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April 1st, 2010 Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (http://www.renesas.com)

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BIPOLAR ANALOG INTEGRATED CIRCUIT μ PC1295C

2 PHASE BRUSHLESS MOTOR SPEED CONTROL

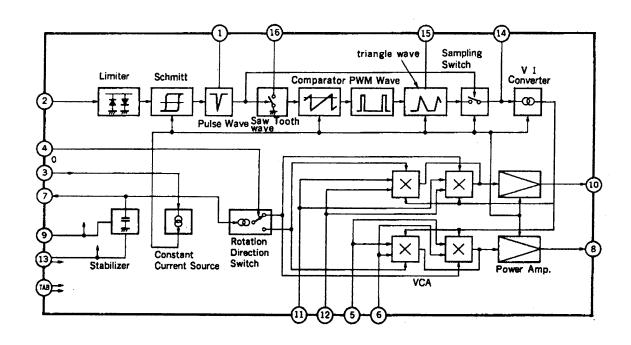
DESCRIPTION

μPC1295C is a silicon monolithic integrated circuit designed for 2 phase brushless motor speed control circuit.
μPC1295C includes limiter circuit, shumitt circuit, pulse generator, saw tooth wave generator, comparator, PWM generator, triangle wave generator, sampling switch, V–I converter, power amplifier voltage stabilizer, constant current stabilizer and rotation direction switch.

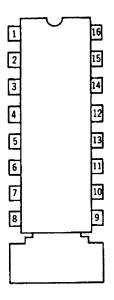
FEATURES

- High output current. $\pm 300 \text{ mA} (R_L = 25 \Omega)$
- Internal rotation direction switch.
- All from FG-Input to power output in 1 chip.

BLOCK DIAGRAM



CONNECTION DIAGRAM (Top View)



PIN No.	CONNECTION	PIN No.	CONNECTION
1	PULSE WIDTH TIME CONSTANT	9	+Vcc
2	FG INPUT	10	OUTPUT 1
3	CONSTANT CURRENT INPUT	11	HALL DEVICE INPUT 1
4	ROTATION DIRECTION SWITCH	12	HALL DEVICE INPUT 1'
5	HALL DEVICE INPUT 2'	13	GND
6	HALL DEVICE INPUT 2	14	SAMPLE HOLD
7	CONSTANT VOLTAGE OUTPUT	15	TRIANGLE WAVE TIME CONSTANT
8	OUTPUT 2	16	SAW TOOTH WAVE TIME CONSTANT
TAB	-Vcc		

ABSOLUTE MAXIMUM RATINGS ($T_a = 25$ °C)

Supply Voltage (No Signal)	Vcc	±15	V
Supply Voltage (Operating)	V _{CC}	±12	٧
Circuit Current	lcc	±0.5	Α
Power Dissipation	P_{D}	1.6*	W
Operating Temperature	Topt	-20 to +75	°C
Storage Temperature	T _{stg}	-40 to +150	°C

* T_B = 60 °C

RECOMMENDED OPERATING CONDITIONS

Supply Voltage

 V_{CC} = ±9 to ±12 V

Input Voltage

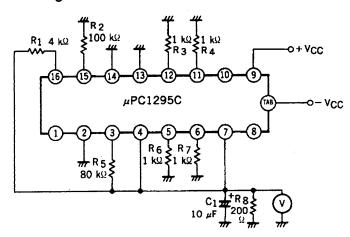
 $V_{ha} = 100 \text{ to } 200 \text{ mV}_{p-p}$

ELECTRICAL CHARACTERISTICS (V_{CC} = ±11 V, f = 400 Hz, T₈ = 25 °C)

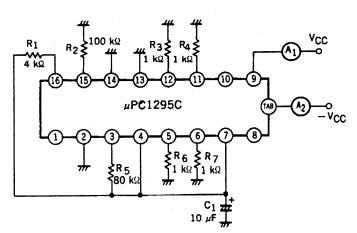
ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	CONDITION
Constant Voltage Output	V _O	3.6	4.0	4.4	V	R _L = 200 Ω
Circuit Current	Icc		±20	±30	mA	RL = ∞
FG Input Threshold Voltage	V _{th}		0.14	0.5	V	
Constant Current Output	¹g	38	46	54	μΑ	R ₂ = 10 kΩ SPEED (#7) = +4 V
Maximum Hold Voltage	V _h (MAX.)	2.8	3.2	3.7	v	$R_2 = 100 \text{ k}\Omega$, $R_1 = 4 \text{ k}\Omega$ $C_2 = 1 \mu\text{F}$ SPEED (#7) = +4 V
Voltage Gain (Power Stage)	Αυ	39	42	45	dB	V _{ha} = 100 mV _{p-p}
Channel Balance (Power Stage)	ΔA _υ		0	±1.5	dB	HOLD (#14) = 1 V
Offset Voltage (Power Stage)	Voffset	-0.7	0.3	1.3	V	V _{ha} = 0
Total Harmonic Distortion (Power Stage)	THD		0.2	1.5	%	
Maximum Output Voltage	V _{om}	+7.2 -7.2	+8.7		V V	R _{L1} = R _{L2} = 25 Ω HOLD (#14) = 1 V
Saturation Voltage	V _{sat}		90	200	mW	I = 1 mA
Reference Voltage	V _{ref}		0	±5	%	

TEST CIRCUITS

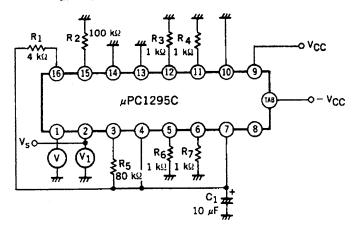
No. 1 Vo = V



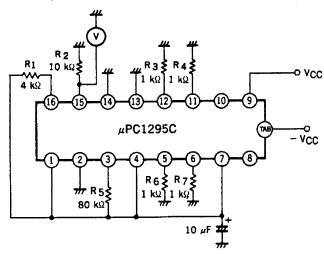
No. 2 ICC= A1, -ICC = A2



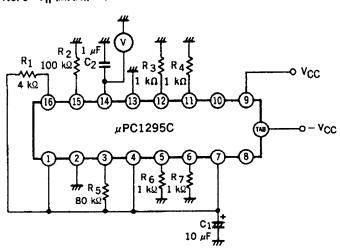
No. 3 Vth = V1



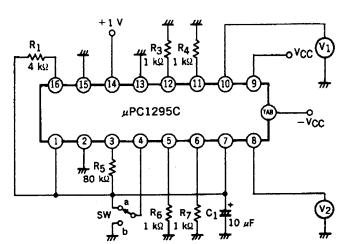
No. 4 ig = V/R2

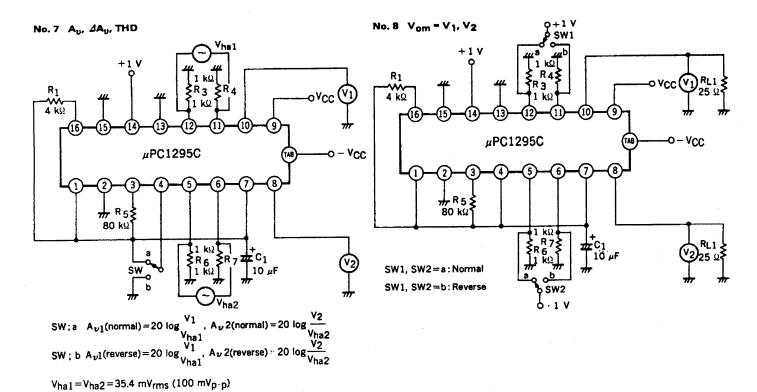


No. 5 Vh (MAX.) = V

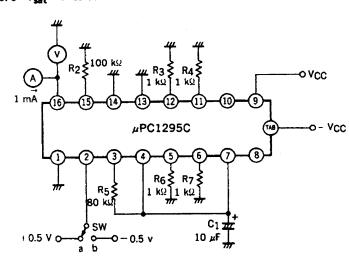


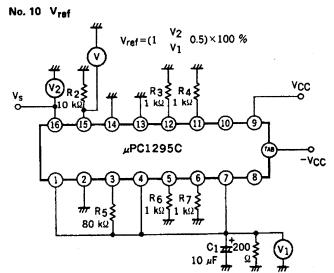
No. 6 $V_{offset} = V_1 - V_2$



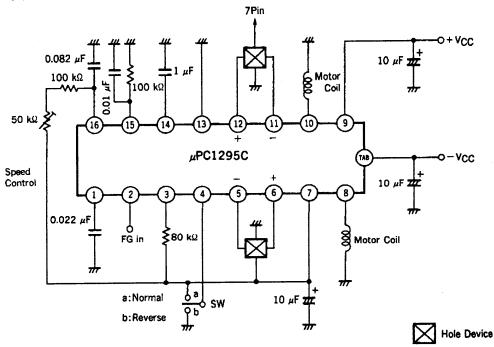


No. 9 V_{sat} = V at SW = b

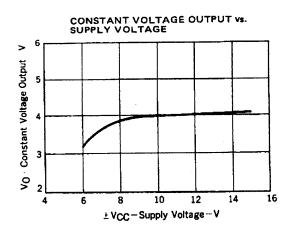


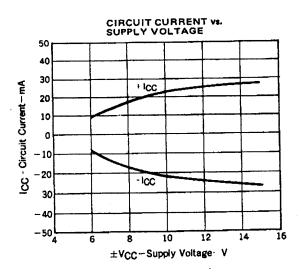


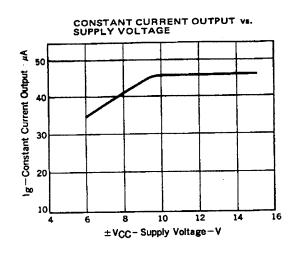
APPLICATION CIRCUIT

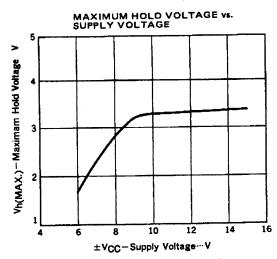


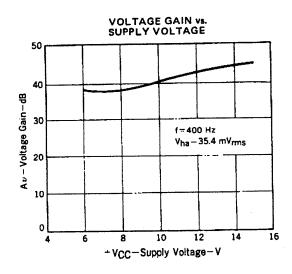
TYPICAL CHARACTERISTICS

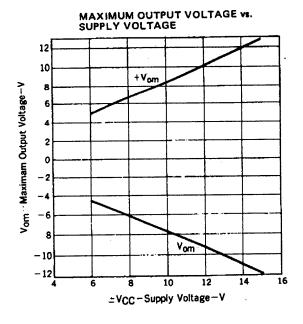


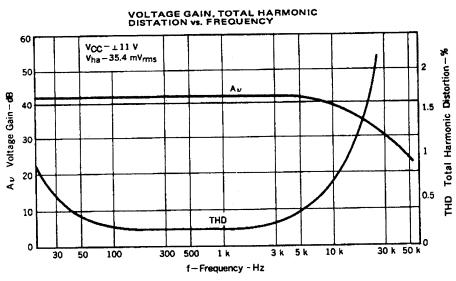


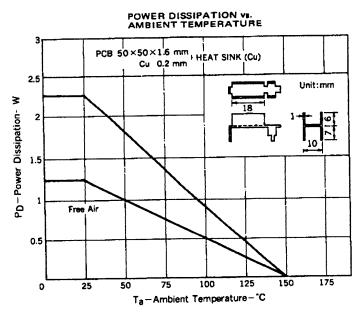




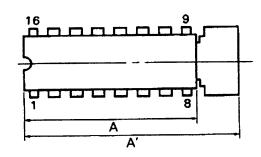


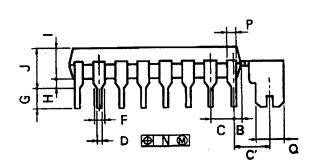


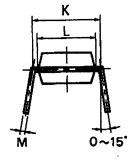




16PIN PLASTIC DIP WITH TAB (300 mil)







P16CT-100-3008

NOTES

- 1) Each lead centerline is located within 0.25 mm (0.01 inch) of its true position (T.P.) at maximum material condition.
- Item "K" to center of leads when formed parallel.

ITEM MILLIMETERS		INCHES			
Α	20.32 MAX.	0.800 MAX.			
A'	24.60 MAX.	0.969 MAX.			
В	1.27 MAX.	0.050 MAX.			
C	2.54 (T.P.)	0.100 (T.P.)			
C,	4.12	0.162			
D	0.50 * 0.10	0.020 '8.886			
F ,	1.1 MIN.	0.043 MIN.			
G	3.4 * 0.3	0.134 + 0.012			
н	0.51 MIN.	0.020 MIN.			
ŗ., Ţ	4.31 MAX.	0.170 MAX.			
J	5.08 MAX.	0.200 MAX.			
К	7.62 (T.P.)	0.300 (T.P.)			
[[6.5	0.256			
M	0.30 '8.65	0.012 0.004			
N	0.25	0.01			
Р	1.0 MIN.	0.039 MIN.			
a	3.17 ^{±0.50}	0.125 ^{ra.020}			