

General Description

DA9220 is a power management unit (PMU) suitable for supplying CPUs, GPUs, DDR memory rails in single in-line pin package (SIPP) modules, smartphones, tablets, and other handheld applications.

DA9220 integrates two single-phase buck converters, each phase requiring a small external 0.10 μ H inductor. Each buck is capable of delivering up to 3 A output current at a 0.3 V to 1.9 V output voltage range. The 2.5 V to 5.5 V input voltage range is suitable for a wide variety of low-voltage systems, including, but not limited to, all Li-Ion battery supplied applications.

With remote sensing, the DA9220 guarantees the highest accuracy and supports multiple PCB routing scenarios without loss of performance.

The pass devices are fully integrated, so no external FETs or Schottky diodes are needed.

A programmable soft start-up can be enabled, which limits the inrush current from the input node and secures a slope-controlled rail activation.

The dynamic voltage control (DVC) supports adaptive adjustment of the supply voltage dependent on the processor load, via either a direct register write using the communication interface (I²C-compatible) or with a programmable input pin.

A configurable GPI allows multiple I²C address selection for multiple instances of DA9220 in the same application.

DA9220 has integrated over-temperature and over-current protection for increased system reliability, without the need for external sensing components.

Key Features

- 2.5 V to 5.5 V input voltage
- 0.3 V to 1.9 V output voltage
- 4 MHz nominal switching frequency
- ±1 % accuracy (static)
- ±5 % accuracy (dynamic)
- I²C-compatible interface (FM+)
- Programmable GPIOs

- Programmable soft-start
- Voltage, current, and temperature supervision
- -40 °C to +85 °C ambient temperature range
- Package: 24WLCSP 2.5 mm x 1.7 mm (0.4 mm pitch)

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Applications

- SIPP modules (SoC, DRAM)
- Smartphones
- Tablet PCs
- Infotainment

- Ultrabooks[™]
- Wi-Fi Modules
- Game Consoles



System Diagrams

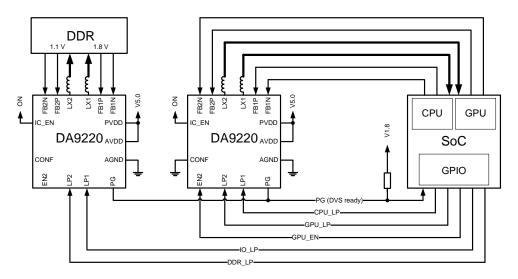


Figure 1: Typical Application Diagram (Port Control)

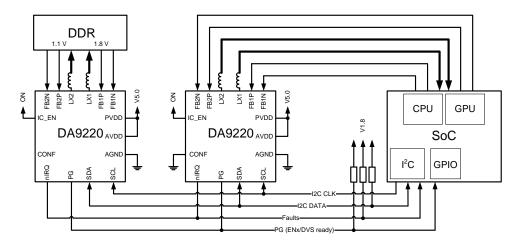


Figure 2: Typical Application Diagram (I²C Control)

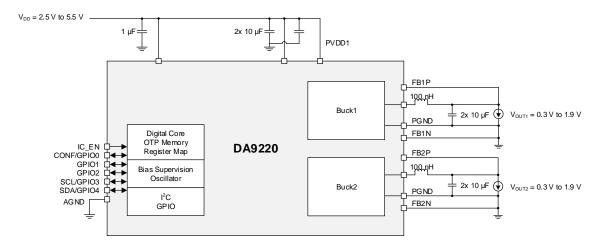


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1 Terms and Definitions

ATE Automated test equipment CPU Central processing unit

DDR Dual data rate

DVC Dynamic voltage control
FET Field effect transistor
FM+ Fast mode plus

GBD Guaranteed by design
GBQ Guaranteed by qualification

GBSPC Guaranteed by statistical process characterization

GPI General purpose input

GPIO General purpose input/output GPU Graphics processing unit

IC Integrated circuit

HW Hardware Li-lon Lithium-ion

OTP One time programmable PCB Printed circuit board

PRS Product requirements specification

SCL Serial clock SDA Serial data

SIPP Single in-line pin package

SW Software



2 Pinout

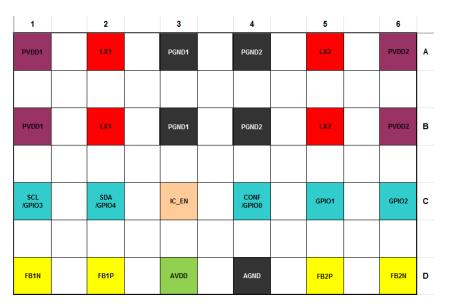




Figure 4: DA9220 Pinout Diagram (Top View)

Table 1: Pin Description

Pin No.	Pin Name	Type (Table 2)	Drive (mA)	Reset State	Description
A1, B1	PVDD1	PWR	5000		Supply voltage for Buck1 power stage, decouple with 10 µF and connect to same source as AVDD
A2, B2	LX1	AIO	5000		Switch node of Buck1, connect a 100 nH inductor between LX1 and output capacitor
A3, B3	PGND1	GND	5000		Buck1 power stage VSS rail
A4, B4	PGND2	GND	5000		Buck2 power stage VSS rail
A5, B5	LX2	AIO	5000		Switch node of Buck2, connect a 100 nH inductor between LX2 and output capacitor
A6, B6	PVDD2	PWR	5000		Supply voltage for Buck2 power stage, decouple with 10 µF and connect to same source as AVDD
C1	SCL/GPIO3	DIO	15		I ² C clock or general purpose I/O
C2	SDA/GPIO4	DIO	15		I ² C data or general purpose I/O
C3	IC_EN	Al	10		Powers up SW control interface and auxiliary circuitry (for example, bandgap, oscillator, and references).
C4	CONF/GPIO0	AI/DIO	10		Chip configuration or general purpose I/O
C5	GPIO1	DIO	10		General purpose I/O
C6	GPIO2	DIO	10		General purpose I/O
D1	FB1N	Al	10		Buck1 negative node of differential voltage feedback, connect to VSS at point of load
D2	FB1P	Al	10		Buck1 positive node of differential voltage feedback, connect to VOUT1 at point of load



Pin No.	Pin Name	Type (Table 2)	Drive (mA)	Reset State	Description
D3	AVDD	PWR	10		Supply rail for analog control circuitry, decouple with 1 µF and connect to same source as PVDD
D4	AGND	GND	10		Analog control and auxiliary circuitry VSS
D5	FB2P	AI	10		Buck2 positive node of differential voltage feedback, connect to VOUT2 at point of load
D6	FB2N	Al	10		Buck2 negative node of differential voltage feedback, connect to VSS at point of load

Table 2: Pin Type Definition

Pin Type	Description	Pin Type	Description
DI	Digital input	Al	Analog input
DO	Digital output	AO	Analog output
DIO	Digital input/output	AIO	Analog input/output
PWR	Power	GND	Ground



3 Characteristics

3.1 Absolute Maximum Ratings

Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, so functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification are not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

Table 3: Absolute Maximum Ratings

Parameter	Description	Conditions	Min	Max	Unit
T _{STG}	Storage temperature		-65	150	°C
TJ	Junction temperature		-40	150	°C
Vsys	System supply voltage		-0.3	6.0	V
V _{PIN}	Voltage on pins		-0.3	6.0	V

3.2 Recommended Operating Conditions

Table 4: Recommended Operating Conditions

Parameter	Description	Conditions (Note 1)	Min	Тур	Max	Unit
Vsys	System supply voltage		2.5		5.5	V
VPIN	Voltage on pins		-0.3		V _{SYS} + 0.3	V
TJ	Junction temperature		-40		125	°C
TA	Ambient temperature		-40		85	°C

Note 1 Within the specified limits, a lifetime of 10 years is guaranteed. If operating outside of these recommended conditions, please consult with Dialog Semiconductor.



3.3 Thermal Characteristics

3.3.1 Thermal Ratings

Table 5: Package Ratings

Parameter	Description	Conditions	Min	Тур	Max	Unit
θја	Package thermal resistance Note 1			32.7		°C/W

Note 1 Obtained from package thermal simulation, 2S2P4L board (JEDEC), influenced by PCB technology and layout.

3.3.2 Power Dissipation

Table 6: Power Dissipation

Parameter	Description	Conditions	Min	Тур	Max	Unit
P _D	Power dissipation	Derating factor above $T_A = 70^{\circ}\text{C}$: 30.6 mW/°C (1/ θ_{JA})		2140		mW

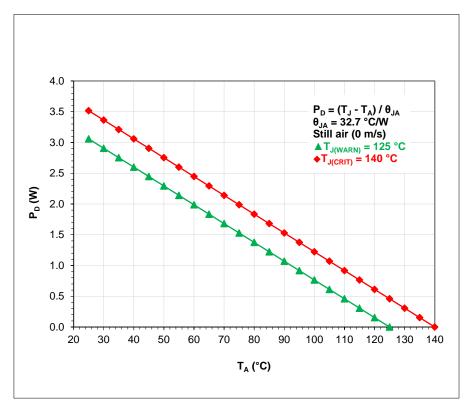


Figure 5: 24WLCSP Power Derating Curve

3.4 ESD Characteristics

Table 7: ESD Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Unit
V _{ESD_} HBM	ESD protection, human body model (HBM)				2	kV



3.5 Buck Characteristics

Unless otherwise noted, the following is valid for T_J = -40 °C to +125 °C, V_{SYS} = 2.5 V to 5.5 V

Table 8: Buck Electrical Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Unit
External Ele	ctrical Conditions					
VIN	Input voltage	V _{IN} = V _{SYS}	2.5		5.5	V
Соит	Output capacitance, per phase, including voltage and temperature coefficient		-40 %	2 x 10	+30 %	μF
ESR _{COUT}	Output capacitor series resistance, per phase	f > 100 kHz		2		mΩ
L	Inductor value, per phase, including current and temperature dependence		-50 %	0.1	+20 %	μH
DCRL	Inductor DC resistance			30	50	mΩ
Electrical Pe	erformance					
Vout	Output voltage, programmable in 10 mV steps	$I_{OUT} = 0$ mA to I_{MAX} $V_{IN} = 2.5$ V to 5.5 V	0.3		1.57	V
Vout_lim	Output voltage, programmable in 10 mV steps	I _{OUT} = 0 mA to I _{MAX} V _{IN} = 3.0 V to 5.5 V	0.3		1.9	V
Ішм	Current limit, programmable per phase Note 1	CHx_ILIM = 1010	-20 %	8	+20 %	A
Vout_acc	Output voltage accuracy, including static line and load regulation	V _{OUT} ≥ 1 V	-1		1	%
Vout_acc	Output voltage accuracy, including static line and load regulation	Vout < 1 V	-10		10	mV
VTHR_PG_RISE	Power good voltage threshold for rising	Referred to Vout	-80	-50	-20	mV
VTHR_PG_DWN	Power good voltage threshold for falling	Referred to Vout	-160	-130	-100	mV
V _{THR_HV}	High V _{OUT} voltage threshold	Referred to V _{OUT}	100	150	200	mV
Vout_tr_line	Line transient response	V _{IN} = 3 V to 3.6 V I _{OUT} = 0.5 * I _{MAX} dt = 10 μs		15		mV
fsw	Switching frequency, post-trim			4		MHz



Parameter	Description	Conditions	Min	Тур	Max	Unit
ton_min	Minimum turn-on pulse 0 % duty is also supported			20		ns
tbuck_en	Turn-on time	CHx_EN = high			20	μs
R _{PD}	Output pull-down resistance for each phase at the LX node, see CHx_PD_DIS	V _{IN} = 3.7 V V _{OUT} = 0.5 V	100	150	200	Ω
R _{ON_PMOS}	On resistance of switching PMOS, per phase	V _{IN} = 3.7 V		36		mΩ
Ron_nmos	On resistance of switching NMOS, per phase	V _{IN} = 3.7 V		17		mΩ
AUTO Mode						
VOUT_TR_LD_1 PH	Load transient response	1-phase V _{OUT} = 1 V I _{OUT} = 0 A to 5 A dl/dt = 10 A/µs		±5		%
PFM Mode						
IQ_PFM_1PH	Quiescent current in PFM	1-phase V _{IN} = 3.7 V No load No switching		88		μА

Note 1 $t_{ON} > 40 \text{ ns}$

3.6 Performance and Supervision Characteristics

Table 9: Electrical Characteristics

Parameter	Description Conditions		Min	Тур	Max	Unit		
Electrical Pe	Electrical Performance							
V _{THR_POR}	Power-on-reset threshold	Threshold for AVDD falling		2.1	2.25	V		
V _{THR_POR_HY}	Power-on-reset hysteresis			200		mV		
Twarn	Thermal warning temperature threshold		115	125	135	°C		
T _{CRIT}	Thermal shutdown temperature threshold		130	140	150	°C		
lin_off	Supply current	OFF state TA = 27 °C IC_EN = 0		0.1	1	μΑ		



Parameter	Description	Conditions	Min	Тур	Max	Unit
lin_on	Supply current	ON state TA = 27 °C IC_EN = 1 Buck off	5	10	20	μΑ

3.7 Digital I/O Characteristics

Table 10: Digital I/O Electrical Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Unit			
Electrical Pe	Electrical Performance								
V _{IH_EN}	Input high voltage, IC enable		1.2		AVDD	V			
VIL_EN	Input low voltage, IC enable				0.4	V			
tic_en	IC enable time				1000	μs			
VIH_GPIO_SCL _SDA	Input high voltage GPIO, SCL, SDA		1.2		AVDD	V			
VIL_GPIO_SCL_ SDA	Input low voltage GPIO, SCL, SDA				0.4	V			
Voh_gpio	Output high voltage GPIO	Push-pull mode lout = 1 mA	0.8*AV DD		AVDD	V			
Vol_gpio	Output low voltage GPIO	Push-pull mode I _{OUT} = 1 mA			0.2*AV DD	V			
Vol_sda	Output low voltage SDA	I _{OUT} = 3 mA		0.24		V			
R _{PD}	GPIO pull-down resistor		2	10	120	kΩ			
R _{PU}	GPIO pull-up resistor		2	10	120	kΩ			



3.8 Timing Characteristics

Table 11: I2C Electrical Characteristics

Parameter	Description	Conditions	Min	Тур	Max	Unit		
Electrical Performance								
t _{BUS}	Bus free time between a STOP and START condition		0.5			μs		
C _{BUS}	Bus line capacitive load				150	pF		
fscL	SCL clock frequency		20 Note 1		1000	kHz		
tLO_SCL	SCL low time		0.5			μs		
thi_scl	SCL high time		0.26			μs		
trise	SCL and SDA rise time	Requirement for input			1000	ns		
tFALL	SCL and SDA fall time	Requirement for input			300	ns		
tsetup_start	Start condition setup time		0.26			μs		
thold_start	Start condition hold time		0.26			μs		
tsetup_stop	Stop condition setup time		0.26			μs		
t _{DATA}	Data valid time				0.45	μs		
t _{DATA_ACK}	Data valid acknowledge time				0.45	μs		
tsetup_data	Data setup time		50			ns		
thold_data	Data hold time		0			ns		

Note 1 Minimum clock frequency is limited to 20 kHz if I2C_TIMEOUT is enabled



3.9 Typical Performance

Unless otherwise noted, $V_{IN} = 3.7$ V, $V_{OUT} = 1.0$ V, $T_A = 25$ °C, 2.0 mm x 1.6 mm 0.1 μH output inductor (DCR = typ. 11.5 m Ω) and 2 x 10 μF output capacitors per-channel.

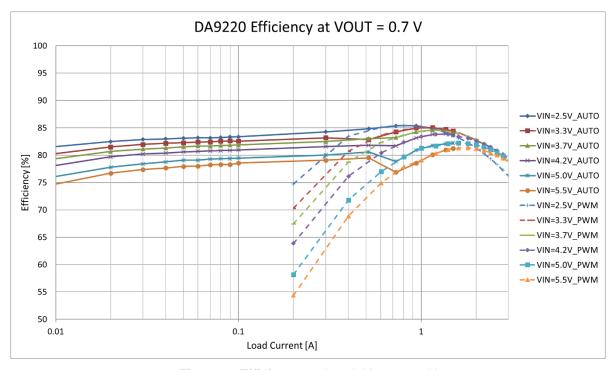


Figure 6: Efficiency vs Load, Vout = 0.7 V

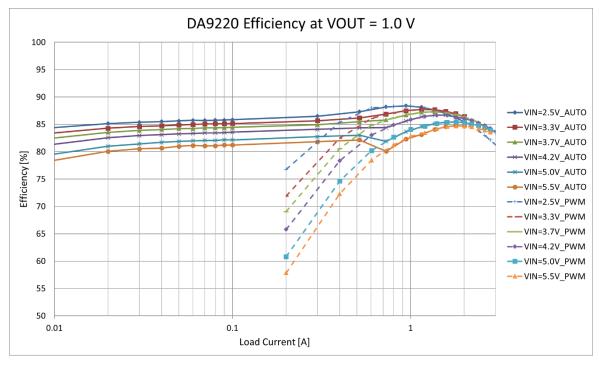


Figure 7: Efficiency vs Load, Vout = 1.0 V



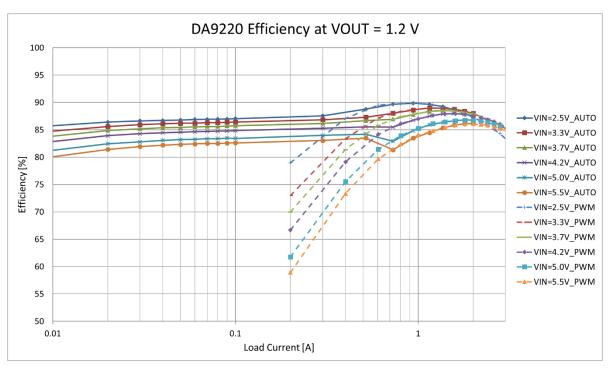


Figure 8: Efficiency vs Load, V_{OUT} = 1.2 V

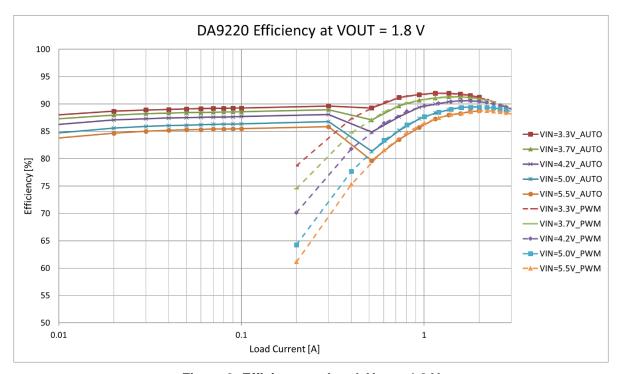


Figure 9: Efficiency vs Load, Vout = 1.8 V



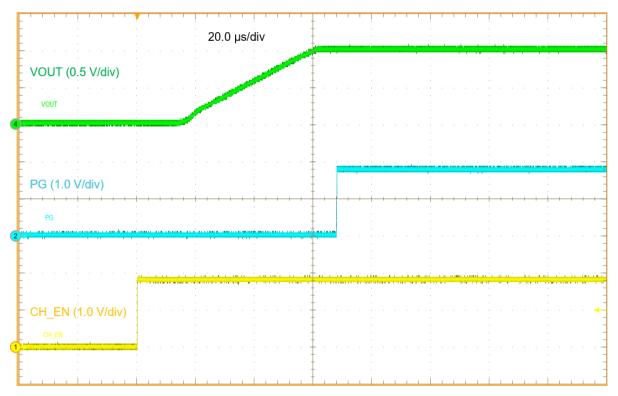


Figure 10: Buck Soft Start-up at 20 mV/µs Slew Rate

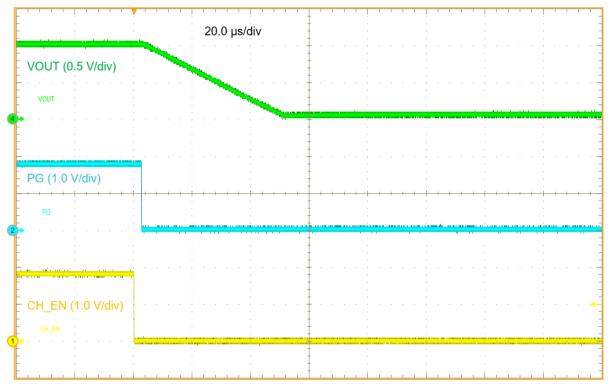


Figure 11: Buck Active Shutdown at 20 mV/µs Slew Rate



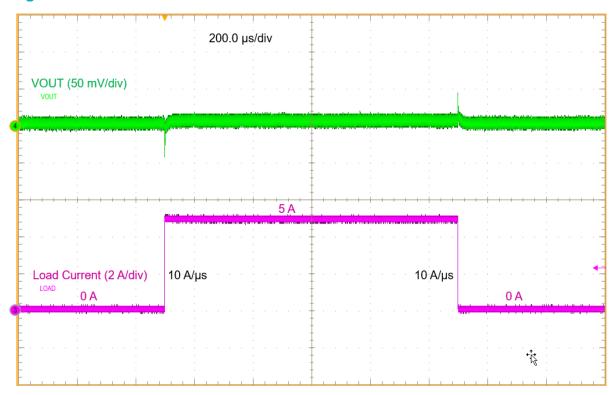


Figure 12: Buck Load Transient Response in PWM Mode, 0 A to 5 A at 10 A/ μ s

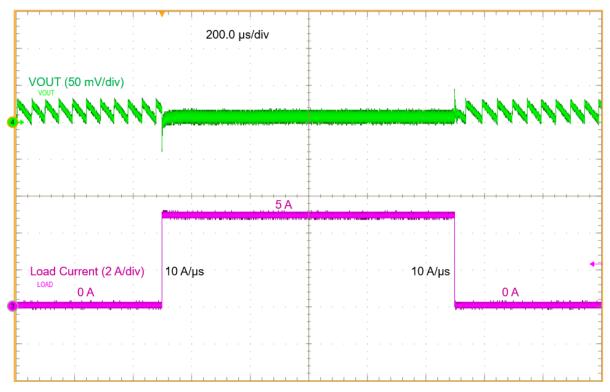


Figure 13: Buck Load Transient Response in AUTO Mode, 0 A to 5 A at 10 A/µs



4 Functional Description

4.1 DC-DC Buck Converter

DA9220 contains two buck converters, Buck1 and Buck2, each capable of delivering up to 3 A output current at a 0.3 V to 1.9 V output voltage range.

Buck1 and Buck2 have two voltage registers each. One defines the normal output voltage, while the other offers an alternative retention voltage. In this way, different application power modes can easily be supported. The voltage selection can be operated either via GPI or via control interface to guarantee the maximum flexibility according to the specific host processor status in the application.

When a buck is enabled, its output voltage is monitored and a power good signal indicates that the buck output voltage has reached a level higher than the V_{THR_PG_RISE} threshold. The power good status is lost when the voltage drops below V_{THR_PG_DWN} or increases above V_{THR_HV}. For each of the buck converters the status of the power good indicator can be read back via I²C from the PG1 and PG2 status bits. It can be also individually assigned to any of the GPIOs by setting the GPIO mode registers to either PG1 or PG2 output.

The buck converters are capable of supporting DVC transitions that occur:

- When the active and selected A- or B-voltage is updated to a new target value.
- When the voltage selection is changed from the A- to B-voltage (or B- to A-voltage) using CH<x>_VSEL.

The DVC controller operates in pulse width modulation (PWM) mode with synchronous rectification.

The slew rate of the DVC transition is individually programmed for each buck converter at 10 mV per 8 μ s, 4 μ s, 2 μ s, 1 μ s, or 0.5 μ s in register bits CH1_SR_DVC and CH2_SR_DVC.

A pull-down resistor (typically 150 Ω) for each phase is always activated unless it is disabled by setting register bits CH<x>_PD_DIS to 1.

4.1.1 Switching Frequency

The buck switching frequency can be tuned using register bit OSC_TUNE. The internal 8 MHz oscillator frequency is tuned in ±160 kHz steps. This impacts the buck converter frequency in steps of 80 kHz and helps to mitigate possible disturbances to other high frequency systems in the application.

4.1.2 Operation Modes and Phase Selection

The buck converters can operate in PWM and PFM modes. The operating mode is selected using register bits CH1_<A or B>_MODE and CH2_<A or B>_MODE.

If the automatic operation mode is selected on CH1_<A or B>_MODE or CH2_<A or B>_MODE, the buck converters automatically change between synchronous PWM mode and PFM depending on the load current. This improves the efficiency across the whole range of output load currents.



4.1.3 Output Voltage Selection

The switching converter can be configured using the I²C interface.

For each buck converter two output voltages can be pre-configured in registers CH<x>_<A or B>_VOUT. The output voltage can be selected by either toggling register bit CH<x>_VSEL or by reprogramming the selected voltage control register. Both changes will result in ramped voltage transitions. After being enabled, the buck converter will, by default, use the register settings in CH<x>_A_VOUT unless the output voltage selection is configured via the GPI port.

Registers CH<1 and 2>_VMAX limit the output voltage that can be set for each of the respective buck converters.

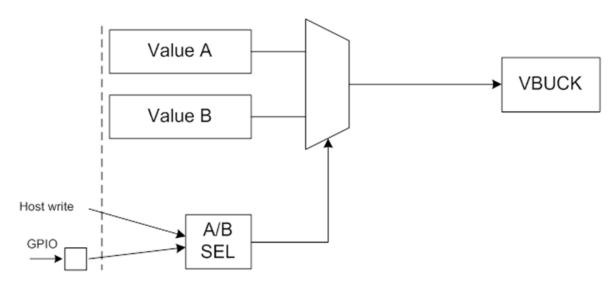


Figure 14: Buck Output Voltage Control Concept

4.1.4 Soft Start-Up and Shutdown

To limit in-rush current from VSYS, the buck converters can perform a soft-start after being enabled. The start-up behavior is a compromise between acceptable inrush current from the battery and turn-on time. Individual ramp times can be configured for each buck converter in registers CH<1 and 2>_SR_STARTUP respectively. Rates higher than 20 mV/µs may produce overshoot during the start-up phase, so they should be considered carefully.

A ramped power down can be selected in register bits CH<1 and 2>_SR_SHDN. When no ramp is selected (immediate power down), the output node will be discharged only by the pull-down resistor, if enabled in registers CH<1 and 2> PD_DIS.

4.1.5 Current Limit

The integrated current limit protects the power stages and external coil from excessive current. The buck current limit should be configured to at least 40 % higher than the required maximum output current.

When the current limit is reached, each buck converter generates an event and an interrupt to the host processor unless the interrupt has been masked using register M_OC<x> in SYS_MASK_1. Register bits OC DVC MASK is used to mask over-current events during DVC transitions.



4.1.6 Thermal Protection

DA9220 is protected from internal overheating by thermal shutdown.

There are two kinds of flags concerning thermal protection, thermal warning and thermal critical. The warning flag is asserted when $T_J > T_{WARN}$ and the critical flag is asserted when $T_J > T_{CRIT}$. When the critical flag is asserted, Buck1 and 2 are shut down immediately.

Table 12: Thermal Protection Control Registers

Category	Register name	Description
Status	TEMP_WARN	Asserted as long as the thermal warning threshold is reached
Sidius	TEMP_CRIT	Asserted as long as the thermal shutdown threshold is reached
IDO avent	E_TEMP_WARN	TEMP_WARN caused event
IRQ event	E_TEMP_CRIT	TEMP_CRIT caused event
	M_TEMP_WARN	TEMP_WARN event IRQ mask
IRQ mask	M_TEMP_CRIT	TEMP_CRIT event IRQ mask
	M_VR_HOT	TEMP_WARN status IRQ mask

Junction Temperature Warning Flag Critical Flag Buck Enable Buck Enable

Figure 15: Thermal Protection Operation



4.2 Internal Circuits

4.2.1 IC_EN/Chip Enable/Disable

IC_EN is chip enable/disable control input. When IC_EN = 0, all blocks except for low I_Q POR are powered-down and buck output is pulled-down.

4.2.2 nIRQ/Interrupt

The interrupt triggers events. Trigger conditions and control registers for each interrupt event are listed in Table 13.

Some of these events are categorized as fault events and affect device operation (for example, buck disable), see Section 4.1.6.

Table 13: Interrupt List

Name	Polarity (Note 1)	Trigger	IRQ Status Register	IRQ Mask Register	Deglitch Period
Thermal warning (event)	N	Tյ rising above TwaRN	E_TEMP_WARN	M_TEMP_WARN	0 s
Thermal critical (event)	N	T _J rising above T _{CRIT}	E_TEMP_CRIT	M_TEMP_CRIT	0 s
System good (event)	Р		E_SG	M_SG	0 s
Buck1 power-good (event)	Р	Buck1 V _{OUT} is in power-good voltage range (not under- or over-voltage)	E_PG1	M_PG1	0 s
Buck2 power-good (event)	Р	Buck2 V _{OUT} is in power-good voltage range (not under- or over-voltage)	E_PG2	M_PG2	0 s
Buck1 over-voltage (event)	N	Buck1 V _{OUT} rising above over-voltage threshold (target voltage + 150 mV)	E_OV1	M_OV1	Rise:8 μs Fall:8 μs
Buck2 over-voltage (event)	N	Buck2 V _{OUT} rising above over-voltage threshold (target voltage + 150 mV)	E_OV2	M_OV2	Rise:8 µs Fall:8 µs
Buck1 under- voltage (event)	N	Buck1 V _{OUT} falling below under-voltage threshold (target voltage - V _{TH_PG)}	E_UV1	M_UV1	0 s
Buck2 under- voltage (event)	N	Buck2 Vouт falling below under-voltage threshold (target voltage - Vтн_PG)	E_UV2	M_UV2	0 s
Buck1 over-current (event)	N	Buck1 current rising above over-current threshold	E_OC1	M_OC1	0 s



Name	Polarity (Note 1)	Trigger	IRQ Status Register	IRQ Mask Register	Deglitch Period
Buck2 over-current (event)	N	Buck2 current rising above over-current threshold	E_OC2	M_OC2	0 s
Buck1 power-good (status) (Note 2)	Р	Buck1 V _{OUT} is in power-good voltage range (not under- or over-voltage)	PG1	M_PG1_STAT (Note 3)	0 s
Buck2 power-good (status) (Note 2)	Р	Buck2 V _{OUT} is in power-good voltage range (not under- or over-voltage)	PG2	M_PG2_STAT (Note 3)	0 s
System good (status) (Note 2)	Р		SG	M_SG_STAT (Note 3)	0 s
Thermal warning (status) (Note 2)	N	T _J rising above T _{WARN}	TEMP_WARN	M_VR_HOT (Note 3)	0 s
GPIO0 change (event)	N	Detect GPIO0 change for active trigger selected GPIO0_TRIG register	E_GPIO0	M_GPIO0	- 100 μs/
GPIO1 change (event)	N	Detect GPIO1 change for active trigger selected GPIO1_TRIG register	E_GPIO1	M_GPIO1	1 ms/ 10 ms/ 100 ms
GPIO2 change (event)	N	Detect GPIO2 change for active trigger selected GPIO2_TRIG register	E_GPIO2	M_GPIO2	

Note 1 Polarity at the source of the flag: P = active-high, N = active-low.

General rule is: normal system state is high, and abnormal system state is low (for example, PG = high means power-good, $TEMP_CRIT = low$ when TEMP critical state).

- **Note 2** Interrupt outputs the status as is. I²C write is not required for interrupt clear.
- Note 3 OTP load value defined by CONF pin setting if CONF_EN = 1.



Table 14: Interrupt Registers Except for Power Good Status

Register	Description
E_ <name></name>	Read-only interrupt event register
	0: No interrupt
	1: Interrupt occurred
	Cleared after being written to I ² C. Set until IRQ is removed.
M_ <name></name>	Interrupt mask register
	0: Not masked
	1: Masked. No IRQ signal sent. Event register (E_ <name>) is updated.</name>

Table 15: Interrupt Registers for Power Good, System Good, and Temp Warning Status

Register	Description
PG <x></x>	Buck <x> power good status. Asserted as long as the buck<x> output voltage is in range (under-voltage threshold < buck output voltage < over-voltage threshold) 0: Not power good 1: Power good</x></x>
M_PG <x>_STAT</x>	Power good status interrupt mask register 0: Not masked 1: Masked. No IRQ signal sent. Power good status register (PG <x>) is updated</x>
SG	System good status 0: Not system good 1: System good
M_SG_STAT	System good status (SG) interrupt mask register 0: Not masked 1: Masked. No IRQ signal sent. System good status register (SG) is updated
TEMP_WARN	Asserted as long as the thermal warning threshold (T _{WARN}) is reached 0: Junction temperature is below T _{WARN} 1: Junction temperature is above T _{WARN}
M_VR_HOT	Temperature warning status (TEMP_WARN) interrupt mask register 0: Not masked 1: Masked. No IRQ signal sent. Temperature warning status register (TEMP_WARN) is updated



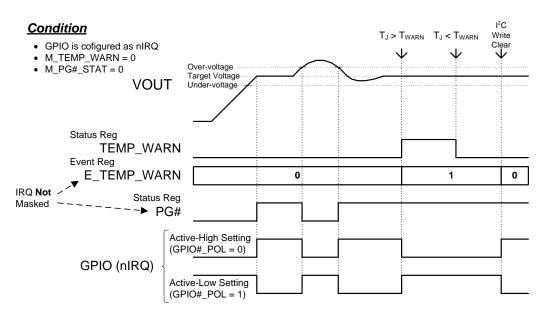


Figure 16: Interrupt Operation Example 1

Condition

- GPIO is configured as nIRQ
- M_VR_HOT = 0
- M_PG1_STAT = 0

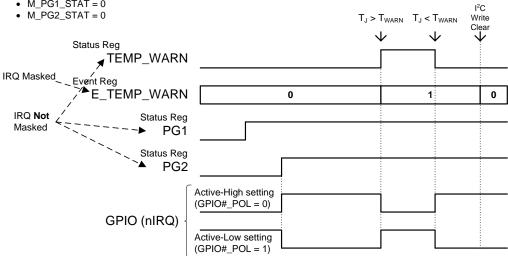


Figure 17: Interrupt Operation Example 2



GPIO(nIRQ)

Condition I^2C • GPIO is configured as nIRQ Write • M SG = 0 System Good __**→** SG Event Reg IRQ Masked _▼ E_SG 0 1 0 IRQ Not Masked Active-High setting (GPIO#_POL = 0)

Figure 18: Interrupt Operation Example 3

Active-Low setting $(GPIO\#_POL = 1)$

Condition

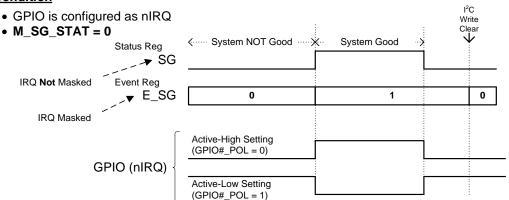


Figure 19: Interrupt Operation Example 4



4.2.3 **GPIO**

4.2.3.1 **GPIO Pin Assignment**

The DA9220 provides up to five GPIO pins, three if the I^2C is enabled, see Table 16. These registers are OTP programmable. When CONF_EN = 1 GPIO0 can be used for chip configuration.

Any register settings for GPIO3 and GPIO4 are ignored and GPIO3 and GPIO4 function as SCL and SDA respectively if I2C_EN = 1.

Table 16: GPIO Pin Assignment

ОТР	Option		GPIO Pin			Available	
I2C_EN	CONF_EN	CONF/ GPIO0	GPIO1	GPIO2	SCL/ GPIO3	SDA/ GPIO4	GPIOs
110	1'b0	GPIO0	GPIO1	GPIO2	GPIO3	GPIO4	5
1'b0	1'b1	CONF	GPIO1	GPIO2	GPIO3	GPIO4	4
1'b1	1'b0	GPIO0	GPIO1	GPIO2	SCL	SDA	3
1'b1	1'b1	CONF	GPIO1	GPIO2	SCL	SDA	2

4.2.3.2 GPIO Function

The GPIOs pins are configurable as the following functions in register GPIO<x>_MODE (x = 0 to 4):

- Buck1 enable input (EN1)
- Buck2 enable input (EN2)
- Buck1 and Buck2 enable input (EN1 & EN2)
- Buck1 DVC control input (DVC1)
- Buck2 DVC control input (DVC2)
- Buck1 and Buck2 DVC control input (DVC1 & DVC2)
- Buck1 and Buck2 OTP setting reload input (RELOAD)
- Buck1 power good output (PG1)
- Buck2 power good output (PG2)
- Buck1 power good and Buck2 power good output (PG1 & PG2)
- System good output (SG)
- Interrupt output (nIRQ)

Table 17: GPIO Function Configuration

GPIO <x>_MODE[3:0]</x>	Function	IO Condition
4'h0	GPIO disable	HiZ
4'h1	EN1	In
4'h2	EN2	In
4'h3	EN1 & EN2	In
4'h4	DVC1	In
4'h5	DVC2	In
4'h6	DVC1 & DVC2	In
4'h7	RELOAD	In
4'h8	PG1	Out



GPIO <x>_MODE[3:0]</x>	Function	IO Condition
4'h9	PG2	Out
4'hA	PG1 & PG2	Out
4'hB	SG	Out
4'hC	nIRQ	Out
4'hD	Reserved	HiZ
4'hE	Low level	Out
4'hF	High level	Out

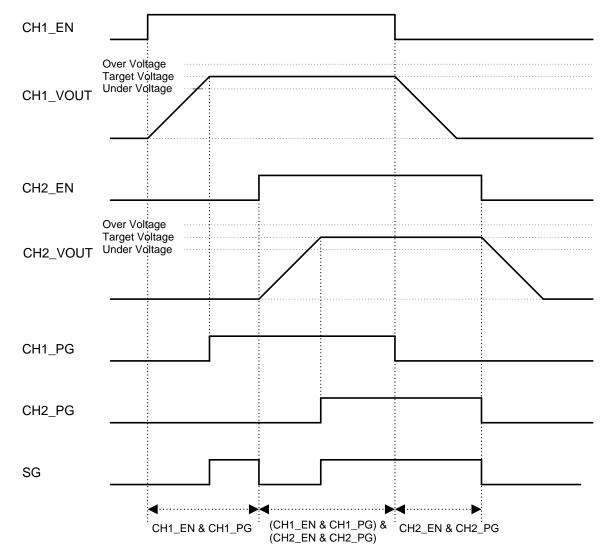


Figure 20: Power Good (PG) and System Good (SG)



4.2.3.3 Chip Configuration Select (CONF)

GPIO0 functions as chip configuration select (CONF) input when CONF_EN = 1.

Three different chip configurations can be selected according to the CONF pin level, whether it is HIGH, LOW, or Hi-Z.

Table 18: GPIO0-Configurable Registers when CONF_EN = 1

Register Name	Description
IF_SLAVE_ADDR[6:0]	I2C slave address
CH1_A_MODE[1:0]	CH1_A Operation mode select
CH1_B_MODE[1:0]	CH1_B Operation mode select
CH1_VSEL	CH1 output voltage and operation selection
CH1_EN	CH1 enable
CH1_A_VOUT[7:0]	CH1 output voltage setting A
CH1_B_VOUT[7:0]	CH1 output voltage setting B
CH2_A_MODE[1:0]	CH2_A Operation mode select
CH2_B_MODE[1:0]	CH2_B Operation mode select
CH2_VSEL	CH2 output voltage and operation selection
CH2_EN	CH2 enable
CH2_A_VOUT[7:0]	CH2 output voltage setting A
CH2_B_VOUT[7:0]	CH2 output voltage setting B
M_PG1_STAT	IRQ mask setting for CH1 power good status
M_PG2_STAT	IRQ mask setting for CH2 power good status
M_SG_STAT	IRQ mask setting for system good status
M_VR_HOT	IRQ mask setting for temp warning status
CH1_EN_DLY[3:0]	Delay setting for CH1 enable
CH1_DIS_DLY[3:0]	Delay setting for CH1 disable
CH2_EN_DLY[3:0]	Delay setting for CH2 enable
CH2_DIS_DLY[3:0]	Delay setting for CH2 disable
GPIO1_MODE[3:0]	GPIO1 mode setting
GPIO2_MODE[3:0]	GPIO2 mode setting
GPIO1_OBUF	GPIO1 output buffer select
GPIO2_OBUF	GPIO2 output buffer select
GPIO1_TRIG[1:0]	GPIO1 input trigger select
GPIO1_POL	GPIO1 polarity select
GPIO1_PUPD	GPIO1 pull-up/pull-down enable
GPIO1_DEB[1:0]	GPIO1 input debounce time setting
GPIO1_DEB_RISE	GPIO1 input debounce rising edge enable
GPIO1_DEB_FALL	GPIO1 input debounce falling edge enable
GPIO2_TRIG[1:0]	GPIO2 input trigger select
GPIO2_POL	GPIO2 polarity select



Register Name	Description
GPIO2_PUPD	GPIO2 pull-up/pull-down enable
GPIO2_DEB[1:0]	GPIO2 input debounce time setting
GPIO2_DEB_RISE	GPIO2 input debounce rising edge enable
GPIO2_DEB_FALL	GPIO2 input debounce falling edge enable

4.2.3.4 OTP Reload (RELOAD)

Buck settings listed in **Error! Reference source not found.** are reloaded from CONF registers by triggering GPIO configured as RELOAD input.

The OTP reload happens at the same time for Buck1 and Buck2 settings. During reloading, Buck1/2 keep operating as configured without shut-down.

Table 19: OTP Reload Registers

Register Name	Description
CH#_VSEL	CH# output voltage and operation selection.
	0: A, 1: B
CH#_A_VOUT[7:0]	CH# output voltage setting A : CH#_A_VOUT * 10 mV
	Setting under 0.3V is clamped to 0.3V, and setting over 1.9V is clamped to 1.9 V
CH#_B_VOUT[7:0]	CH# output voltage setting B : CH#_A_VOUT * 10 mV
	Setting under 0.3 V is clamped to 0.3 V, and setting over 1.9V is clamped to 1.9 V
CH#_A_MODE[1:0]	Operation mode selection
	0: Force PFM
	1: Force PWM. full phase
	2: Force PWM with phase shedding
	3: Auto mode
CH#_B_MODE[1:0]	Operation mode selection
	0: Force PFM
	1: Force PWM. full phase
	2: Force PWM with phase shedding
	3: Auto mode

4.3 Operating Modes

4.3.1 ON

DA9220 is ON when the IC_EN port is higher than V_{IH_EN} and the supply voltage is higher than V_{THR_POR} . Once enabled, the host processor can start communicating with DA9220 using the control interface, after the t_{IC_EN} delay.

4.3.2 OFF

DA9220 is OFF when the IC_EN port is lower than $V_{\text{IL}_{EN}}$. In OFF, the bucks are always disabled and LX nodes are pulled down by (typically 150 Ω) internal pull-down resistors.

4.4 I²C Communication

All features of DA9220 can be controlled with the I²C interface which is enabled or disabled in register I2C_EN.



I2C_EN	Description
0	I ² C disable: SCL/GPIO3 and SDA/GPIO4 pins can be used as GPIO
1	I ² C enable: SCL/GPIO3 and SDA/GPIO4 pins are used as I ² C clock input and I ² C data input/output.

GPIO3 functions as the I^2C clock and GPIO4 carries all the power manager bidirectional I^2C data. The I^2C interface is open-drain supporting multiple devices on a single line. The bus lines have to be pulled high by external pull-up resistors (2 k Ω to 20 k Ω). The standard frequency of the I^2C bus is 1 MHz in fast-mode plus (FM+), 400 kHz in fast-mode, or 100 kHz in standard mode.

4.4.1 I²C Protocol

All data is transmitted across the I²C bus in eight-bit groups. To send a bit, the SDA line is driven towards the intended state while the SCL is low (a low SDA indicates a zero bit). Once the SDA has settled, the SCL line is brought high and then low. This pulse on SCL clocks the SDA bit into the receiver's shift register.

A two-byte serial protocol is used containing one byte for address and one byte data. Data and address transfer are transmitted MSB first for both read and write operations. All transmissions begin with the START condition from the master while the bus is in idle state (the bus is free). It is initiated by a high to low transition on the SDA line while the SCL is in the high state (a STOP condition is indicated by a low to high transition on the SDA line while the SCL is in the high state).



Figure 21: I²C START and STOP Condition Timing

The I²C bus is monitored for a valid slave address whenever the interface is enabled. It responds immediately when it receives its own slave address. The acknowledge is done by pulling the SDA line low during the following clock cycle (white blocks marked with A in Figure 22 and Figure 23).

The protocol for a register write from master to slave consists of a START condition, a slave address with read/write bit, and the eight-bit register address followed by eight bits of data, terminated by a STOP condition. DA9220 responds to all bytes with acknowledge (A), see Figure 22.

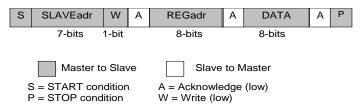


Figure 22: I²C Byte Write (SDA Line)

When the host reads data from a register it first has to write to DA9220 with the target register address and then read from DA9220 with a repeated START, or alternatively a second START, condition. After receiving the data, the host sends no acknowledge (A*) and terminates the transmission with a STOP condition, see Figure 23.



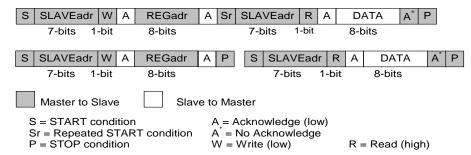


Figure 23: I²C Byte Read (SDA Line) Examples



5 Register Definitions

5.1 Register Map

Table 20: Register Map

Addr	Register	7	6	5	4	3	2	1	0
System	Module								
System									
0x0001	SYS_STATUS_0	Reserved	Reserved	Reserved	Reserved	Reserved	SG	TEMP_CRIT	TEMP_W ARN
0x0002	SYS_STATUS_1	PG2	OV2	UV2	OC2	PG1	OV1	UV1	OC1
0x0003	SYS_STATUS_2	Reserved	Reserved	Reserved	Reserved	Reserved	GPIO2	GPIO1	GPIO0
0x0004	SYS_EVENT_0	Reserved	Reserved	Reserved	Reserved	Reserved	E_SG	E_TEMP_C RIT	E_TEMP_ WARN
0x0005	SYS_EVENT_1	E_PG2	E_OV2	E_UV2	E_OC2	E_PG1	E_OV1	E_UV1	E_OC1
0x0006	SYS_EVENT_2	Reserved	Reserved	Reserved	Reserved	Reserved	E_GPIO2	E_GPIO1	E_GPIO0
0x0007	SYS_MASK_0	Reserved	Reserved	Reserved	Reserved	Reserved	M_SG	M_TEMP_C RIT	M_TEMP_ WARN
0x0008	SYS_MASK_1	M_PG2	M_OV2	M_UV2	M_OC2	M_PG1	M_OV1	M_UV1	M_OC1
0x0009	SYS_MASK_2	Reserved	Reserved	Reserved	Reserved	Reserved	M_GPIO2	M_GPIO1	M_GPIO0
0x000A	SYS_MASK_3	Reserved	Reserved	Reserved	Reserved	M_VR_HO T	M_SG_STA T	M_PG2_ST AT	M_PG1_S TAT
0x000B	SYS_CONFIG_0	CH1_DIS_D	LY<3:0>			CH1_EN_DL	Y<3:0>		
0x000C	SYS_CONFIG_1	CH2_DIS_D	LY<3:0>			CH2_EN_DL	Y<3:0>		
0x000D	SYS_CONFIG_2	Reserved	OC_LATCH(OFF<1:0>	OC_DVC_ MASK	PG_DVC_M	ASK<1:0>	Reserved	Reserved
0x000E	SYS_CONFIG_3	Reserved	OSC_TUNE	<2:0>		Reserved	Reserved	I2C_TIMEO UT	Reserved
0x0010	SYS_GPIO0_0	Reserved	Reserved	Reserved	GPIO0_MOI	DE<3:0>			GPIO0_O BUF
0x0011	SYS_GPIO0_1	GPIO0_D EB_FALL	GPIO0_D EB_RISE	GPIO0_DEB	3<1:0>	GPIO0_P UPD	GPIO0_POL	GPIO0_TRIG<	:1:0>
0x0012	SYS_GPIO1_0	Reserved	Reserved	Reserved	GPIO1_MOI	DE<3:0>			GPIO1_O BUF
0x0013	SYS_GPIO1_1	GPIO1_D EB_FALL	GPIO1_D EB_RISE	GPIO1_DEB	S<1:0>	GPIO1_P UPD	GPIO1_POL	GPIO1_TRIG<	:1:0>
0x0014	SYS_GPIO2_0	Reserved	Reserved	Reserved	GPIO2_MOI	DE<3:0>			GPIO2_O BUF
0x0015	SYS_GPIO2_1	GPIO2_D EB_FALL	GPIO2_D EB_RISE	GPIO2_DEB	J<1:0>	GPIO2_P UPD	GPIO2_POL	GPIO2_TRIG<	:1:0>



Addr	Register	7	6	5	4	3	2	1	0
Buck Co	ntrol		•	•					•
Buck1									
0x0020	BUCK_BUCK1_0	Reserved	CH1_SR_D\	/C_DWN<2:0>		CH1_SR_DV	'C_UP<2:0>		CH1_EN
0x0021	BUCK_BUCK1_1	Reserved	CH1_SR_SF	IDN<2:0>		CH1_SR_STARTUP<2:0>		CH1_PD_ DIS	
0x0022	BUCK_BUCK1_2	Reserved	Reserved	Reserved	Reserved	CH1_ILIM<3:	:0>		
0x0023	BUCK_BUCK1_3	CH1_VMAX	<7:0>						
0x0024	BUCK_BUCK1_4	Reserved	Reserved	Reserved	CH1_VSE L	CH1_B_MOD	DE<1:0>	CH1_A_MOD	E<1:0>
0x0025	BUCK_BUCK1_5	CH1_A_VOL	JT<7:0>						
0x0026	BUCK_BUCK1_6	CH1_B_VOL	JT<7:0>						
0x0027	BUCK_BUCK1_7	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	CH1_RIPPLE.	_CANCEL_<1
Buck2	•								
0x0028	BUCK_BUCK2_0	Reserved	CH2_SR_DV	/C_DWN<2:0>		CH2_SR_DV	'C_UP<2:0>		CH2_EN
0x0029	BUCK_BUCK2_1	Reserved	CH2_SR_SH	IDN<2:0>		CH2_SR_ST	ARTUP<2:0>		CH2_PD_ DIS
0x002A	BUCK_BUCK2_2	Reserved	Reserved	Reserved	Reserved	CH2_ILIM<3:	:0>		
0x002B	BUCK_BUCK2_3	CH2_VMAX	<7:0>						
0x002C	BUCK_BUCK2_4	Reserved	Reserved	Reserved	CH2_VSE L	CH2_B_MOD	DE<1:0>	CH2_A_MOD	E<1:0>
0x002D	BUCK_BUCK2_5	CH2_A_VOL	JT<7:0>						
0x002E	BUCK_BUCK2_6	CH2_B_VOL	JT<7:0>						
0x002F	BUCK_BUCK2_7	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	CH2_RIPPL 1:0>	E_CANCEL<
Serializa	tion								
0x0048	OTP_DEVICE_ID	DEV_ID<7:0	>						
0x0049	OTP_VARIANT_ID	MRC<3:0> VRC<3:0>							
0x004A	OTP_CUSTOMER_ID	CUST_ID<7:	CUST_ID<7:0>						
0x004B	OTP_CONFIG_ID	CONFIG_RE	CONFIG_REV<7:0>						



5.1.1 System

Table 21: SYS_STATUS_0 (0x0001)

Bit	Symbol	Description
[2]	SG	Asserted as long as the enabled buck output voltage is in range
[1]	TEMP_CRIT	Asserted as long as the thermal shutdown threshold is reached
[0]	TEMP_WARN	Asserted as long as the thermal warning threshold is reached

Table 22: SYS_STATUS_1 (0x0002)

Bit	Symbol	Description
[7]	PG2	Asserted as long as the Buck2 output voltage is in range
[6]	OV2	Asserted as long as Buck2 hitting over-voltage
[5]	UV2	Asserted as long as Buck2 hitting under-voltage
[4]	OC2	Asserted as long as Buck2 hitting over-current
[3]	PG1	Asserted as long as the Buck1 output voltage is in range
[2]	OV1	Asserted as long as Buck1 hitting over-voltage
[1]	UV1	Asserted as long as Buck1 hitting under-voltage
[0]	OC1	Asserted as long as Buck1 hitting over-current

Table 23: SYS_STATUS_2 (0x0003)

Bit	Symbol	Description
[2]	GPIO2	GPIO2 status
[1]	GPIO1	GPIO1 status
[0]	GPIO0	GPIO0 status

Table 24: SYS_EVENT_0 (0x0004)

Bit	Symbol	Description
[2]	E_SG	SG caused event. Writing 1 action clear this bit into 0 if event source has been released.
[1]	E_TEMP_CRIT	TEMP_CRIT caused event. Writing 1 action clear this bit into 0 if event source has been released.
[0]	E_TEMP_WARN	TEMP_WARN caused event. Writing 1 action clear this bit into 0 if event source has been released.



Table 25: SYS_EVENT_1 (0x0005)

Bit	Symbol	Description
[7]	E_PG2	PG2 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[6]	E_OV2	OV2 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[5]	E_UV2	UV2 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[4]	E_OC2	OC2 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[3]	E_PG1	PG1 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[2]	E_OV1	OV1 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[1]	E_UV1	UV1 caused event. Writing 1 action clear this bit into 0 if event source has been released.
[0]	E_OC1	OC1 caused event. Writing 1 action clear this bit into 0 if event source has been released.

Table 26: SYS_EVENT_2 (0x0006)

Bit	Symbol	Description
[2]	E_GPIO2	GPIO2 event. Writing 1 action clear this bit into 0 if event source has been released.
[1]	E_GPIO1	GPIO1 event. Writing 1 action clear this bit into 0 if event source has been released.
[0]	E_GPIO0	GPIO0 event. Writing 1 action clear this bit into 0 if event source has been released.

Table 27: SYS_MASK_0 (0x0007)

Bit	Symbol	Description	
[2]	M_SG	SG IRQ mask	
[1]	M_TEMP_CRIT	TEMP_CRIT IRQ mask	
[0]	M_TEMP_WARN	TEMP_WARN IRQ mask	

Table 28: SYS_MASK_1 (0x0008)

Bit	Symbol	Description	
[7]	M_PG2	PG2 event IRQ mask	
[6]	M_OV2	OV2 event IRQ mask	
[5]	M_UV2	UV2 event IRQ mask	
[4]	M_OC2	OC2 event IRQ mask	
[3]	M_PG1	PG1 event IRQ mask	
[2]	M_OV1	OV1 event IRQ mask	
[1]	M_UV1	UV1 event IRQ mask	
[0]	M_OC1	OC1 event IRQ mask	



Table 29: SYS_MASK_2 (0x0009)

Bit	Symbol	Description	
[2]	M_GPIO2	GPIO2 IRQ mask	
[1]	M_GPIO1	GPIO1 IRQ mask	
[0]	M_GPIO0	GPIO0 IRQ mask	

Table 30: SYS_MASK_3 (0x000A)

Bit	Symbol	Description	
[3]	M_VR_HOT	Temp warning status IRQ mask. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
[2]	M_SG_STAT	SG status IRQ mask. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
[1]	M_PG2_STAT	PG2 status IRQ mask Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
[0]	M_PG1_STAT	PG1 status IRQ mask. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	

Table 31: SYS_CONFIG_0 (0x000B)

Bit	Symbol	Description		
[7:4]	CH1_DIS_DLY	Delay for CH1 disable. Active with GPIO configured as EN1&EN2 control and IC_EN control. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		
		Value	Description	
		0x0	0	
		0x1	1.0 ms	
		0x2	2.0 ms	
		0x3	3.0 ms	
		0x4	4.0 ms	
		0x5	5.0 ms	
		0x6	6.0 ms	
		0x7	7.0 ms	
		0x8	8.0 ms	
		0x9	9.0 ms	
		0xA	10.0 ms	
		0xB	11.0 ms	
		0xC	12.0 ms	
		0xD	13.0 ms	
		0xE	14.0 ms	
		0xF	15.0 ms	
[3:0]	CH1_EN_DLY	Delay for CH1 enable. Active with GPIO configured as EN1&EN2 control and IC_EN control. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		



Bit	Symbol	Description		
		Value	Description	
		0x0	0	
		0x1	0.5 ms	
		0x2	1.0 ms	
		0x3	1.5 ms	
		0x4	2.0 ms	
		0x5	2.5 ms	
		0x6	3.0 ms	
		0x7	3.5 ms	
		0x8	4.0 ms	
		0x9	4.5 ms	
		0xA	5.0 ms	
		0xB	5.5 ms	
		0xC	6.0 ms	
		0xD	6.5 ms	
		0xE	7.0 ms	
		0xF	7.5 ms	

Table 32: SYS_CONFIG_1 (0x000C)

Bit	Symbol	Description			
[7:4]	CH2_DIS_DLY	Delay for CH2 disable. Active with GPIO configured as EN1&EN2 control and IC_EN control. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1			
		Value Description			
		0x0	0		
		0x1	1.0 ms		
		0x2	2.0 ms		
		0x3 3.0 ms			
		0x4 4.0 ms			
		0x5	5.0 ms		
		0x6	6.0 ms		
		0x7	7.0 ms		
		0x8	8.0 ms		
		0x9	9.0 ms		
		0xA	10.0 ms		
		0xB	11.0 ms		
		0xC	12.0 ms		
		0xD	13.0 ms		



Bit	Symbol	Description			
		0xE	14.0 ms		
		0xF	15.0 ms		
[3:0]	CH2_EN_DLY	Delay for CH2 enable. Active with GPIO configured as EN1&EN2 control and IC_EN control. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1			
		Value	Description		
		0x0	0		
		0x1	0.5 ms		
		0x2	1.0 ms		
		0x3	1.5 ms		
		0x4	2.0 ms		
		0x5	2.5 ms		
		0x6	3.0 ms		
		0x7	3.5 ms		
		0x8	4.0 ms		
		0x9	4.5 ms		
		0xA	5.0 ms		
		0xB	5.5 ms		
		0xC	6.0 ms		
		0xD	6.5 ms		
		0xE	7.0 ms		
		0xF	7.5 ms		



Table 33: SYS_CONFIG_2 (0x000D)

Bit	Symbol	Description			
[6:5]	OC_LATCHOFF	Over-current latch-off setting. BUCK shut-down after OCP for 8 µs/1 ms/3 ms unless disable setting. IRQ is generated unless IRQ is masked.			
		Value Description			
		0x0	Latch off disable		
		0x1	Latch off after 8 µs of OCP signal		
		0x2	Latch off after 1 ms of OCP signal		
		0x3	Latch off after 3 ms of OCP signal		
[4]	OC_DVC_MASK	Over-current event (IRQ and latch-off feature) mask during DVC ramp-up and ramp-down for both CH1 and CH2			
[3:2]	PG_DVC_MASK	Power-good	I mask during DVC for both CH1 and CH 2		
		Value Description			
		0x0	No mask		
		0x1	Mask as not power good during DVC		
		0x2	Mask as power good during DVC		
		0x3	Reserved		

Table 34: SYS_CONFIG_3 (0x000E)

Bit	Symbol	Description	1	
[6:4]	OSC_TUNE	Tune oscillator frequency, tuned frequency = Current + OSC_TUNE * 160 kHz		
		Value	Description	
		0x3	3	
		0x2	2	
		0x1	1	
		0x0	0	
		0x7	-1	
		0x6	-2	
		0x5	-3	
		0x4	-4	
[1]	I2C_TIMEOUT	Enable automatic reset of 2-wire interface (if SDA stays low for >50 ms).		



Table 35: SYS_GPIO0_0 (0x0010)

Bit	Symbol	Description	on
[4:1]	GPIO0_MODE	GPIO func	tion mode select
		Value	Description
		0x0	GPIO disable
		0x1	EN1 input
		0x2	EN2 input
		0x3	EN1 & EN2 input
		0x4	DVC1 input
		0x5	DVC2 input
		0x6	DVC1 & DVC2 input
		0x7	RELOAD input
		0x8	PG1 output
		0x9	PG2 output
		0xA	PG1 & PG2 output
		0xB	SG output
		0xC	nIRQ output
		0xD	Reserved
		0xE	Low output
		0xF	High output
[0]	GPIO0_OBUF	GPIO outp	ut buffer select
		Value	Description
		0x0	open-drain output
		0x1	push-pull output



Table 36: SYS_GPIO0_1 (0x0011)

Bit	Symbol	Description	on
[7]	GPIO0_DEB_FALL	GPI debou	ice falling edge
[6]	GPIO0_DEB_RISE	GPI debounce rising edge	
[5:4]	GPIO0_DEB	GPI debounce time	
		Value	Description
		0x0	100 μs debouce
		0x1	1 ms debouce
		0x2	10 ms debounce
		0x3	100 ms debounce
[3]	GPIO0_PUPD	GPIO pull-	up/pull-down enable
		Value	Description
		0x0	GPI: pull-down disabled, GPO: pull-up to AVDD disabled
		0x1	GPI: pull-down enabled, GPO: pull-up to AVDD enabled
[2]	GPIO0_POL	GPIO polarity	
		Value	Description
		0x0	GPIO is active-high
		0x1	GPIO is active-low
[1:0]	GPIO0_TRIG	GPI trigger	r type
		Value	Description
		0x0	Dual-edge triggered
		0x1	Pos-edge triggered
		0x2	Neg-edge triggered
		0x3	Reserved (No trigger)

Table 37: SYS_GPIO1_0 (0x0012)

Bit	Symbol	Description	
[4:1]	GPIO1_MODE	GPIO function mode select. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
		Value	Description
		0x0	GPIO disable
		0x1	EN1 input
		0x2	EN2 input
		0x3	EN1 & EN2 input
		0x4	DVC1 input
		0x5	DVC2 input
		0x6	DVC1 & DVC2 input



Bit	Symbol	Description	on
		0x7	RELOAD input
		0x8	PG1 output
		0x9	PG2 output
		0xA	PG1 & PG2 output
		0xB	SG output
		0xC	nIRQ output
		0xD	Reserved
		0xE	Low output
		0xF	High output
[0]	GPIO1_OBUF		ut buffer select. Initial value is determined by setting at the start-up in CONF_EN = 1
		Value	Description
		0x0	open-drain output
		0x1	push-pull output



Table 38: SYS_GPIO1_1 (0x0013)

Bit	Symbol	Description	on	
[7]	GPIO1_DEB_FALL		ice falling edge. Initial value is determined by setting at the start-up in CONF_EN = 1	
[6]	GPIO1_DEB_RISE	GPI debounce rising edge. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		
[5:4]	GPIO1_DEB	GPI debounce time. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		
		Value	Description	
		0x0	100 μs debouce	
		0x1	1 ms debouce	
		0x2	10 ms debounce	
		0x3	100 ms debounce	
[3]	GPIO1_PUPD	GPIO pull-up/pull-down enable. Initial value is determine by CONF pin setting at the start-up in CONF_EN = 1		
		Value	Description	
		0x0	GPI: pull-down disabled, GPO: pull-up to AVDD disabled	
		0x1	GPI: pull-down enabled, GPO: pull-up to AVDD enabled	
[2]	GPIO1_POL		rity. Initial value is determined by CONF pin he start-up in CONF_EN = 1	
		Value	Description	
		0x0	GPIO is active-high	
		0x1	GPIO is active-low	
[1:0]	GPIO1_TRIG		r type. Initial value is determined by CONF pin he start-up in CONF_EN = 1	
		Value	Description	
		0x0	Dual-edge triggered	
		0x1	Pos-edge triggered	
		0x2	Neg-edge triggered	
		0x3	Reserved (No trigger)	

Table 39: SYS_GPIO2_0 (0x0014)

Bit	Symbol	Description	
[4:1]	GPIO2_MODE	GPIO function mode select. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
		Value Description	
		0x0 GPIO disable	
		0x1 EN1 input	
		0x2	EN2 input
		0x3	EN1 & EN2 input



Bit	Symbol	Description	on
		0x4	DVC1 input
		0x5	DVC2 input
		0x6	DVC1 & DVC2 input
		0x7	RELOAD input
		0x8	PG1 output
		0x9	PG2 output
		0xA	PG1 & PG2 output
		0xB	SG output
		0xC	nIRQ output
		0xD	Reserved
		0xE	Low output
		0xF	High output
[0]	GPIO2_OBUF		ut buffer select. Initial value is determined by setting at the start-up in CONF_EN = 1
		Value	Description
		0x0	open-drain output
		0x1	push-pull output



Table 40: SYS_GPIO2_1 (0x0015)

Bit	Symbol	Description	Description		
[7]	GPIO2_DEB_FALL		GPI debouce falling edge. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		
[6]	GPIO2_DEB_RISE	GPI debounce rising edge. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1			
[5:4]	GPIO2_DEB	GPI debounce time. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1			
		Value	Description		
		0x0	100 μs debouce		
		0x1	1 ms debouce		
		0x2	10 ms debounce		
		0x3	100 ms debounce		
[3]	GPIO2_PUPD	GPIO pull-up/pull-down enable. Initial value is determine by CONF pin setting at the start-up in CONF_EN = 1			
		Value	Description		
		0x0	GPI: pull-down disabled, GPO: pull-up to AVDD disabled		
		0x1	GPI: pull-down enabled, GPO: pull-up to AVDD enabled		
[2]	GPIO2_POL		rity. Initial value is determined by CONF pin he start-up in CONF_EN = 1		
		Value	Description		
		0x0	GPIO is active-high		
		0x1	GPIO is active-low		
[1:0]	GPIO2_TRIG		r type. Initial value is determined by CONF pin he start-up in CONF_EN = 1		
		Value	Description		
		0x0	Dual-edge triggered		
		0x1	Pos-edge triggered		
		0x2	Neg-edge triggered		
		0x3	Reserved (No trigger)		



5.1.2 Buck1

Table 41: BUCK_BUCK1_0 (0x0020)

Bit	Symbol	Description	Description	
[6:4]	CH1_SR_DVC_DWN	Voltage sle	ew-rate for DVC ramp-down	
		Value	Description	
		0x0	10 mV/8 μs	
		0x1	10 mV/4 μs	
		0x2	10 mV/2 μs	
		0x3	10 mV/µs	
		0x4	20 mV/ µs	
		0x5	Reserved	
		0x6	Reserved	
		0x7	Reserved	
[3:1]	CH1_SR_DVC_UP	Voltage slew-rate for DVC ramp-up		
		Value	Description	
		0x0	10 mV/8 μs	
		0x1	10 mV/4 μs	
		0x2	10 mV/2 μs	
		0x3	10 mV/µs	
		0x4	20 mV/µs	
		0x5	40 mV/μs	
		0x6	Reserved	
		0x7	Reserved	
[0]	CH1_EN	Channel enable. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1		



Table 42: BUCK_BUCK1_1 (0x0021)

Bit	Symbol	Description	on
[6:4]	CH1_SR_SHDN	Voltage sle	ew-rate during shut-down
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/µs
		0x4	20 mV/µs
		0x5	Reserved
		0x6	Reserved
		0x7	Immediate power-down
[3:1]	CH1_SR_STARTUP	Voltage sle	ew-rate during startup
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/μs
		0x4	20 mV/µs
		0x5	40 mV/μs
		0x6	Reserved
		0x7	Reserved
[0]	CH1_PD_DIS	Pull-down	while buck is disabled. 0: enable, 1: disable

Table 43: BUCK_BUCK1_2 (0x0022)

Bit	Symbol	Description		
[3:0]	CH1_ILIM	Select OCP threshold (A)		
		Value	Description	
		0x0	Reserved	
		0x1	3.5	
		0x2	4.0	
		0x3	4.5	
		0x4	5.0	
		0x5	5.5	
		0x6	6.0	
		0x7	6.5	
		0x8	7.0	
		0x9	7.5	



Bit	Symbol	Description	
		0xA	8.0
		0xB	8.5
		0xC	9.0
		0xD	9.5
		0xE	10.0
		0xF	Disable

Table 44: BUCK_BUCK1_3 (0x0023)

Bit	Symbol	Description	
[7:0]	CH1_VMAX	VOUT max setting (V): From 0.30 V (0x1E) to 1.90 V (0xBE) in 10 mV steps. This is a read-only register.	
		Value Description	
		0x1E	0.3
		0x1F	0.31
		0x20	0.32
		Continuing through	
		0x99	1.53
		То	
		0xBD	1.89
		0xBE	1.9

Table 45: BUCK_BUCK1_4 (0x0024)

Bit	Symbol	Description	on
[4]	CH1_VSEL	Output voltage and operation selection: 0: A, 1: B. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
[3:2]	CH1_B_MODE	Operation mode selection. Initial value is determined by CONF pin setting at the start up in CONF_EN = 1	
		Value	Description
		0x0	Force PFM operation
		0x1	Force PWM operation
		0x2	Force PWM operation
		0x3	Auto mode
[1:0]	CH1_A_MODE	Operation mode selection. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
		Value	Description
		0x0	Force PFM operation
		0x1	Force PWM operation



Bit	Symbol	Description	
		0x2	Force PWM operation
		0x3	Auto mode

Table 46: BUCK_BUCK1_5 (0x0025)

Bit	Symbol	Description	on
[7:0]	CH1_A_VOUT	Output voltage setting A: Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1 From 0.30 V (0x1E) to 1.90 V (0xBE) in steps of 10 mV (default 1.0 V) Write-protected when value is written below 0.30 V or above 1.90 V	
		Value	Description
		0x1E	0.3
		0x1F	0.31
		0x20	0.32
		Continuing through	
		0x64	1
		То	
		0xBC	1.88
		0xBD	1.89
		0xBE	1.9

Table 47: BUCK_BUCK1_6 (0x0026)

Bit	Symbol	Description	Description		
[7:0]	CH1_B_VOUT	Output voltage setting B: Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1 From 0.30 V (0x1E) to 1.90 V (0xBE) in steps of 10 mV (default 1.0 V) Write-protected when value is written below 0.30 V or above 1.90 V			
		Value Description			
		0x1E	0.3		
		0x1F	0.31		
		0x20	0.32		
		Continuing through			
		0x64	1		
		То			
		0xBC	1.88		
		0xBD	1.89		
		0xBE	1.9		



Table 48: BUCK_BUCK1_7 (0x0027)

Bit	Symbol	Description	
[3]	Reserved	Reserved	
[2]	Reserved	Reserved	
[1:0]	CH1_RIPPLE_CANCEL	Ripple cancel control (can be used to improve output overshoot at heavy to light load transient).	
		Value	Description
		0x0	No ripple cancel
		0x1	Small ripple cancel
		0x2	Mid ripple cancel
		0x3	Large ripple cancel



5.1.3 Buck2

Table 49: BUCK_BUCK2_0 (0x0028)

Bit	Symbol	Description	on
[6:4]	CH2_SR_DVC_DWN	Voltage sle	ew-rate for DVC ramp-down
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/µs
		0x4	20 mV/μs
		0x5	Reserved
		0x6	Reserved
		0x7	Reserved
[3:1]	CH2_SR_DVC_UP	Voltage slew-rate for DVC ramp-up	
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/μs
		0x4	20 mV/µs
		0x5	40 mV/μs
		0x6	Reserved
		0x7	Reserved
[0]	CH2_EN	Channel enable. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	



Table 50: BUCK_BUCK2_1 (0x0029)

Bit	Symbol	Description	on
[6:4]	CH2_SR_SHDN	Voltage sle	ew-rate during power-down
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/μs
		0x4	20 mV/μs
		0x5	Reserved
		0x6	Reserved
		0x7	Immediate power-down
[3:1]	CH2_SR_STARTUP	Voltage slew-rate during startup	
		Value	Description
		0x0	10 mV/8 μs
		0x1	10 mV/4 μs
		0x2	10 mV/2 μs
		0x3	10 mV/µs
		0x4	20 mV/μs
		0x5	40 mV/μs
		0x6	Reserved
		0x7	Reserved
[0]	CH2_PD_DIS	Pull-down	while BUCK is disabled. 0: enable, 1: disable

Table 51: BUCK_BUCK2_2 (0x002A)

Bit	Symbol	Description	on
[3:0]	CH2_ILIM	Select OCP threshold	
		Value	Description
		0x0	Reserved
		0x1	3.5
		0x2	4.0
		0x3	4.5
		0x4	5.0
		0x5	5.5
		0x6	6.0
		0x7	6.5
		0x8	7.0
		0x9	7.5



Bit	Symbol	Description	
		0xA	8.0
		0xB	8.5
		0xC	9.0
		0xD	9.5
		0xE	10.0
		0xF	Disable

Table 52: BUCK_BUCK2_3 (0x002B)

Bit	Symbol	Description	on .
[7:0]	CH2_VMAX	VOUT max setting (V): From 0.30 V (0x1E) to 1.90 V (0xBE) in steps of 10 mV This is a read-only register.	
		Value	Description
		0x1E	0.3
		0x1F	0.31
		0x20	0.32
		Continuing	through
		0x64	1
		То	
		0xBC	1.88
		0xBD	1.89
		0xBE	1.9

Table 53: BUCK_BUCK2_4 (0x002C)

Bit	Symbol	Description	on
[4]	CH2_VSEL	Output voltage and operation selection: 0: A, 1: B. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
[3:2]	CH2_B_MODE	•	mode selection. Initial value is determined by setting at the start-up in CONF_EN = 1
		Value	Description
		0x0	Force PFM operation
		0x1	Force PWM operation
		0x2	Force PWM operation
		0x3	Auto mode
[1:0]	CH2_A_MODE	Operation mode selection. Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1	
		Value	Description
		0x0	Force PFM operation
		0x1	Force PWM operation



Bit	Symbol	Description	
		0x2	Force PWM operation
		0x3	Auto mode

Table 54: BUCK_BUCK2_5 (0x002D)

Bit	Symbol	Description	on
[7:0]	CH2_A_VOUT	Output voltage setting A: Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1 From 0.30 V (0x1E) to 1.90 V (0xBE) in steps of 10 mV (default 1.0 V) Write-protected when value is written below 0.30 V or above 1.90 V	
		Value	Description
		0x1E	0.3
		0x1F	0.31
		0x20	0.32
		Continuing	through
		0x64	1
		То	
		0xBC	1.88
		0xBD	1.89
		0xBE	1.9

Table 55: BUCK_BUCK2_6 (0x002E)

Bit	Symbol	Description	n
[7:0]	CH2_B_VOUT	Output voltage setting B: Initial value is determined by CONF pin setting at the start-up in CONF_EN = 1 From 0.30 V (0x1E) to 1.90 V (0xBE) in steps of 10 mV (default 1.0 V) Write-protected when value is written below 0.30 V or above 1.90 V	
		Value	Description
		0x1E	0.3
		0x1F	0.31
		0x20	0.32
		Continuing	through
		0x64	1
		То	
		0xBC	1.88
		0xBD	1.89
		0xBE	1.9



Table 56: BUCK_BUCK2_7 (0x002F)

Bit	Symbol	Description	
[3]	Reserved	Reserved	
[2]	Reserved	Reserved	
[1:0]	CH2_RIPPLE_CANCEL	Ripple cancel control (can be used to improve output overshoot at heavy to light load transient).	
		Value	Description
		0x0	No ripple cancel
		0x1	Small ripple cancel
		0x2	Mid ripple cancel
		0x3	Large ripple cancel



5.1.4 Serialization

Table 57: OTP_DEVICE_ID (0x0048)

Bit	Symbol	Description
[7:0]	DEV_ID	Device ID

Table 58: OTP_VARIANT_ID (0x0049)

Bit	Symbol	Description
[7:4]	MRC	Mask Revision Code
[3:0]	VRC	Chip Variant Code

Table 59: OTP_CUSTOMER_ID (0x004A)

Bit	Symbol	Description
[7:0]	CUST_ID	Customer ID

Table 60: OTP_CONFIG_ID (0x004B)

Bit	Symbol	Description
[7:0]	CONFIG_REV	OTP Variant



- 6 Package Information
- 6.1 Package Outlines



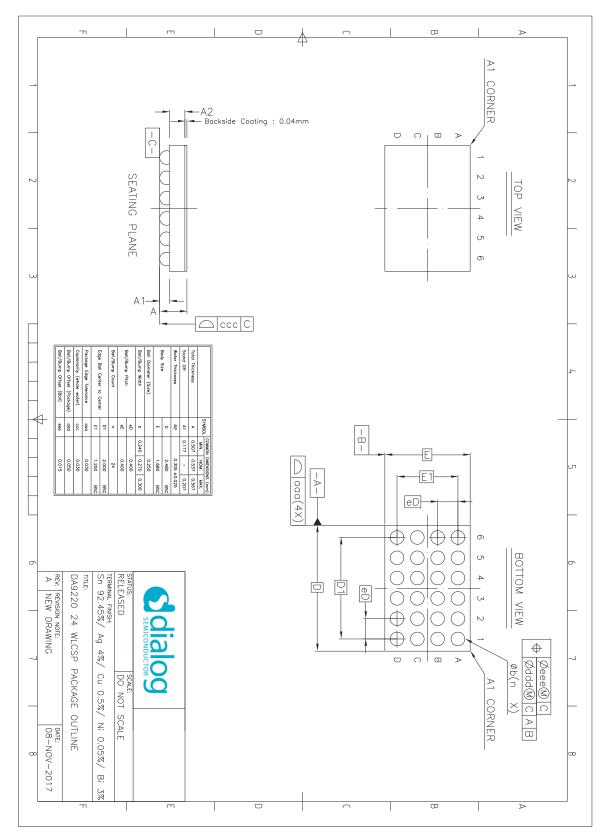


Figure 24: Package Outline Drawing



6.2 Moisture Sensitivity Level

The moisture sensitivity level (MSL) is an indicator for the maximum allowable time period (floor lifetime) in which a moisture sensitive plastic device, once removed from the dry bag, can be exposed to an environment with a specified maximum temperature and a maximum relative humidity before the solder reflow process. The MSL classification is defined in Table 61.

For detailed information on MSL levels refer to the IPC/JEDEC standard J-STD-020, which can be downloaded from http://www.jedec.org.

The DA9220 package is qualified for MSL1.

Table 61: MSL Classification

MSL Level	Floor Lifetime	Conditions
MSL 1	Unlimited	≤30 °C / 85 % RH

6.3 WLCSP Handling

Manual handling of WLCSP packages should be reduced to the absolute minimum. In cases where it is still necessary, a vacuum pick-up tool should be used. In extreme cases plastic tweezers could be used, but metal tweezers are not acceptable, since contact may easily damage the silicon chip.

Removal of a WLCSP package will cause damage to the solder balls. Therefore a removed sample cannot be reused.

WLCSP packages are sensitive to visible and infrared light. Precautions should be taken to properly shield the chip in the final product.

6.4 Soldering Information

Refer to the IPC/JEDEC standard J-STD-020 for relevant soldering information. This document can be downloaded from http://www.jedec.org.



7 Ordering Information

The ordering number consists of the part number followed by a suffix indicating the packing method. For details and availability, please consult Dialog Semiconductor's customer support portal or your local sales representative.

Table 62: Ordering Information

Part Number	Package	Size (mm)	Shipment Form	Pack Quantity
DA9220-xxV72 24 WLC3		2.5 x 1.7	T&R	4500
DA9220-xxV76	24 WLCSP	2.5 x 1.7	Waffle Tray	140
DA9220-70V72 Standard OTP Variant V _{OUT1} = 1.2 V, V _{OUT2} = 1.8 V	24 WLCSP	2.5 x 1.7	T&R	4500
DA9220-70V76 Standard OTP Variant Vout1 = 1.2 V, Vout2 = 1.8 V	24 WLCSP	2.5 x 1.7	Waffle Tray	140
DA9220-71V72 24 WLCSP Standard OTP Variant Vout1 = 1.0 V, Vout2 = 1.0 V		2.5 x 1.7	T&R	4500
DA9220-71V76 Standard OTP Variant Vout1 = 1.0 V, Vout2 = 1.0 V	24 WLCSP	2.5 x 1.7	Waffle Tray	140

8 Application Information

The following recommended components are examples selected from requirements of a typical application.

8.1 Capacitor Selection

Ceramic capacitors are used as bypass capacitors at all VDD and output rails. When selecting a capacitor, especially for types with high capacitance at smallest physical dimension, the DC bias characteristic has to be taken into account.

Table 63: Recommended Capacitor Types

Application	Value	Size	Temp. Char.	Tol. (%)	V-Rate	Туре
VOUT output bypass	10 μF	0402	X5R ±15 %	±20	6.3 V	Murata GRM155R60J106ME15
PVDDx bypass	10 μF	0603	X5R ±15 %	±20	25 V	Murata GRM188R61E106MA73
AVDD bypass	1μF	0402	X5R ±15 %	±10	10 V	Murata GRM155R61A105KE15



8.2 Inductor Selection

Inductors should be selected based on the following parameters:

Rated maximum current

Usually a coil provides two current limits: ISAT specifies the maximum current at which the inductance drops by 30 % of the nominal value, and IMAX is defined by the maximum power dissipation and is applied to the effective current.

DC resistance

Critical for the converter efficiency and should therefore be minimized.

Table 64: Recommended Inductor Types

Value (µH)	Size (mm)	I _{MAX} (DC) (A)	ISAT (A)	Tol. (%)	DC Resistance (mΩ)	Туре
0.1	2.0 x 1.6 x 1.0	6.5	9.0	±20	11.5	Cyntec HTEN20161T-R10MDR
0.1	1.6 x 0.8 x 1.0	5.2	6.5	±20	17	Taiyo Yuden MEKK1608TR10M
0.1	1.6 x 0.8 x 0.8	4.1	9.4	±20	19	Taiyo Yuden MCHK1608TR10MJN
0.11	2.0 x 1.25 x 0.8	5.8	6.9	±20	9.1	Taiyo Yuden MCHK2012TR11MKG
0.1	1.0 x 0.5 x 0.55	2.3	2.2	±20	41	Taiyo Yuden MCEE1005TR10MHN
0.1	2.5 x 2.0 x 1.2	12	13	±20	4	TDK TFM252012ALMAR10MT
0.1	1.6 x 0.8 x 0.95	3.8	4.3	±20	15	Tokyo Coil Engineering TFP160810M-R10N
0.11	2.0 x 1.6 x 0.6	3.0	6.0	±20	24	Wurth Elektronik WE-PMMI 744 799 771 11



Revision History

Revision	Date	Description		
2.2	15-Feb-2022	Modification:		
		Rebranded to Renesas		
2.1	17-Sep-2020	Modifications:		
		Section 4.2.3.4: Added new section		
		Section 8.2: Updated Table 64		
2.0	18-Jul-2019	Modifications:		
		Section 3.5: Updated R _{PD} condition		
		 Section 3.9: Added typical performance graphs 		
		Section 7: Updated Table 62: Ordering Information		
		Section 8.2: Updated Table 64: Recommended Inductor Types		
1.1	01-Mar-2019	Modifications:		
		 Section 3.5: Updated Buck tBUCK_EN parameter condition and value, RPD parameter description 		
		 Section 3.7 Updated R_{PD} and R_{PU} parameter values 		
		Section 8.2: Updated Table 64: Recommended Inductor Types		
		Removed watermark		
1.0	02-Oct-2018	Modifications:		
		Section 3.5: Updated Buck Vout_tr_Line, Vout_tr_Ld_1PH, and La		
		IQ_PFM_1PH parameter descriptions ■ Section 5.1.2: Updated BUCK_BUCK1_4 register description		
		Section 5.1.3: Updated BUCK_BUCK2_4 register description		
0.3	28-Sep-2018	Modifications:		
0.0	20 00p 2010	 Section 3.5: Updated Buck R_{ON_PMOS} and R_{ON_NMOS} parameter values 		
		 Section 0: Updated V_{THR_POR} parameter and added V_{THR_POR_HYS} parameter 		
0.2	10 Jul 2010	Modifications:		
0.2	10-Jul-2018			
		 Section 3.1: Updated V_{SYS} and V_{PIN} Max values and moved note to Section 3.3.1 		
		Section 3.2: Added V _{PIN} and updated note		
		 Section 3.3.1: Updated thermal ratings 		
		 Section 3.3.2: Updated power dissipation and added Figure 5: 24WLCSP Power Derating Curve 		
		 Section Error! Reference source not found.: Updated Buck electrical characteristics 		
		Section 0: Added I _{IN_OFF} and I _{IN_ON} parameters		
		 Section 4.1: Updated DC-DC buck converter description 		
		Section 4.1.2: Removed mention of phase shedding		
		Section 4.1.4: Renamed section to Soft Start-Up and Shutdown Section 4.2.3: Added Figure 30: Power Coad (PC) and Surface		
		 Section 4.2.3.2: Added Figure 20: Power Good (PG) and System Good (SG) 		
		Section 5.1: Updated Register map		
		 Section 5.1.2: Updated BUCK_BUCK1_2 register description and added BUCK_BUCK1_7 		
		 Section 5.1.3: Updated BUCK_BUCK2_2 register description and added BUCK_BUCK2_7 		
		 Section 5.1.4: Updated MRC bit (register OTP_VARIANT_ID) reset value 		

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Revision	Date	Description	
		Section 7: Added part numbers	
		Section 8.2: Updated Table 64: Recommended Inductor Types	
0.1	12-Apr-2018	Initial version.	



Status Definitions

Revision	Datasheet Status	Product Status	Definition
1. <n></n>	Target	Development	This datasheet contains the design specifications for product development. Specifications may be changed in any manner without notice.
2. <n></n>	Preliminary	Qualification	This datasheet contains the specifications and preliminary characterization data for products in pre-production. Specifications may be changed at any time without notice in order to improve the design.
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