

RL78/G22

Serial Array Unit (UART Communication)

Introduction

This application note explains how to use UART communication through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

Target Device

RL78/G22

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

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1. Specification

1.1 Overview of Specification

In this application note, UART communication is performed through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

Table 1-1 shows the peripheral function to be used and its use. Figures 1-1 and 1-2 illustrate UART communication operation.

Table 1-1 Peripheral Function and Use

Peripheral Function	Use
Serial array unit UART0	Perform UART communication using the TxD0 pin (transmission) and the RxD0 pin (reception).

Figure 1-1 UART Reception Timing Chart

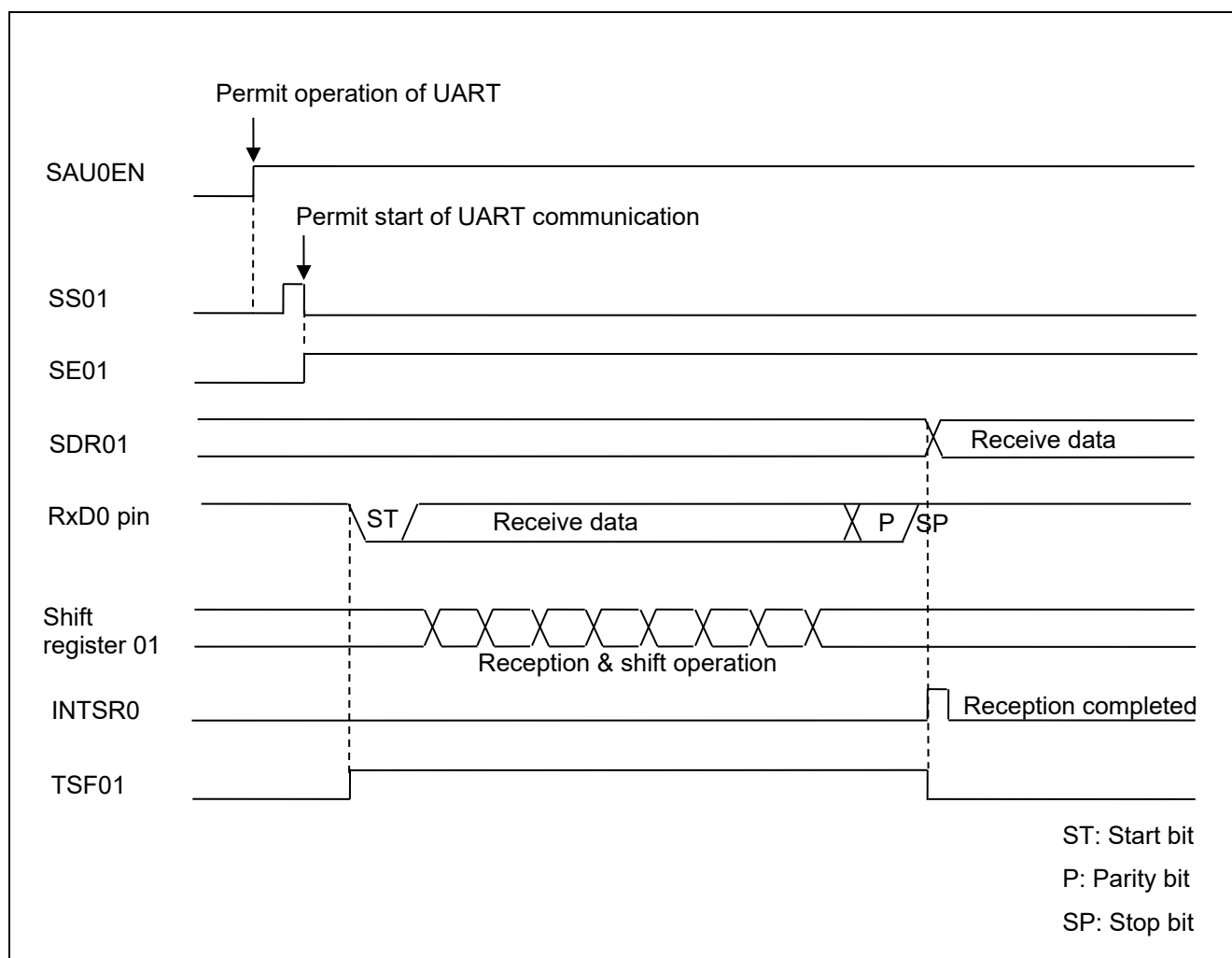
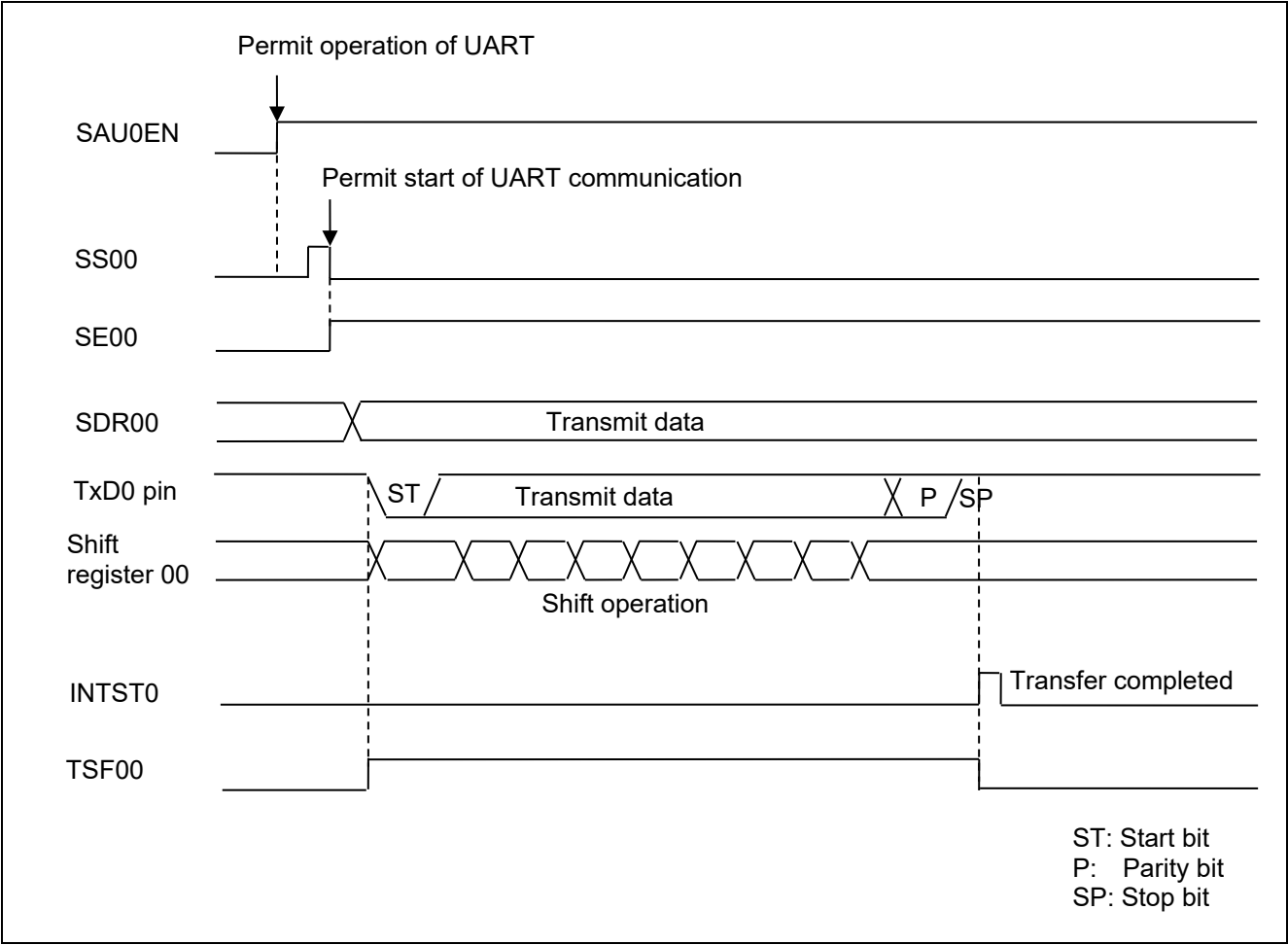


Figure 1-2 UART Transmission Timing Chart



1.2 Outline of Operation

This sample code transmits, to the device on the opposite side, the data corresponding to that received from the device. If an error occurs, it transmits to the device the data corresponding to the error. Tables 1-2 and 1-3 show the correspondence between transmit data and receive data.

Table 1-2 Correspondence between Receive Data and Transmit Data

Receive Data	Response (Transmit) Data
T (54H)	O (4FH), K (4BH), "CR" (0DH), "LF" (0AH)
t (74H)	o (6FH), k (6BH), "CR" (0DH), "LF" (0AH)
Other than above	U (55H), C (43H), "CR" (0DH), "LF" (0AH)

Table 1-3 Correspondence between Error and Transmit Data

Error	Response (Transmit) Data
Parity error	P (50H), E (45H), "CR" (0DH), "LF" (0AH)
Framing error	F (46H), E (45H), "CR" (0DH), "LF" (0AH)
Overrun error	O (4FH), E (45H), "CR" (0DH), "LF" (0AH)

The following describes the major settings of the peripheral functions.

(1) Initial settings of the UART

- Use SAU0 channels 0 and 1 as UART.
- Use the P12/TxD0 pin and the P11/RxD0 pin for data output and data input, respectively.
- The data length is 8 bits.
- Set the data transfer direction to LSB first.
- Use even parity as the parity setting.
- Set the receive data level to standard.
- Set the transfer rate to 9600 bps.
- Use reception end interrupt (INTSR0), transmission end interrupt (INTST0), and error interrupt (INTSRE0).
- Set the interrupt priority orders of INTSR0, INTST0, and INTSRE0 to low priority.

2. Operation Confirmation Conditions

The operation of the sample code provided with this application note has been tested under the following conditions.

Table 2-1 Operation Confirmation Conditions

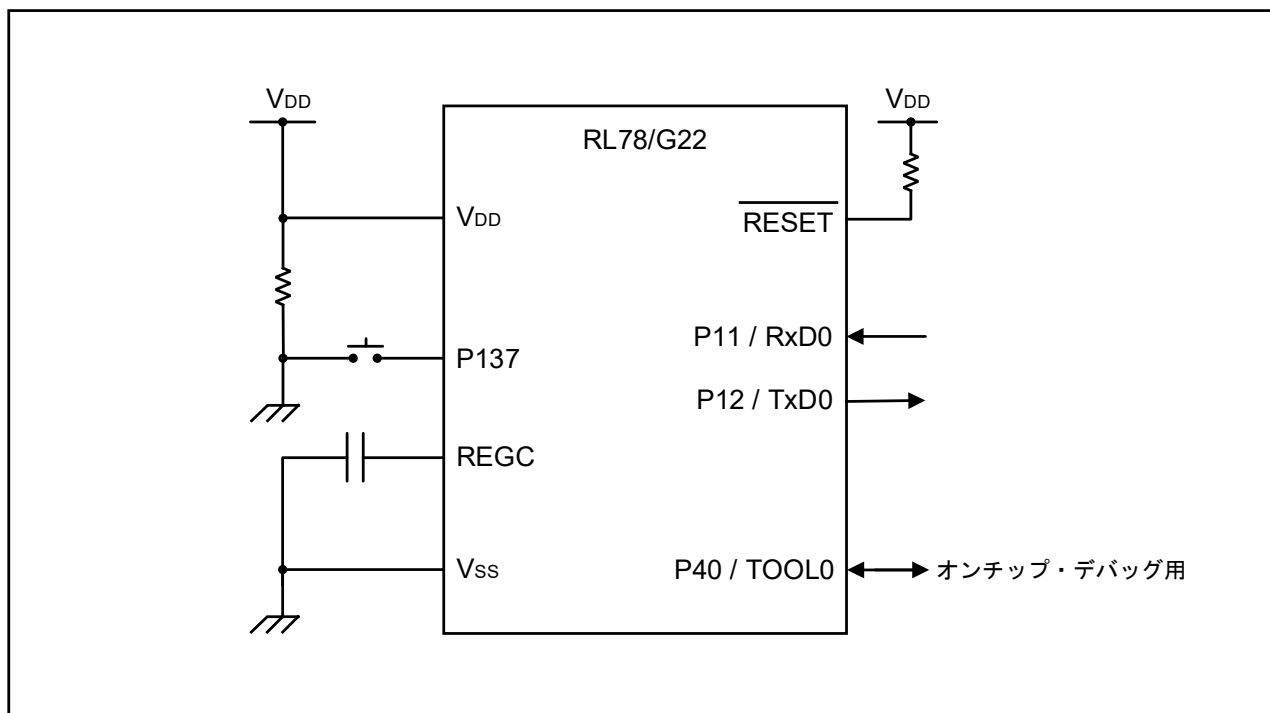
Item	Description
MCU used	RL78/G22 (R7F102GGE2DFB)
Board used	RL78/G22-48p Fast Prototyping Board (RTK7RLG220C00000BJ)
Operating frequency	High-speed on-chip oscillator clock (f_{IH}): 32 MHz
Operating voltage	5.0V (Available from 1.8V to 5.5V)
Integrated development environment (CS+)	CS+ V8.11.00 from Renesas Electronics Corp.
C compiler (CS+)	CC-RL V1.12.00 from Renesas Electronics Corp.
Integrated development environment (e2studio)	e2 studio V2024-04 from Renesas Electronics Corp.
C compiler (e2studio)	CC-RL V1.13.01 from Renesas Electronics Corp.
Integrated development environment (IAR)	IAR Embedded Workbench for Renesas RL78 V5.10.1 from IAR Systems Corp.
C compiler (IAR)	IAR C/C++ Compiler for Renesas RL78 V5.10.1 from IAR Systems Corp.
Smart Configurator	V.1.10.0 from Renesas Electronics Corp.
Board support package (r_bsp)	V.1.6.2 from Renesas Electronics Corp.

3. Hardware Descriptions

3.1 Example of Hardware Configuration

Figure 3-1 shows an example of the hardware configuration used in the application note.

Figure 3-1 Hardware Configuration



Note 1. This simplified circuit diagram was created to show an overview of connections only. When actually designing your circuit, make sure the design includes appropriate pin handling and meets electrical characteristic requirements (connect each input-only port to VDD or VSS through a resistor).

Note 2. VDD must not be lower than the reset release voltage (VLVD0) that is specified for the LVD0.

3.2 List of Pins to be Used

Table 3-1 lists the pins to be used and their functions.

Table 3-1 Pins to be Used and Their Functions

Pin name	I/O	Function
P12 / TxD0	Output	Data transmission pin
P11 / RxD0	Input	Data reception pin

Caution In this application note, only the used pins are processed. When actually designing your circuit, make sure the design includes sufficient pin processing and meets electrical characteristic requirements.

4. Software Explanation

4.1 Setting of Option Byte

Table 4-1 shows the option byte settings.

Table 4-1 Option Byte Settings

Address	Setting Value	Contents
000C0H / 040C0H	11101111B	Disables the watchdog timer. (Counting stopped after reset)
000C1H / 040C1H	11111110B	LVD0 detection voltage: Reset mode At rising edge TYP. 1.90 V (1.84 V ~ 1.95 V) At falling edge TYP. 1.86 V (1.80 V ~ 1.91 V)
000C2H / 040C2H	11101000B	HS mode, High-speed on-chip oscillator clock (f_{IH}): 32 MHz
000C3H / 040C3H	10000101B	Enables on-chip debugging

4.2 List of Constants

Table 4-2 Constants lists the constants that are used in the sample code.

Table 4-2 Constants

Constant Name	Setting Value	Description
MessageOK[4]	"OK¥r¥n"	Response message to reception of "T".
Messageok[4]	"ok¥r¥n"	Response message to reception of "t".
MessageUC[4]	"UC¥r¥n"	Response message to reception of characters other than "T" or "t".
MessageFE[4]	"FE¥r¥n"	Response message to a framing error.
MessagePE[4]	"PE¥r¥n"	Response message to a parity error.
MessageOE[4]	"OE¥r¥n"	Response message to an overrun error.

4.3 List of Variables

Table 4-3 lists global variables.

Table 4-3 Global Variables

Type	Variable Name	Contents	Function Used
uint8_t	g_Uart0RxBuf	Receive data buffer	main()
uint8_t	g_Uart0RxErr	Receive error factor	main()、 r_Config_UART0_callback_receiveend、 r_Config_UART0_callback_error
MD_STATUS	g_Uart0TxEnd	transmission completion flag	main()、 r_Config_UART0_callback_sendend
uint8_t	gp_uart0_tx_address	Transmit data pointer	R_Config_UART0_Send、 r_Config_UART0_interrupt_send
uint16_t	g_uart0_tx_count	Transmit data number counter	R_Config_UART0_Send、 r_Config_UART0_interrupt_send
uint8_t	gp_uart0_rx_address	Receive data pointer	R_Config_UART0_Receive、 r_Config_UART0_interrupt_receive、 r_Config_UART0_interrupt_error
uint16_t	g_uart0_rx_count	Receive data number counter	R_Config_UART0_Receive、 r_Config_UART0_interrupt_receive
uint16_t	g_uart0_rx_length	Receive data number	R_Config_UART0_Receive、 r_Config_UART0_interrupt_receive

4.4 List of Functions

Table 4-4 shows a list of functions.

Table 4-4 Functions

Function Name	Outline
main()	Main processing
r_Config_UART0_interrupt_send()	UART0 transmission end interrupt handling
r_Config_UART0_interrupt_receive()	UART0 reception end interrupt handling
r_Config_UART0_interrupt_error()	UART0 error interrupt handling

4.5 Specification of Functions

The function specifications of the sample code are shown below.

main()	
Outline	Main processing
Header	r_cg_macrodriver.h、r_cg_userdefine.h、Config_UART0.h
Declaration	void main(void);
Description	This function sends the data corresponding to the data received from the counterpart device to the counterpart device.
Argument	None
Return Value	None
r_Config_UART0_interrupt_send()	
Outline	UART0 transmission end interrupt handling
Header	r_cg_macrodriver.h、r_cg_userdefine.h、Config_UART0.h
Declaration	#pragma interrupt r_Config_UART0_interrupt_send(vect=INTST0)
Description	This function starts sending data. It then updates the send data pointer and the number of data to be sent counter.
Argument	None
Return Value	None
r_Config_UART0_interrupt_receive()	
Outline	UART0 reception end interrupt handling
Header	r_cg_macrodriver.h、r_cg_userdefine.h、Config_UART0.h
Declaration	#pragma interrupt r_Config_UART0_interrupt_receive(vect=INTSR0)
Description	This function stores the received data in RAM. It then updates the receive data pointer and the receive data count counter.
Argument	None
Return Value	None
r_Config_UART0_interrupt_error()	
Outline	UART0 error interrupt handling
Header	r_cg_macrodriver.h、r_cg_userdefine.h、Config_UART0.h
Declaration	#pragma interrupt r_Config_UART0_interrupt_error(vect=INTSRE0)
Description	This function stores the error factor in RAM and clears the receive error flag.
Argument	None
Return Value	None

4.6 Flowcharts

4.6.1 Main Processing

Figure 4-1 and 4-2 show flowcharts of the main processing.

Figure 4-1 Main Processing (1/2)

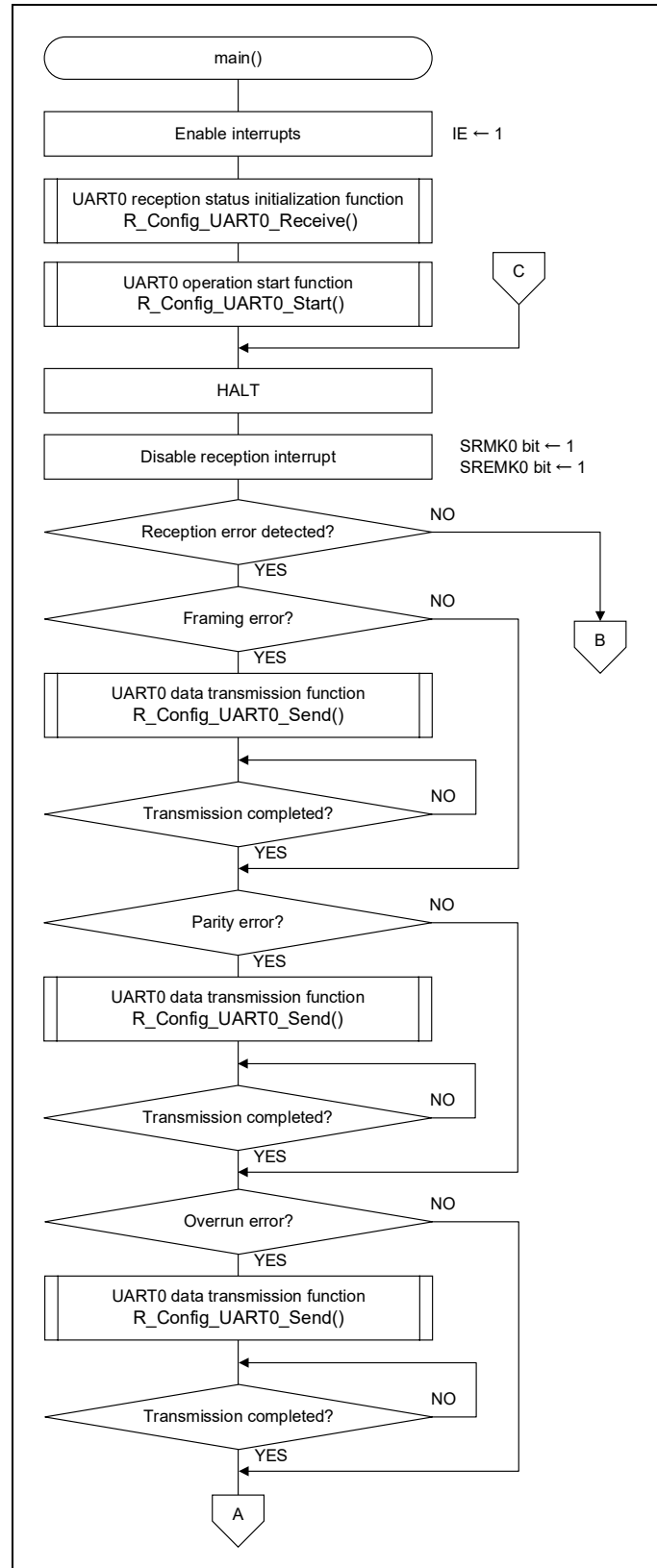
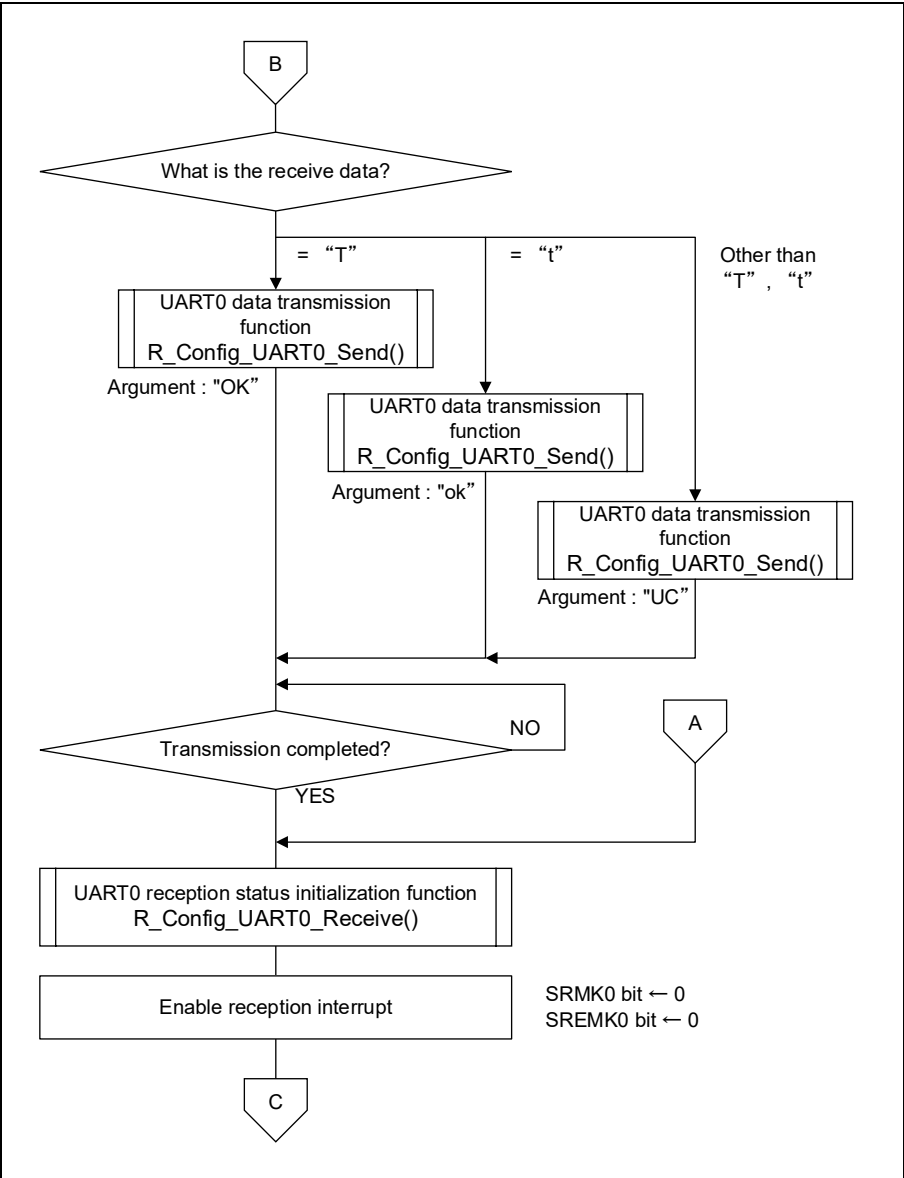


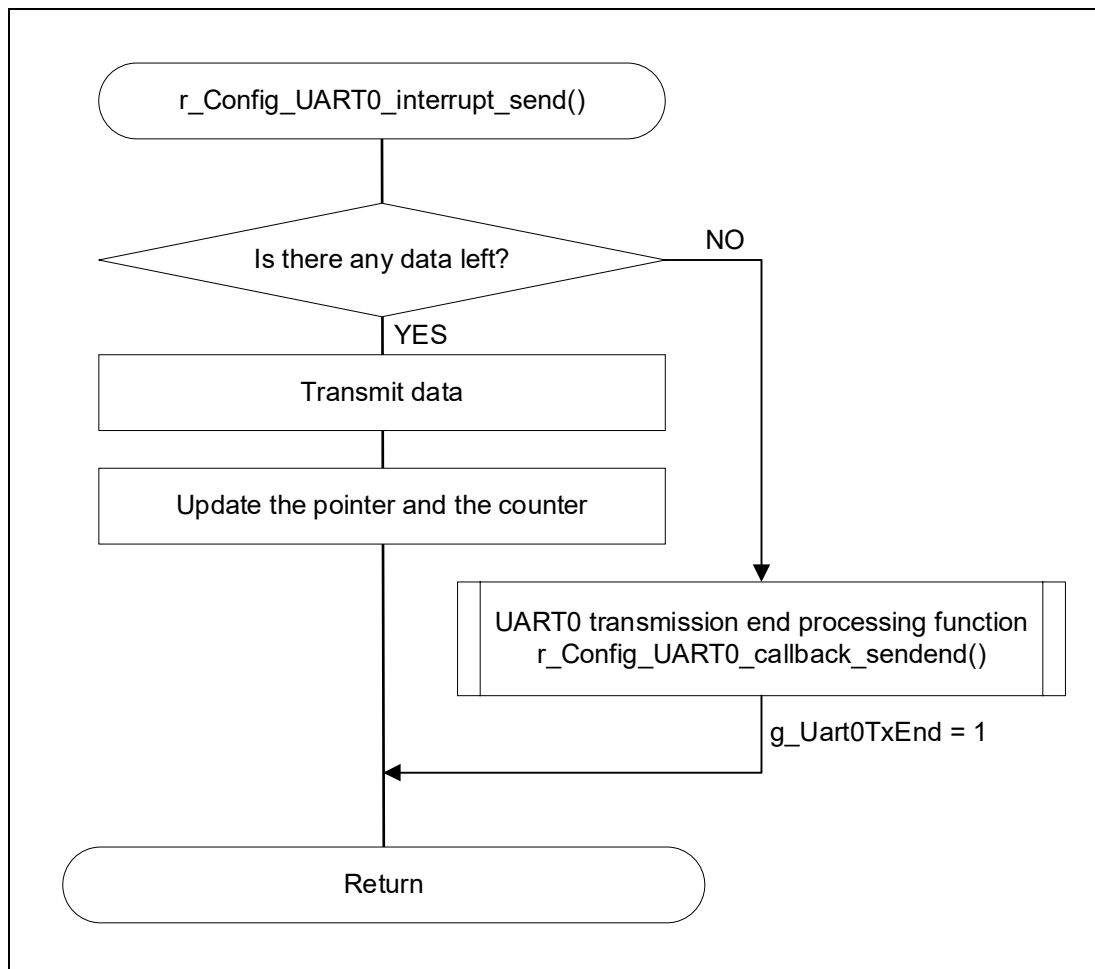
Figure 4-2 Main Processing (2/2)



4.6.2 UART0 Transmission End Interrupt Handling

Figure 4-3 shows the flowchart of the UART0 transmission end interrupt handling.

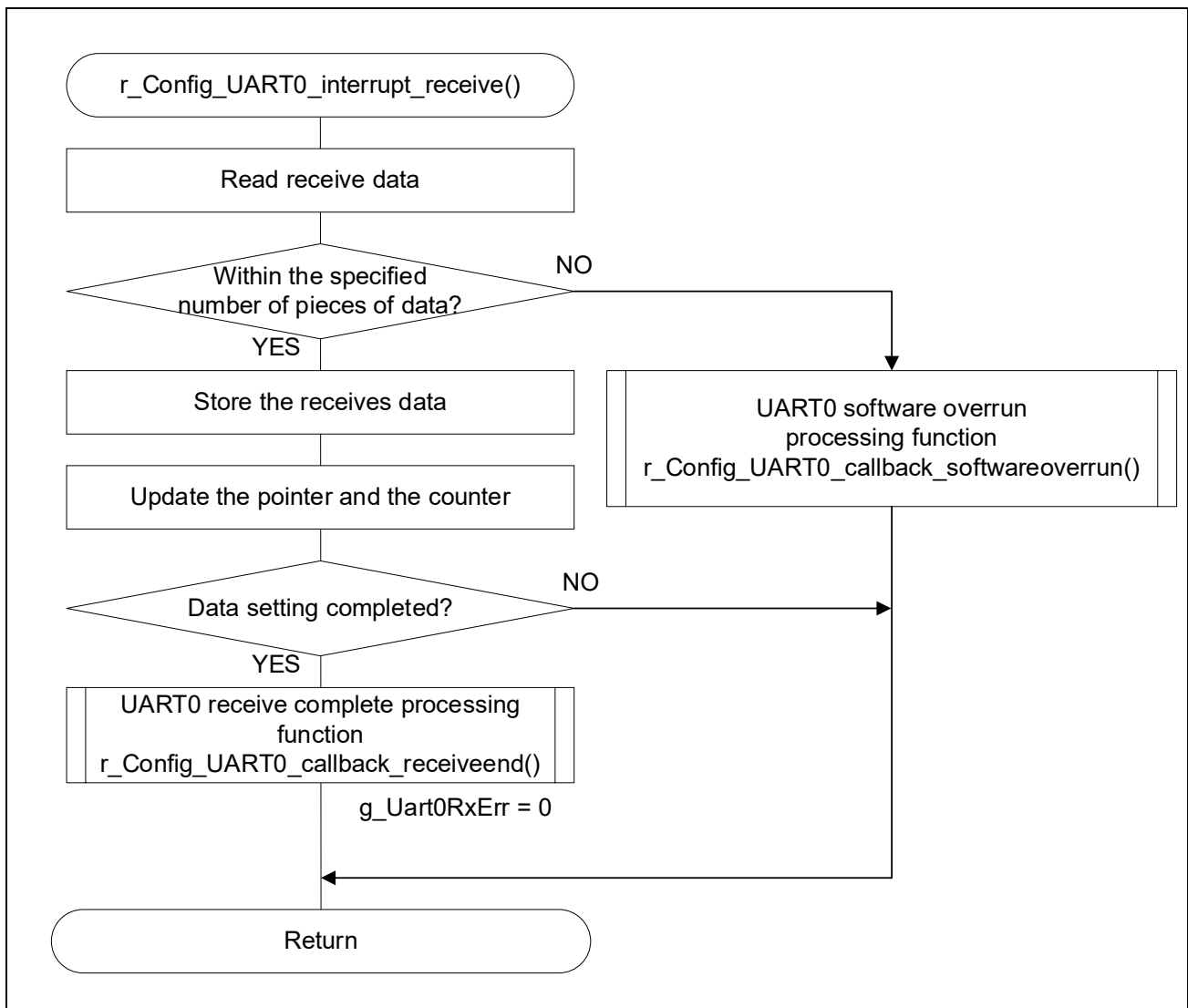
Figure 4-3 UART0 Transmission End Interrupt Handling



4.6.3 UART0 Reception End Interrupt Handling

Figure 4-4 shows the flowchart of the UART0 reception end interrupt handling.

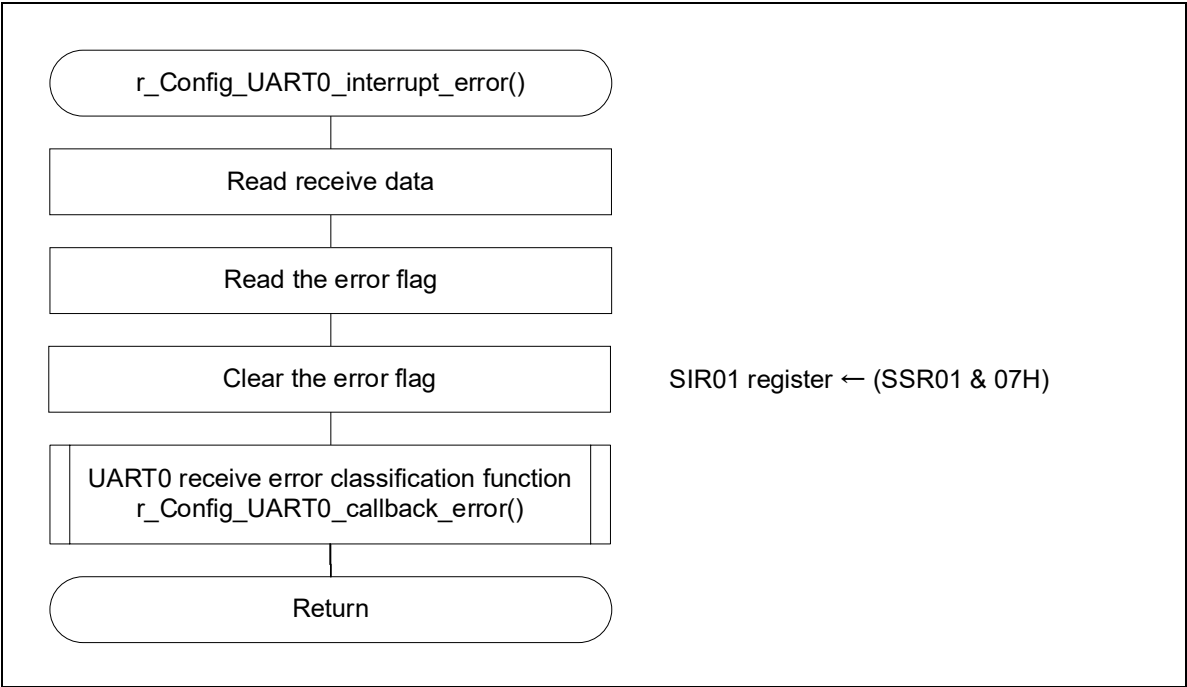
Figure 4-4 UART0 Reception End Interrupt Handling



4.6.4 UART0 Error Interrupt Handling

Figure 4-5 shows the flowchart of the UART0 error interrupt handling.

Figure 4-5 UART0 Error Interrupt Handling



5. Sample Code

Sample code can be downloaded from the Renesas Electronics website.

6. Reference Documents

RL78/G22 User's Manual: Hardware (R01UH0978)

RL78 family user's manual software (R01US0015)

The latest versions can be downloaded from the Renesas Electronics website.

Technical update

The latest versions can be downloaded from the Renesas Electronics website.

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Revision History

Rev.	Date	Description	
		Page	Summary
1.00		-	First Edition

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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(Rev.5.0-1 October 2020)

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