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2010年4月1日
瑞萨电子公司

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7546/7547 群

定时器 A 的操作（输出比较功能实现 PWM 输出）

1. 要点

本篇资料介绍如何使用定时器 A 的比较输出功能产生 PWM 波形。

2. 说明

该应用说明适用于以下条件：

- 采用的 MCU：M37546 群
M37547 群
- 振荡频率：8MHz

3. 内容

3.1 PWM 输出波形说明

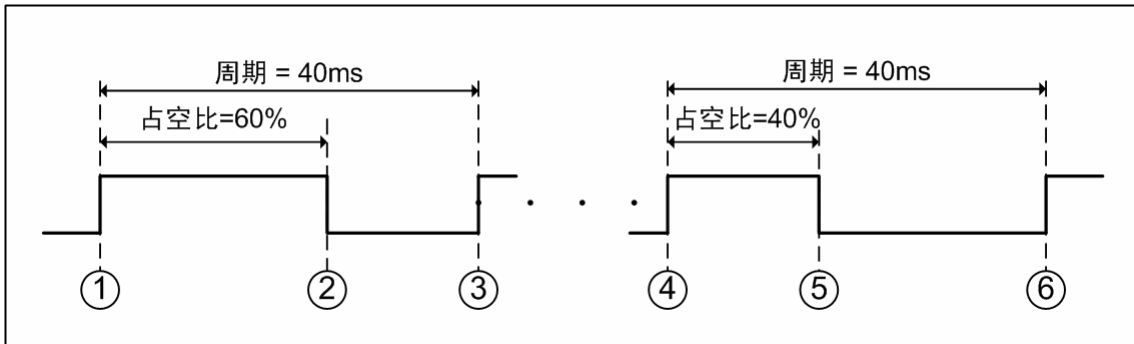


图 1 PWM 输出波形示意图

• 说明

1. 初始化定时器 A 和输出比较功能，设定 PWM 输出的周期和占空比。
2. 当定时器的计数值与比较锁存器中的值一致时，比较输出触发产生；比较输出波形反转。
3. 在定时器下一次下溢时，比较缓冲器中的新设定值写入比较锁存器，当比较输出触发再次产生后，输出波形反转。
4. 重复输出 10 个周期的 PWM 波形后调整占空比参数。
5. 当比较锁存器中新设定值与定时器计数值一致时，比较输出触发产生；比较输出波形反转。
6. 重复输出 10 个周期，调整了占空比的 PWM 波形。

3.2 PWM 输出波形产生时序图

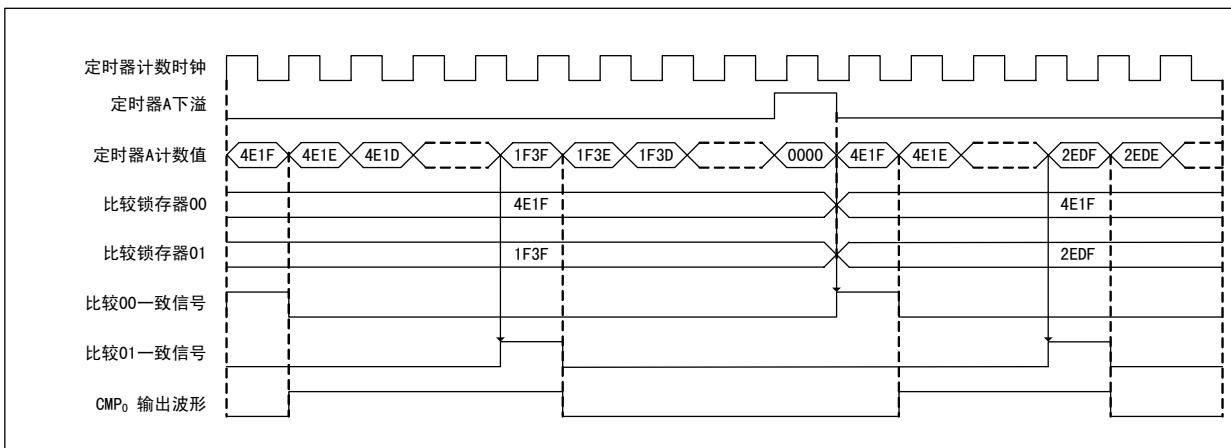


图 2 输出比较功能产生 PWM 波形的时序图

3.3 PWM 参数计算公式

以下公式用于计算 PWM 波形的周期和占空比参数：

$$\text{PWM 周期} = (TA + 1) / f(\text{定时器计数时钟});$$

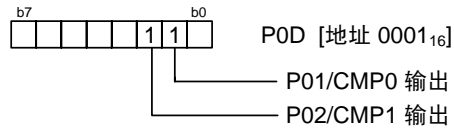
$$\text{输出“H”脉冲占空比} = [(CMPi0 - CMPi1) / (TA+1)] \times 100\%; \quad (i = 0, 1, 2, 3)$$

注：定时器 A 包括低位 (TAL) 和高位 (TAH)；
 CMPi0 和 CMPi1 为输出比较通道 i 的比较锁存器；
 输出比较通道 i 选择正极性输出。

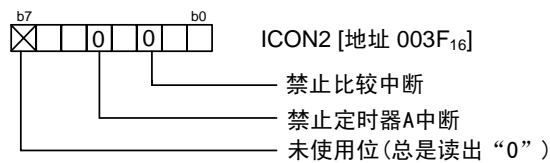
3.4 寄存器设置

本说明使用输出比较通道 0 生成 PWM 波形，特殊寄存器设置方法如下，当使用输出比较通道 1 到 3 时，设置方法相同。

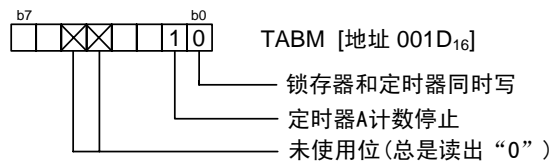
(1) 设置端口P0方向寄存器



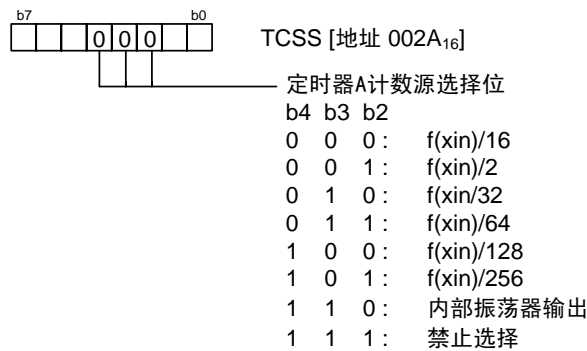
(2) 设置中断控制寄存器2



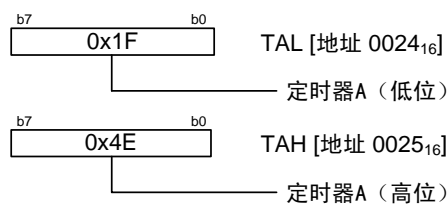
(3) 设置定时器A、B模式寄存器



(4) 设置定时器计数源设定寄存器

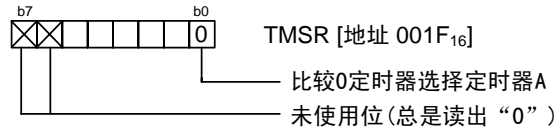


(5) 设置定时器A

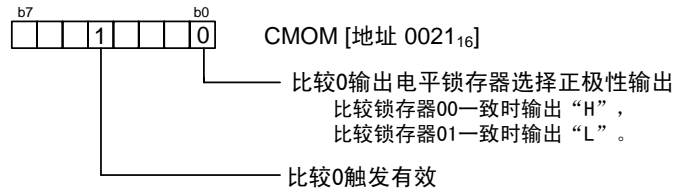


注意：必须按照定时器A的低位（TAL），定时器A的高位（TAH）的顺序给两个寄存器写

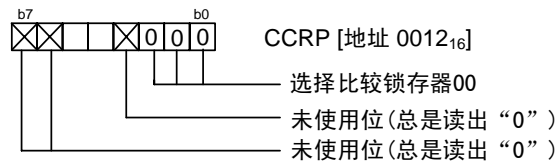
(6) 设置捕捉/比较定时器源选择寄存器



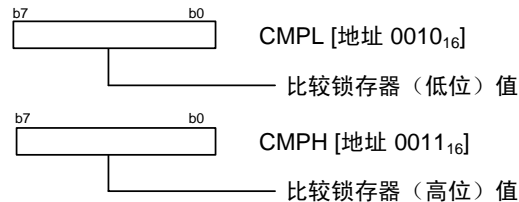
(7) 设置比较输出模式选择寄存器



(8) 设置捕捉/比较寄存器R/W指针



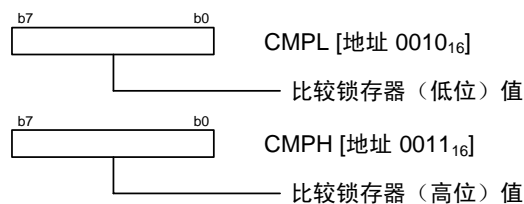
(9) 设置比较锁存器00



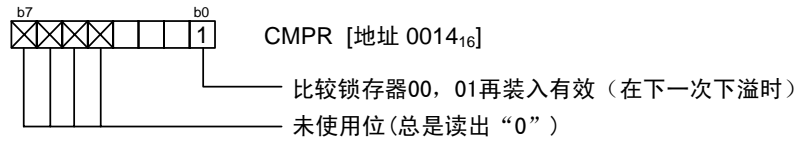
(10) 设置捕捉/比较寄存器R/W指针



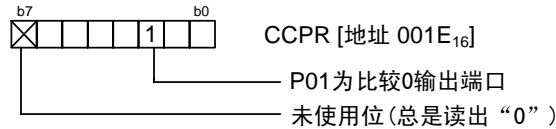
(11) 设置比较锁存器01



(12) 设置比较设置再装入寄存器



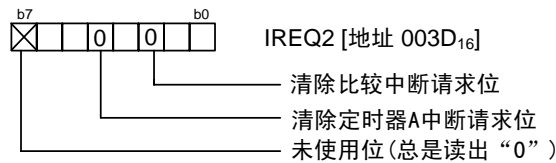
(13) 设置捕捉/比较端口寄存器



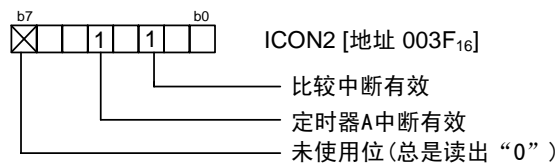
(14) 设置比较中断源设定寄存器



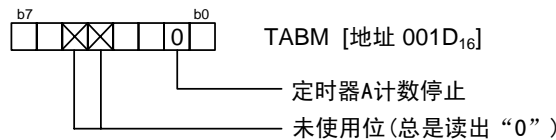
(15) 设置中断请求寄存器2



(16) 设置中断控制寄存器2



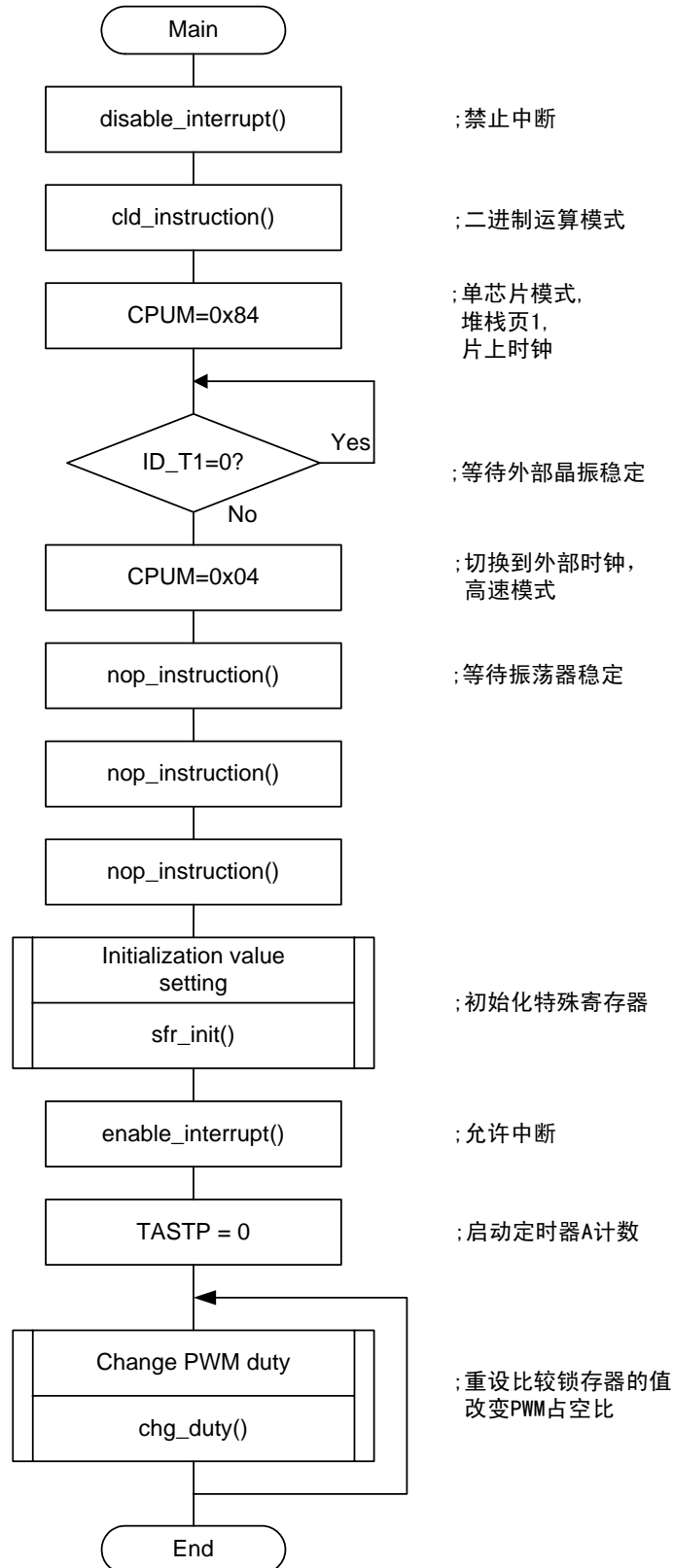
(17) 设置定时器A、B模式寄存器



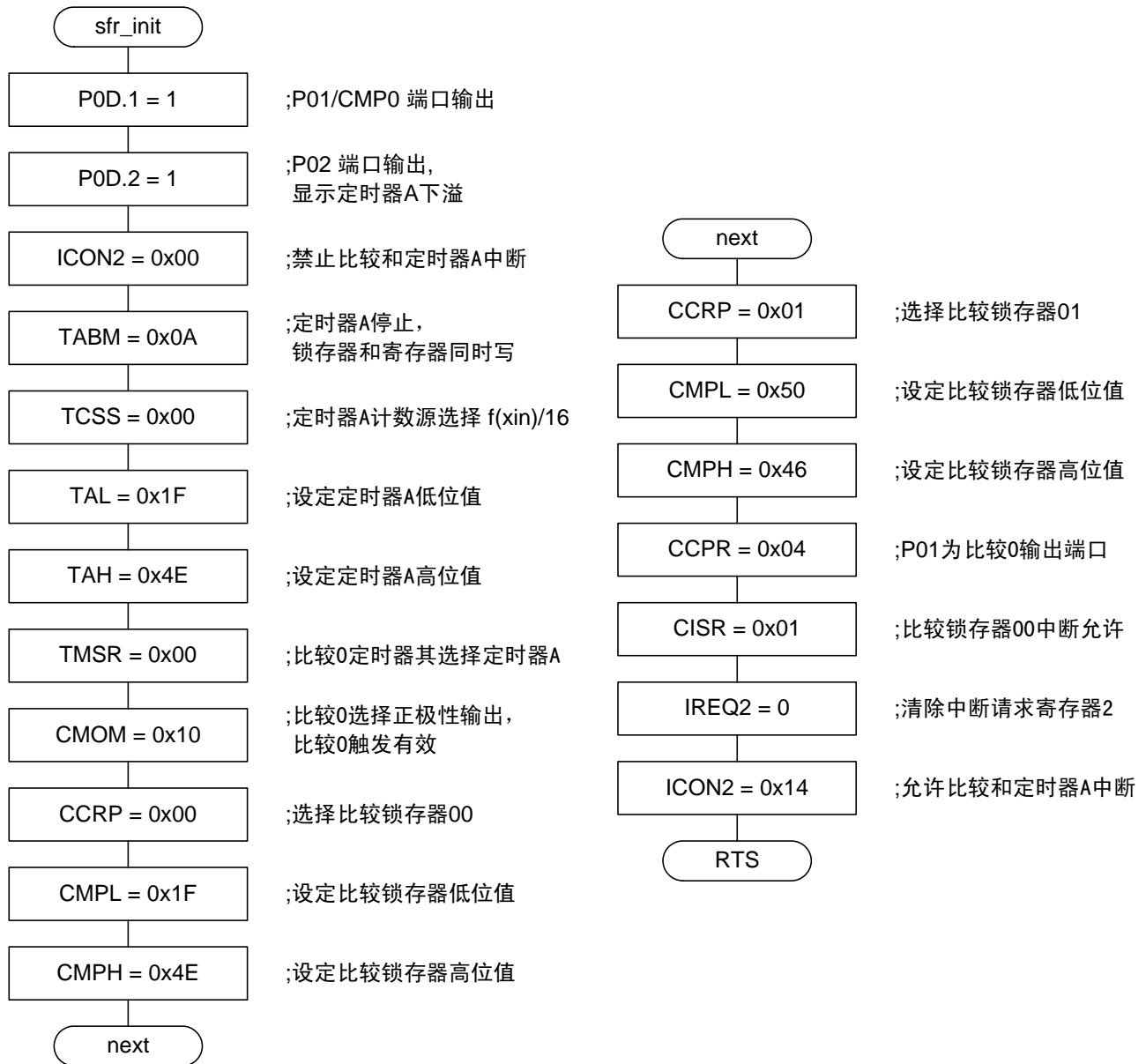
注：在定时器 A 计数期间要改变输出比较通道 0 输出波形时，重复上述步骤(8)~(12)。必须将比较锁存器 00, 01 重装入位设置为“1”（下次下溢时重装入有效），这样在定时器下次下溢时，比较缓冲器中的新设定值才写入比较锁存器。

4. 程序流程图

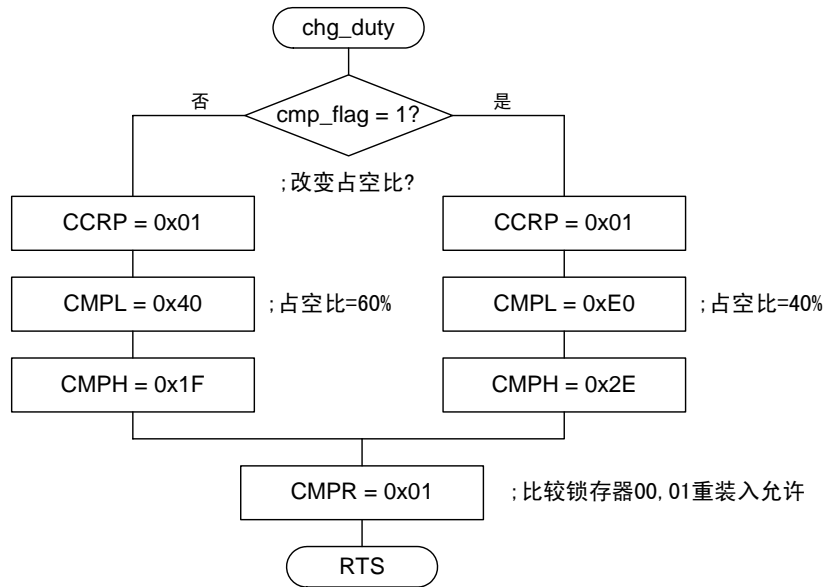
4.1 主程序流程图



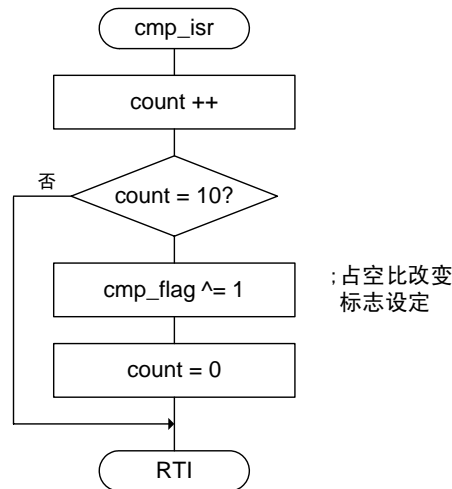
4.2 输出比较初始化子程序 (cmp_init)



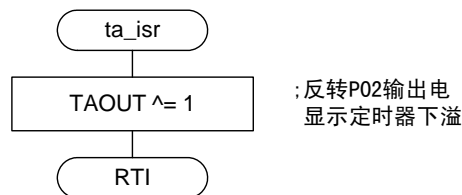
4.3 PWM 输出占空比参数设定子程序 (chg_duty)



4.4 比较中断服务子程序 (cmp_isr)



4.5 定时器 A 中断服务子程序 (ta_isr)



5. 参考例程

请从瑞萨科技网站上下载参考例程。

在 7546/7547 群的网页上单击左边的“Application Notes”下载应用笔记。

6. 参考文献

数据手册

7546/7547 群硬件手册

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Rev.	发行日	修订内容	
		页	要点
1.01	2006.10.26	—	初版发行
1.02	2008.03.17	2	修改 3.1 说明内容第 2、3 项；修改 3.3 公式（定时器时钟→定时器计数时钟；脉冲时间→脉冲占空比）和注释内容
		3	修改 3.4 寄存器设置内容（比较→输出比较通道）
		9	修改参考例程内容
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10. 本公司一直致力于提高产品的质量和可靠性，但一般来说，半导体产品总会以一定的概率发生故障、或者由于使用条件不同而出现错误运行等。为了避免因本公司的产品发生故障或者错误运行而导致人身事故和火灾或造成社会性的损失，希望客户能自行负责进行冗余设计、采取延烧对策及进行防止错误运行等的安全设计(包括硬件和软件两方面的设计)以及老化处理等，这是作为机器和系统的出厂保证。特别是单片机的软件，由于单独进行验证很困难，所以要求在顾客制造的最终的机器及系统上进行安全检验工作。
11. 如果把本资料所记载的产品从其载体设备上卸下，有可能造成婴儿误吞的危险。顾客在将本公司产品安装到顾客的设备上时，请顾客自行负责将本公司产品设置为不容易剥落的安全设计。如果从顾客的设备上剥落而造成事故时，本公司将不承担任何责任。
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