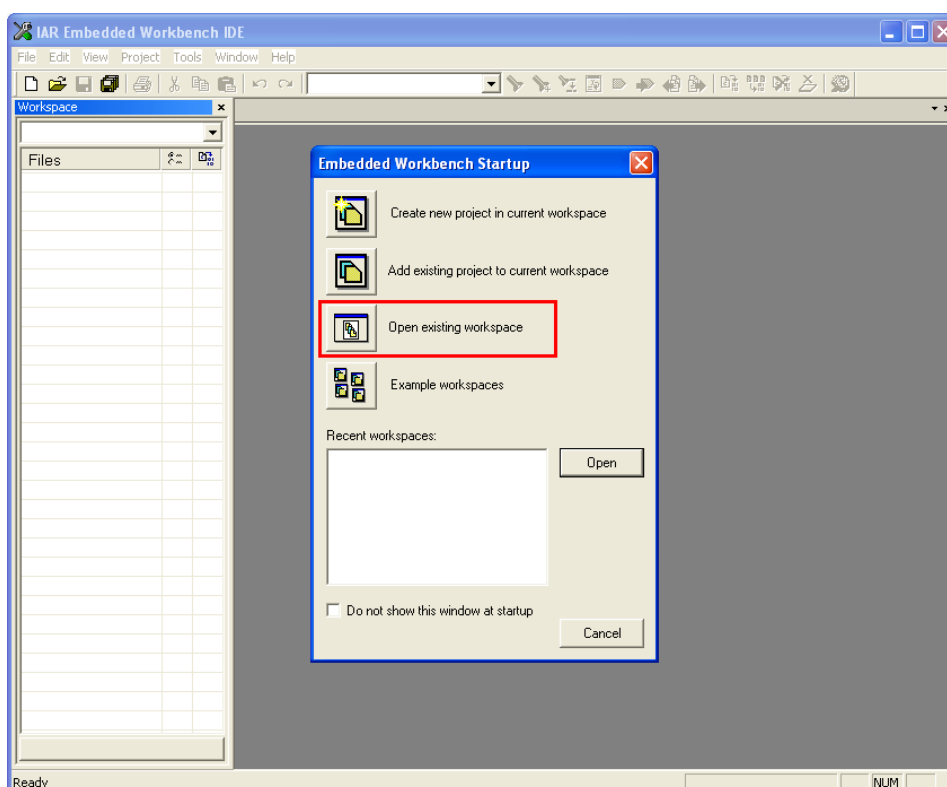


Figure 6-1 IAR Embedded Workbench startup menu

Then, open the workspace of the Sample Programs for the TK-78K0R/KG3+UZ board: [File] -> [Open] -> [Workspace] or select “Open existing project” in the start window of IAR.

Locate the sample project Programs for the TK-78K0R/KG3+UZ board. By default, the installation folder is: “C:\MyDocuments\78K0RSamplePrograms\TK-78K0RKG3+UZ”. Open the file “TK-78K0RKG3+UZ.eww”. This is the workspace file that contains general information about the demonstration projects and corresponding settings.

After the workspace has been opened the projects contained in the workspace are displayed. You should now select the project on which you want to work with the list box at the top of the workspace window. For example, you could chose the project “TK-78K0RKG3 MAC sample 1 - Debug”, then it will appear in bold in the project list. Now click on the little “+” sign next to this project filename to show all files that were part of this selected project. The screen should now look similar to this:

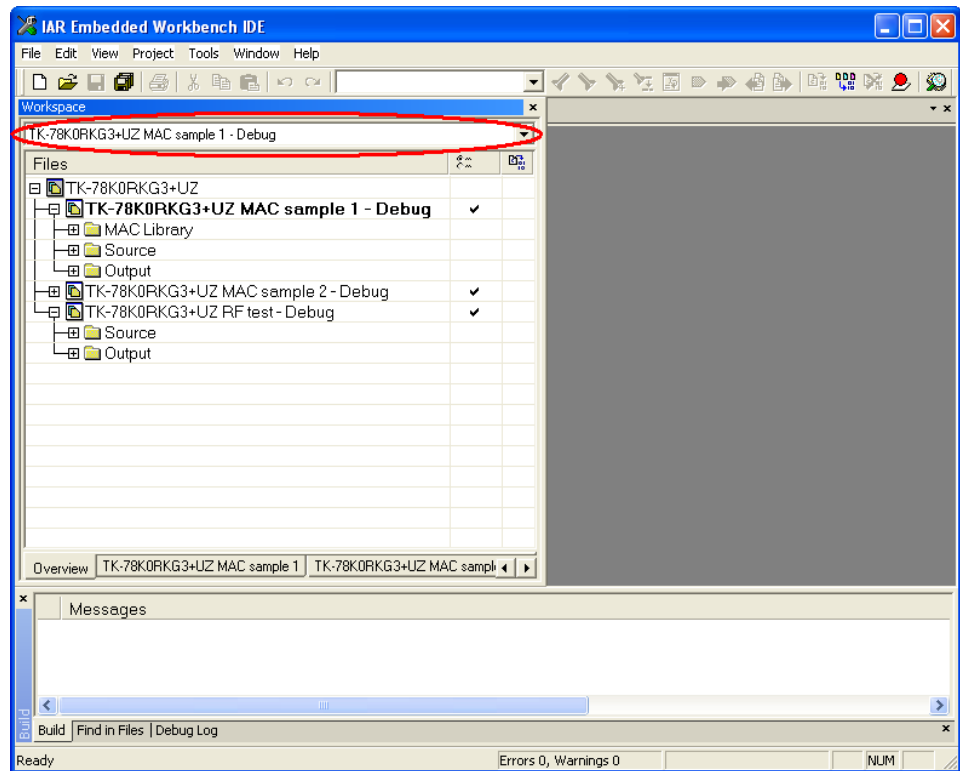


Figure 6-2 IAR project workspace

As a next step check some settings of the IAR Embedded Workbench that have to be made for correct operation and usage of the On-Board debug function of the TK-78K0R/KG3+UZ board. Similar settings should also be done in order to flash program the board via the TK interface of IAR.

First highlight the upper project folder called “TK-78K0RKG3 MAC sample 1 – Debug” in the workspace window. Then select [Project] -> [Options] from the pull-down menus.

Next select the category “Debugger”. Make sure that the driver is set to “TK-78” in order to use the On-Board debug function of the TK-78K0R/KG3+UZ board. The device description file must be set to “io78f1168_a0.ddf”. The corresponding COM port where the TK-78K0R/KG3+UZ board is connected to the host PC will be detected automatically by the IAR C-SPY debugger.

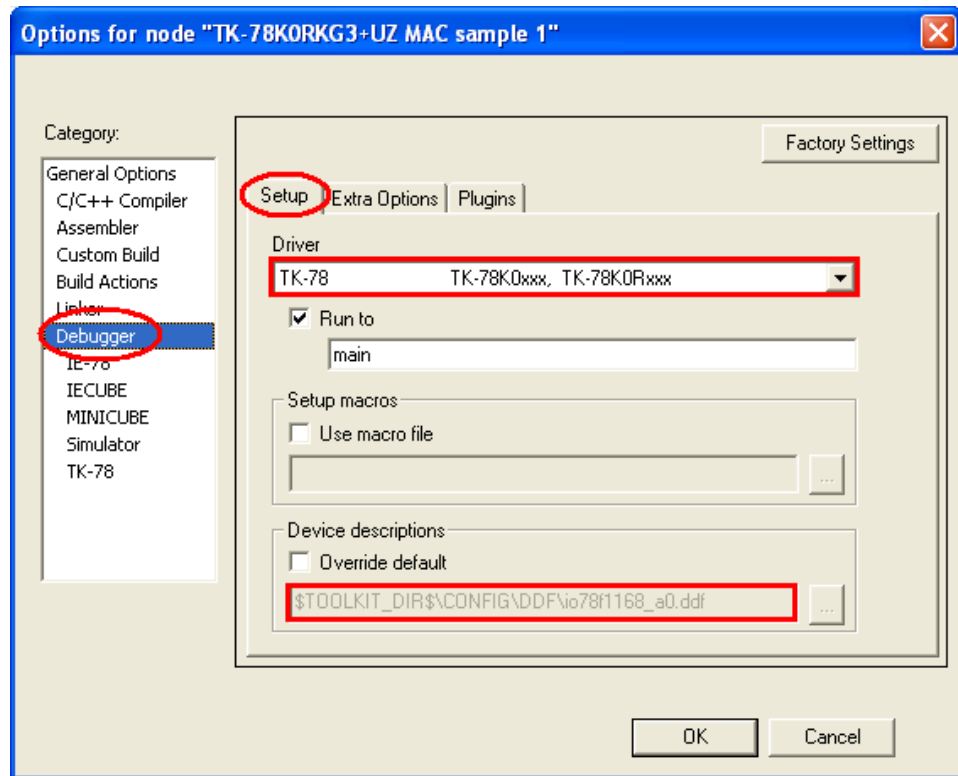


Figure 6-3 IAR Debugger options

Then it is required to check that the right output file format is selected. Select the category “Linker”. Select the “Output” tab and check that the output format will contained the debug information for the C-Spy debugger like in the screen below;

Important Remark When you are working with the TK interface of IAR to debug or to flash program a sample project, always ensure that the Debug output file format for the C-spy debugger of IAR is selected.

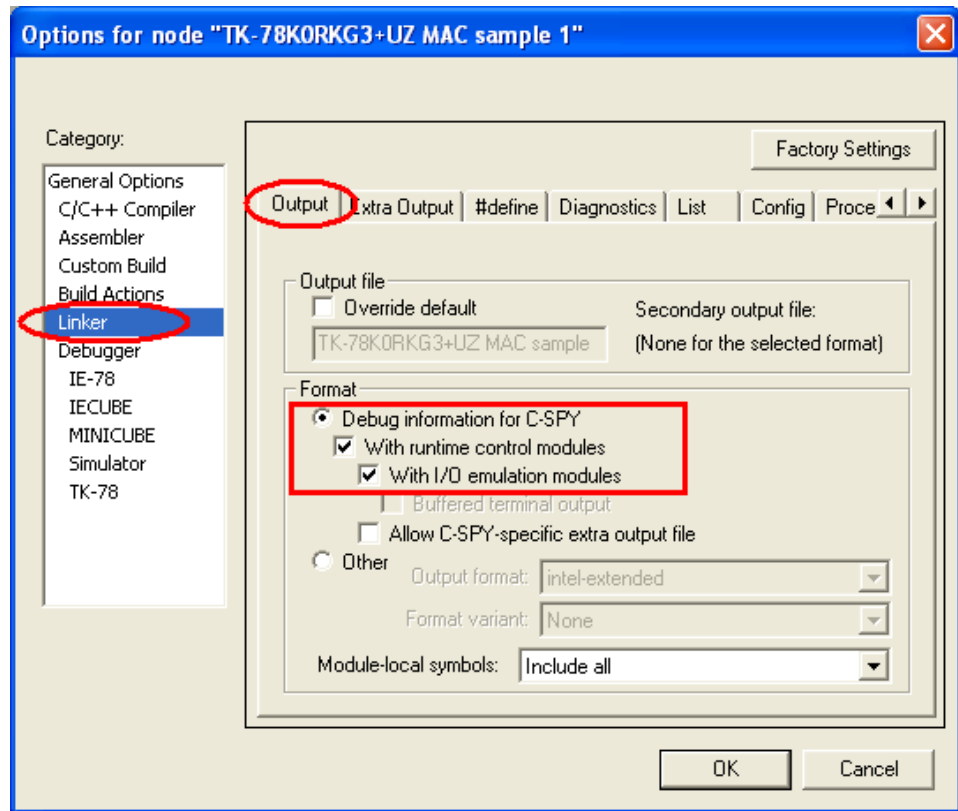


Figure 6-4 Debug output file format setting

Next the correct linker settings of the demo project will be checked. This can be done in the "Linker" category as shown below. Select the "Config" tab and check that the linker command file "lnk78f1166_a0.xcl" which is located in the directory "xcl" of the project is selected. This file is used by the linker and contains information on where to place the different sections of code, data and constants that may be used within the demo project:

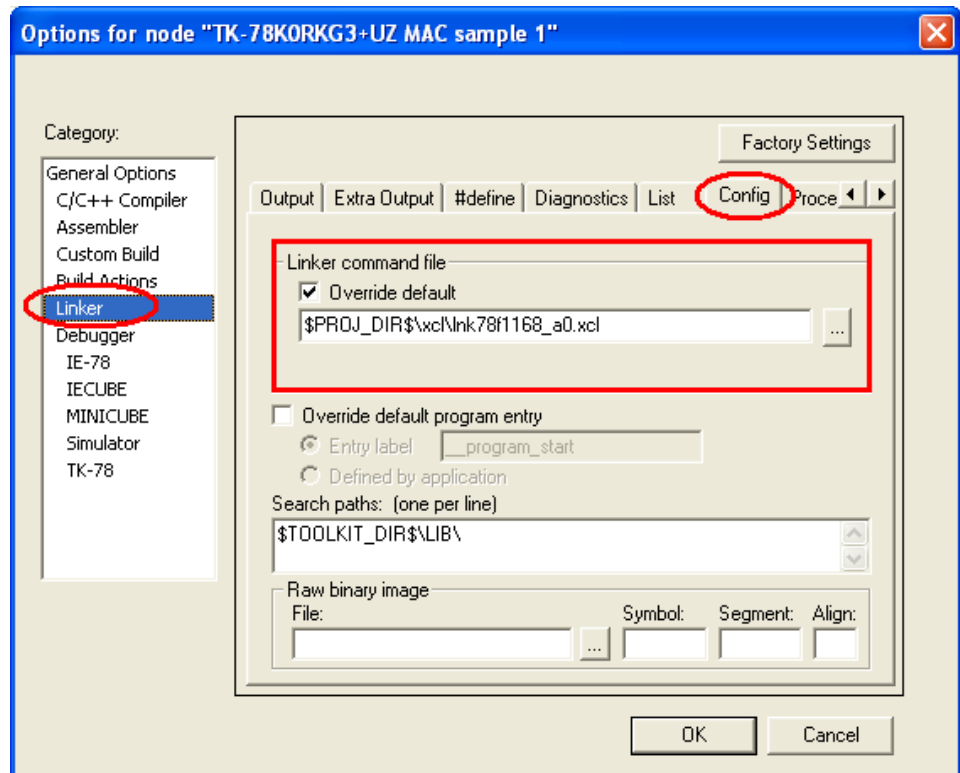


Figure 6-5 IAR Linker options

Now after everything has been setup correctly it is time to compile and link the demonstration project. Close the “Options” menu and select “Rebuild All” from the “Project” menu. If the project is compiled and linked without errors or warnings it can now be downloaded to the TK-78K0R/KG3+UZ board and debugged.

Before starting a debug session, please check that the target board configuration is set according to the settings written in the section "*On-chip debug mode with IAR TK-interface*".

Then, to start the IAR C-SPY debugger select the option “Debug” from the “Project” menu or press the “Debugger” button.



In the next step the TK-78 Emulator has to be configured before downloading a new application. Press the OK button to enter the emulator hardware setup. Set the configuration as show in the figure below and start the download by pressing the OK button.

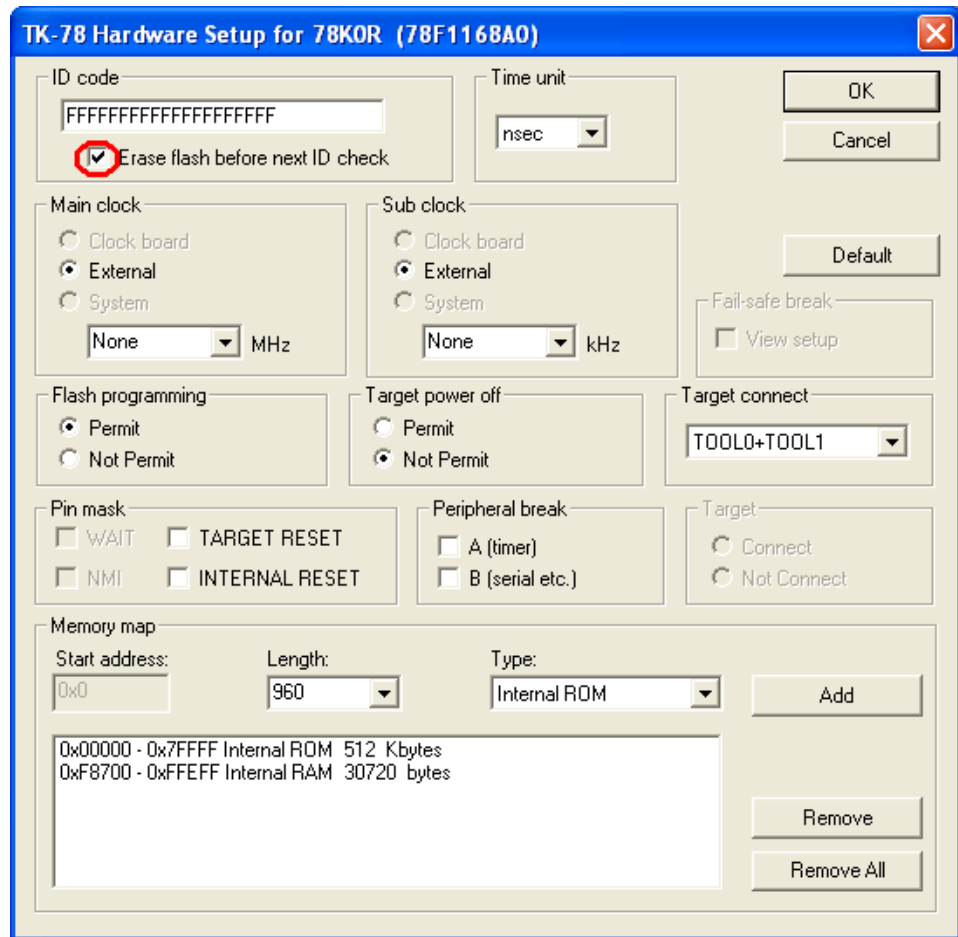


Figure 6-7 TK-78 hardware setup menu

Now the debugger is started and the demo project is downloaded to the TK-78K0R/KG3+UZ board. The progress of downloading is indicated by blue dots in the TK-78 Emulator window. Please note, downloading of larger executables can take some time.

After the download was completed all debug features of IAR C-SPY debugger are available, i.e. Single Stepping, Step Over/-In/-Out, Go-Execution, Breakpoints, Register / Memory view etc.

To get more details on the debugger configuration and capabilities please refer to the “78K IAR Embedded Workbench IDE User Guide” of the IAR installation.

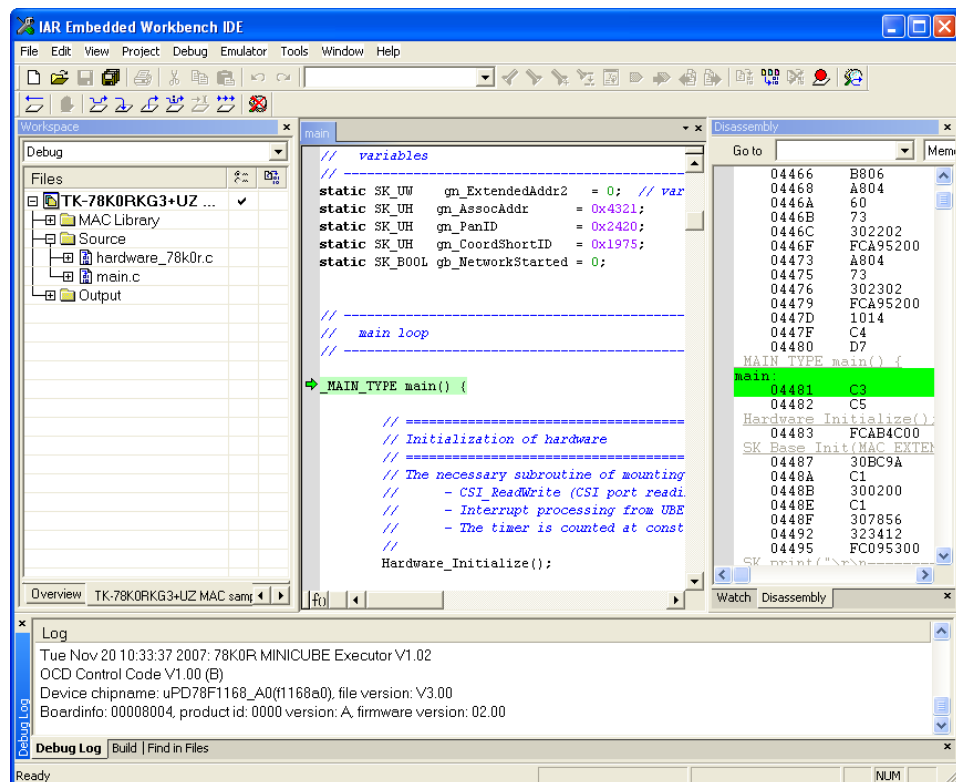


Figure 6-8 IAR C-SPY Debugger

6.2 Generating and Flash Programming a Hex File

The 78K0R/KG3+UZ boards will come pre-programmed with the “MAC sample program 2” application. In order to demonstrate the other applications or to develop your own application, you should know how to generate and program a hex file into a board.

Generation of a hex file:

To generate an output file for flash programming purpose, please select the “Release” target of your project. Then rebuild the project by selecting [Project] -> [Options] -> [Rebuilt all]. You should see the HEX file in the workspace under the directory “Output”.

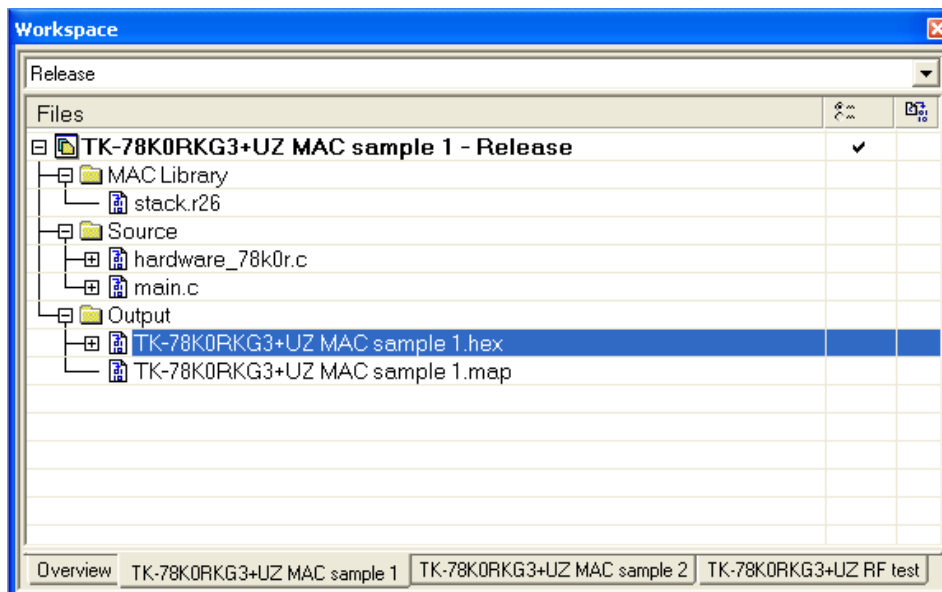


Figure 6-9 Workspace of the MAC Sample Program 1

Location of your hex file:

The generated HEX file is located in the output directory chosen for “Executable/ Libraries”. All output file directory are defined in the Embedded Workbench menu [Project] -> [Options] -> [General Options] -> [Output].

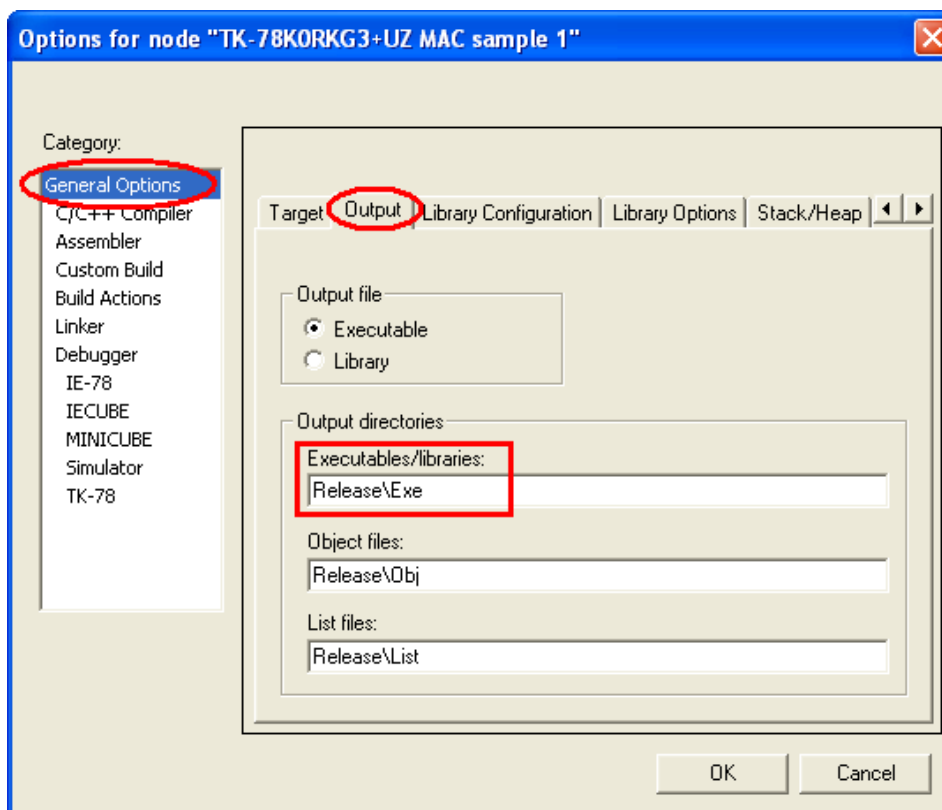


Figure 6-10 IAR output files location

In our case the directory of the MAC Sample Program 1 will be found under the folder “Exe” in the folder “Release” of the project (see the structure of the project in the section “7.1 Introduction and Structure”).

Name and format of your hex file:

The name of your output file and its format can be easily customized in the following menu that is shown in the screen below: [Project] -> [Options] -> [Linker] -> [Output].

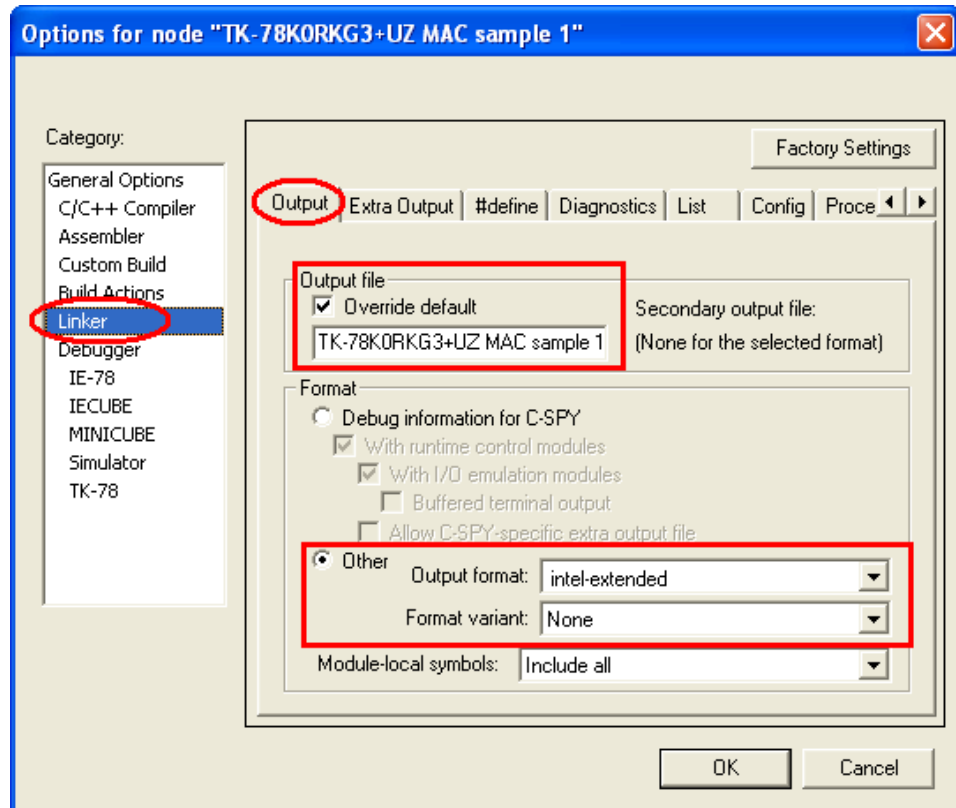


Figure 6-11 IAR output files settings: name and format

Programming the Hex file with the corresponding project:

When you just come to generate the HEX file with IAR from your “Release” target of a project, it is really easy to program it into the board: you just need to download it with the button “Debug” or with the command [Project] -> [Debug]. When the download is complete you should click the “Stop debugging” button:



and disconnect the board.

But before programming the board, you should:

- Select “TK-78” in the menu [Options] -> [Debugger] -> [Setup] -> [Driver]. When the microcontroller is part of the family 78K0R, you do not need to select the COM port of connection because IAR do that automatically. But you need to check that the board is the only one connected to your PC to avoid confusion.
- Disable the item “Run to main” in the menu [Options] -> [Debugger] -> [Setup]
- Disable the load of the stack plugin in the menu [Options] -> [Debugger] -> [Plugins]
- Set the switch in the right position given by the *Table 3-4 3.5* “On chip debug mode for the TK-78K0R/KG3+UZ”.

- Connect the board via the USB cable provided

Programming the Hex file with a default project:

If you want to program a HEX file in your TK-78K0R/KG3+UZ board but you have not the corresponding source project for IAR, you could follow these instructions:

Open any IAR project for the TK-78K0R board (RF test, MAC sample program 1 or 2), select the “Release” target.

Select “TK-78” in the [Options] -> [Debugger] -> [Setup] -> [Driver].

Disable the item “Run to main” in the menu [Options] -> [Debugger] -> [Setup].

Disable the load of the stack plugin in the menu [Options] -> [Debugger] -> [Plugins].

Set the switch in the right position given by the *Table 3-4 3.5* “On chip debug mode for the TK-78K0R/KG3+UZ”.

Connect the board via the USB cable provided (and remove any other board connected).

Replace the original HEX file of the opened project by the one you want to program, and give it the same name (see the section “*Location of your hex file*” and “*Name of your hex file*”).

What is really primordial is to change the option of IAR in order you could program the board with your chosen HEX file putting in the location of this default project. You should select “Ask” in the following menu [Tools] -> [Options] -> [Project] -> [Make before debugging].

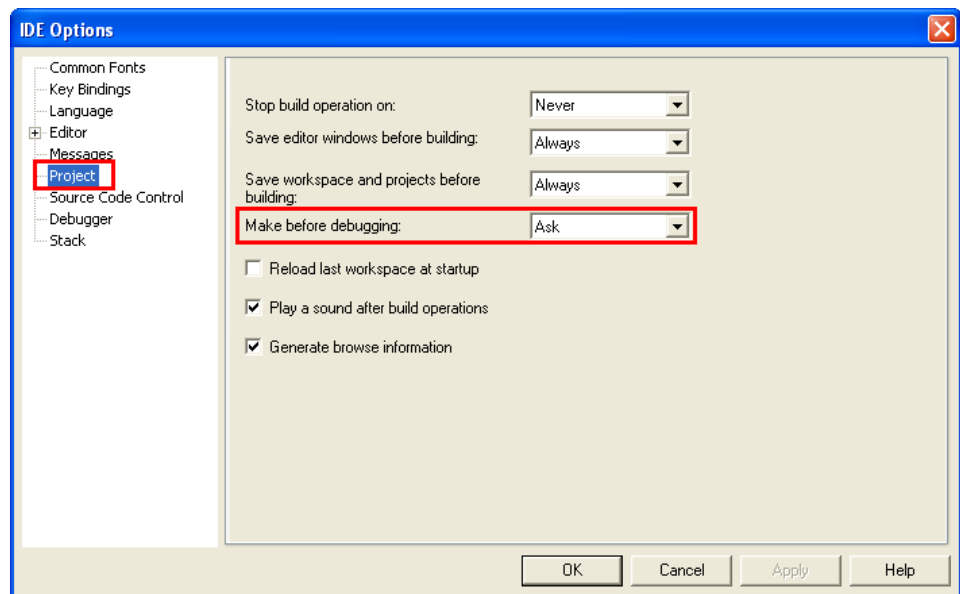


Figure 6-13 IAR environment option setting

Now you could program the board with the Debug button or by selecting the command [Project] -> [Debug].

A window will ask the following question you should answer “NO”.

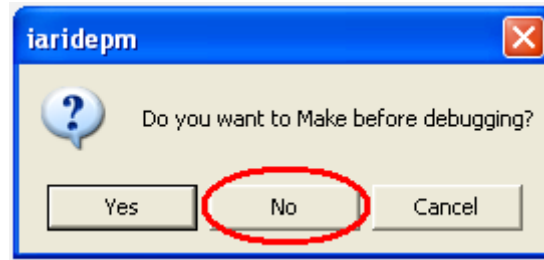


Figure 6-14 Question before debugging

After you board will be programmed, it could take more or less time depending on the size of your program. When the download is complete, you should click the “Stop Debugging” button



and disconnect the board.

- Notes**
1. In the case you want to program a HEX file into the stick via the TK interface of IAR, you should do exactly the same but using the IAR projects dedicated to the Stick, and changing the settings of the switch according to *Table 4-1 4.1 “USB interface setting of SW2 (78K0R_UZ_Stick)”*.
 2. There are different possibilities to download directly this HEX file into the flash memory of the device:
 - the TK interface of IAR (as just shown)
 - the tool Minicube2 and the QB programmer GUI
 Please note that Minicube2 is a separate product from NEC Electronics and not included in this *78K0R ZigBee™ PRO Premium Development Kit*, but can be purchased from your supplier.

6.3 Setting of different MAC address by Preprocessor command

Some settings can be done by pre-processor options like in the sample program “TK-78K0RKG3+UZ MAC sample 1”. In the MAC sample program 1, the pre-processor options are used to set the MAC address of the board.

Each board need to be programmed with a different MAC address, so before programming the device, you have to ensure that the “MAC_ADDR” pre-processor option has a unique value.

- Remark** Note that you cannot use the same output file to flash program the device, because the address will not be unique. You need to generate different output file from your project with different pre-processor options.

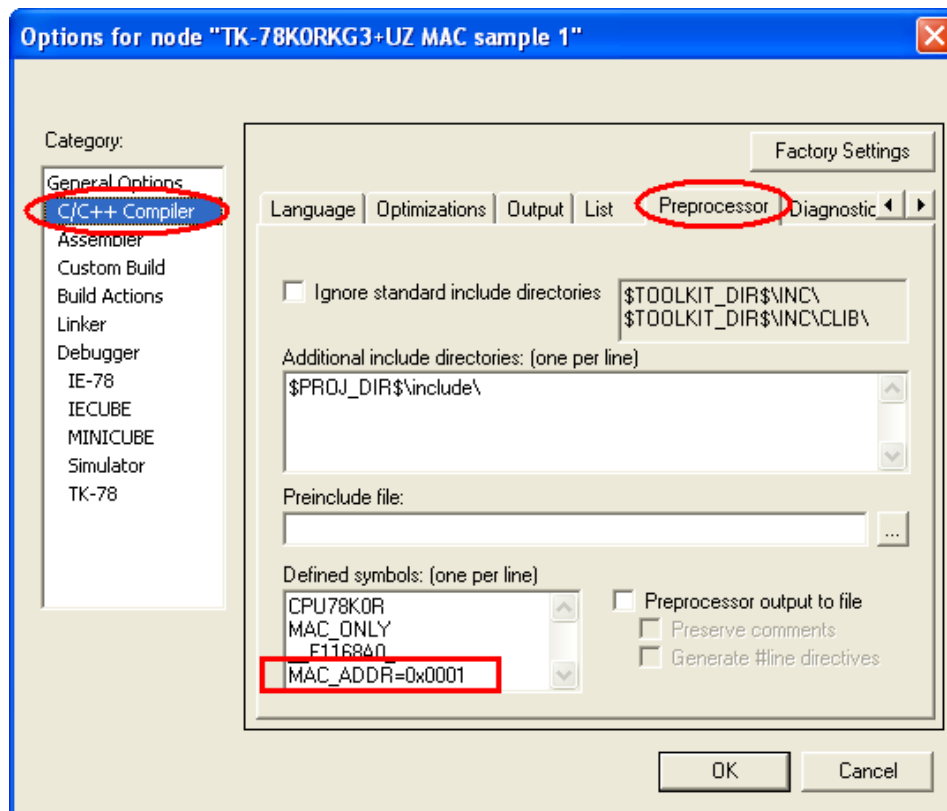


Figure 6-16 IAR Pre-processor options

6.4 Using of the UART for debugging

All the sample programs demonstrates the utilization of the UART serial interface communication via the USB port to send message and give visual information, but also to interact with the sample application (except in MAC Sample Program 2 where no action is required from the user).

The TK interface of IAR also uses the USB/UART communication for on-board debugging purpose.

Because the TK-78K0R debugging interface and the serial interface used by the application are sharing the same USB/UART port, they can not be used at the same time.

So please close the IAR C-SPY debugger after the sample program has been downloaded to the board. Unplug the USB interface and make the necessary changes on the switches of the board to allow normal serial communication via the USB port (that is to say changes the switch settings to switch from debugging mode to normal operation mode). Plug the USB interface and open a terminal program. Configure the serial com port of your terminal program and press the reset button to restart the sample program.

Chapter 7 Sample Programs

The 78K0R ZigBee™ Premium Development Kit is provided with three different sample programs.

The 78K0R ZigBee™ Premium sample projects for IAR Systems Embedded Workbench can be found directly in the folder : “C:\MyDocuments\78K0RSamplePrograms\”, (if you chose the default installation folder during the section “5.2.2 Sample Programs Installation”).

Remark If the installation destination folder was changed at the time of Sample Programs installation process, you will find them in: “<new-folder>\78K0RSamplePrograms”.

7.1 Introduction and Structure

The 3 sample programs are located in the same folder “78K0R Sample Programs”, but there is one folder for the TK-78K0R/KG3+UZ board and another for the 78K0R_UZ_Stick board.

All the sample programs for the TK-78K0R/KG3 board are located in the folder “TK-78K0RKG3+UZ” and the sample programs for the 78K0R_UZ_Stick are located in the folder “78K0R UZ Stick”. Both folders contain the associated workspace file whose extension is .EWW, and also the folder “settings” which contains the configuration files required by IAR for each workspace. Each sample program is located in a single directory, which will be called main directory of the sample, so we have these different folders associated to the Sample Programs:

- folder “MAC Sample 1”
- folder “MAC Sample 2” (Note that this sample program has not been develop for the 78K0R_UZ_Stick because there is no Joystick available on the hardware stick)
- folder “RF Test”

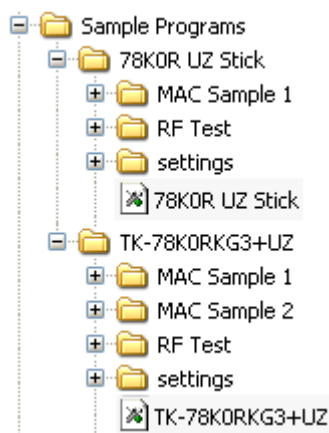


Figure 7-1 Global project structure

All the Sample Programs use the same directory structure.

- All the C sources files are located in the directory “Source”.
- The “include” directory contains all the C header files.

- The folder “MAC library” contains the IEEE.802.15.4 MAC stack library for the 78K0R.
- The “xcl” directory contains the default linker control file of the 78K0R/Kx3 device, which can be modified eventually.
- Each sample program uses the two default targets; The first target “Debug” in the folder of the same name holds all files used for debugging session and the other one “Release” (in the folder of the same name) contains the programmable files, for programming the 78K0R/Kx3 internal Flash memory via the Minicube2.
- All the configuration files for IAR Embedded Workbench are located in the folder “settings”.

Three other files can be also found in each sample program folder:

- The dependency information file .DEP
- The project setting file .EWD
- The project file .EWP

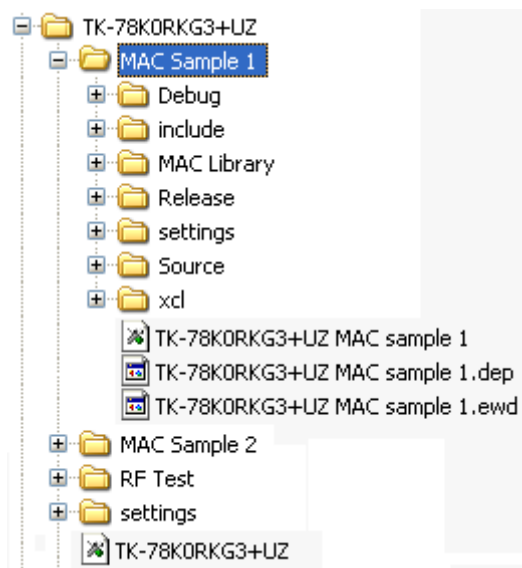


Figure 7-2 Structure of a sample project

All output file of the development tools for the corresponding target are generated by default in the directories “Debug” or “Release”, and more particularly in the sub-directory “Exe”.

For details of using IAR Embedded Workbench and the IAR C-SPY Debugger please refer to the “78K IAR Embedded Workbench IDE User Guide”.

7.2 User Configurable Network Parameters

Various network parameters will always be user specific and must be tailored to the user application; these user configurable parameters can be found in the different files.

In the header file “basic settings.h”, you will find some parameters like the default MAC address or the channel used.

```
MAC_EXTENDED_ADDRESS1
MAC_EXTENDED_ADDRESS2
RF_CHANNEL
```

In the file “main.c”, you could choose the PanID of your network, but also the default short address of your network coordinator and your end device.

```
gn_PanID -> Pan ID of the network
gn_AssocAddr -> default short address for end device
gn_CoordShortID -> default short address of the coordinator
```

7.3 System Operation

This section provides a brief overview of the operation of the sample programs provided. It is recommended that the reader familiarizes themselves with the MAC Library Reference Manual to fully understand the operation and usage of the library.

The below flow diagram shows the main program initialization and entry points for the MAC sample application 1 (Text chat).

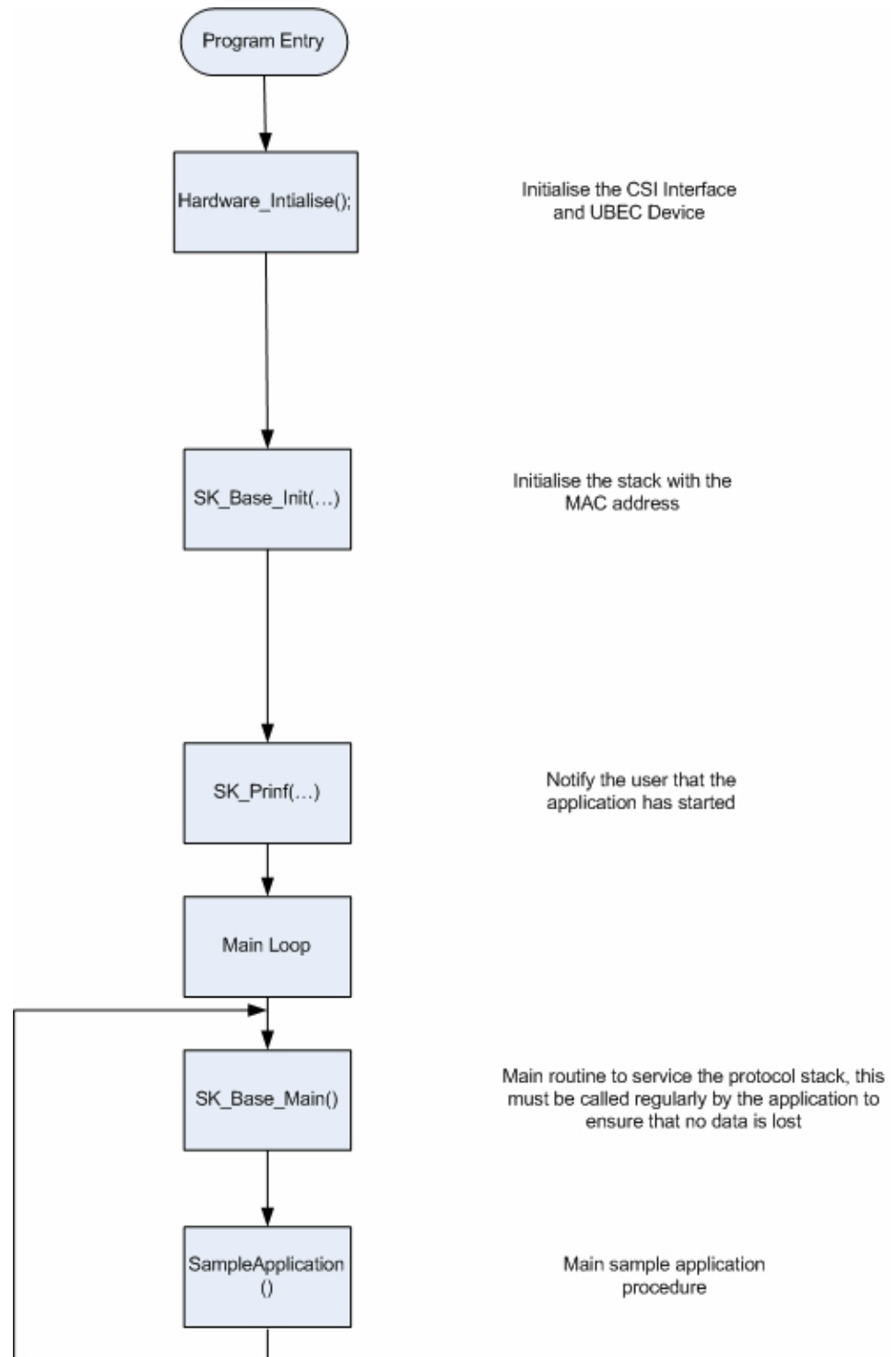


Figure 7-3 Initialization flow diagram

The main part of the program is the SampleApplication() procedure, the elements of this process are:

- Servicing the SK_LAYER_API for messages.
- Managing and actioning of the user interface.

7.3.1 Servicing the SK_LAYER_API

The following flow chart shows the message processing of the API layer, the procedure SK_GetMessage is used to determine the relevant command state and also provides a pointer to any received packet data. See the MAC Library Reference Manual for detailed explanations of the MAC commands and the API processing functions.

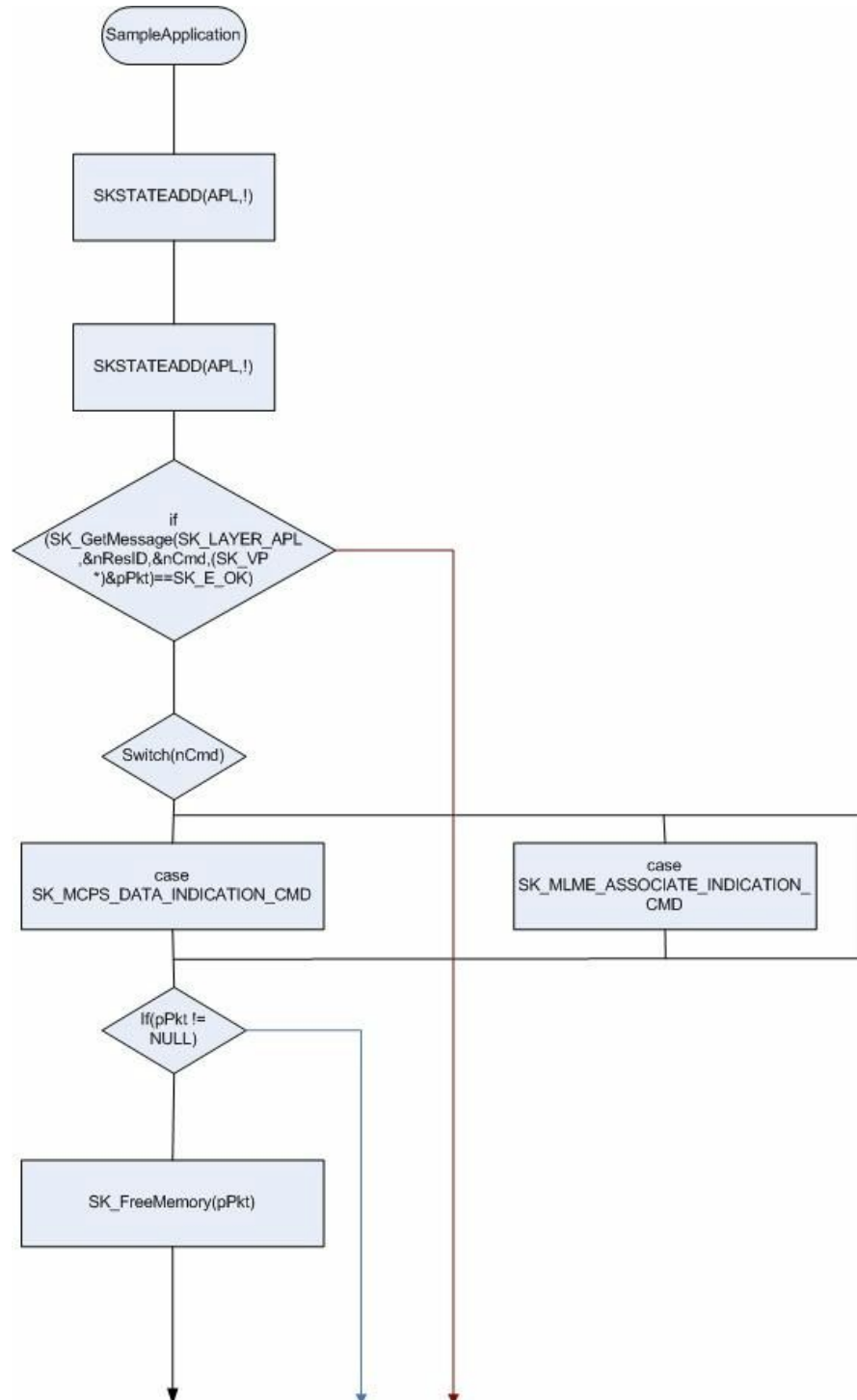


Figure 7-4 API management flow diagram

7.3.2 Managing and Actioning of the User Interface

The remainder of the procedure reads characters from the user interface and acts as a command parser. The command parser will decode the characters and process them so that the correct menu commands and relevant API calls are issued.

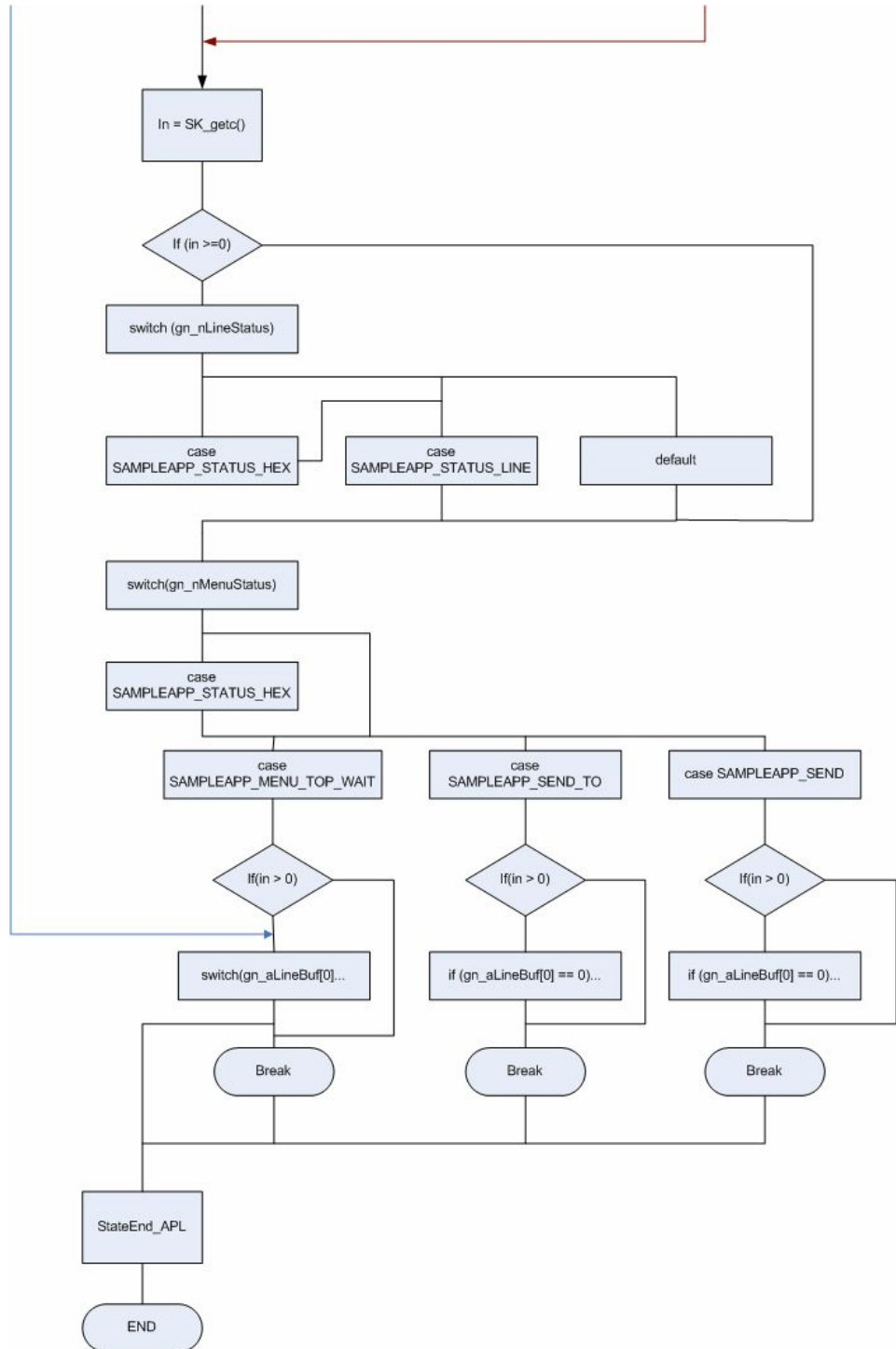


Figure 7-5 Command parser flow diagram

Chapter 8 Attachments

This document contains the following file attachments:

- Circuit Diagram of the CPU Board
- Circuit Diagram of the UZ2400 RF Board
- Circuit Diagram of 78K0R_UZ_Stick

Use the *Attachments* tab to see them.

