Description

RENESAS

The 9DB1233 zero-delay buffer supports PCIe Gen3 requirements, while being backwards compatible to PCIe Gen2 and Gen1. The 9DB1233 is driven by a differential SRC output pair from an IDT 932S421 or 932SQ420 or equivalent main clock generator. It attenuates jitter on the input clock and has a selectable PLL bandwidth to maximize performance in systems with or without spread-spectrum clocking.

Typical Applications

12-output PCIe Gen3 zero-delay/fanout buffer

Output Features

Twelve 0.7V current mode differential HSCL output pairs

Features

- 3 selectable SMBus addresses; multiple devices can share the same SMBus segment
- 12 OE# pins; hardware control of each output
- PLL or bypass mode; PLL can dejitter incoming clock
- Selectable PLL bandwidth; minimizes jitter peaking in downstream PLLs
- Spread spectrum compatible; tracks spreading input clock for low EMI
- SMBus interface; unused outputs can be disabled
- Undriven differential outputs in Power-down; improved power management

Key Specifications

- Cycle-to-cycle jitter < 50ps
- Output-to-output skew < 50ps
- PCIe Gen3 phase jitter < 1.0ps RMS
- Pin compatible with DB1200 Yellow Cover device



Block Diagram

Contents

| Description |
|--|
| Typical Applications |
| Output Features |
| Features |
| Key Specifications 1 |
| Block Diagram |
| Pin Assignments |
| Pin Descriptions |
| Absolute Maximum Ratings |
| Electrical Characteristics–Clock Input Parameters |
| Electrical Characteristics–Current Consumption |
| Electrical Characteristics–Input/Supply/Common Parameters |
| Electrical Characteristics–DIF 0.7V Current Mode Differential Outputs |
| Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics |
| Electrical Characteristics-PCIe Phase Jitter Parameters |
| Clock Periods Differential Outputs with Spread Spectrum Enabled |
| Clock Periods Differential Outputs with Spread Spectrum Disabled |
| Terminations |
| General SMBus Serial Interface Information |
| Package Outline Drawings |
| Marking Diagram |
| Ordering Information |
| Revision History |

Pin Assignments

| Figure 1. | Pin Assignments for | or 6.10mm Body 64-TSSOP | Package - Top View |
|-----------|---------------------|-------------------------|--------------------|
| | | | |

| DIF_IN 2 63 AGND DIF_IN# 3 62 IREF GND 4 61 VDD OE0# 5 60 OE11# DIF_0 6 59 DIF_11 DIF_0 7 58 DIF_11# VDD 8 57 VDD GND 9 56 GND OE1# 10 55 OE10# DIF_1 11 54 DIF_10 DIF_1 11 54 DIF_10 DIF_2 14 51 DIF_9 DIF_2 14 51 DIF_9 DIF_2 15 50 DIF_9# GND 16 7 48 VDD OE3# 18 67 OE8# DIF_3 19 66 DIF_8 DIF_3 20 45 DIF_8# OE4# 21 44 OE7# DIF_4 22 43 DIF_7 DIF_4 22 43 DIF_7 DIF_4 23 42 DIF_7# VDD 24 41 VDD GND 25 40 GND OE5# 26 39 OE6# DIF_5 27 38 DIF_6 DIF_5 27 38 DIF_6 TF_6 27 38 DIF_6 DIF_6# **ADR_SEL 29 36 VTTPWRGD#/PD HIGH_BW# 30 35 BYPASS#/PLL VDD 31 34 GND |
|---|
|---|

64-TSSOP

** Indicates 120kOhm pull-dow n

SMBus Address Selection (Pin 29)

| ADR_SEL | Voltage | SMBus Adr (Wr/Rd) |
|---------|---|-------------------|
| Low | <0.8V | DC/DD |
| Mid | 1.2 <vin<1.8v< td=""><td>D6/D7</td></vin<1.8v<> | D6/D7 |
| High | Vin > 2.0V | D4/D5 |

Power Groups

| Pin N | lumber | Description | | | |
|----------------|----------------|------------------|--|--|--|
| VDD | GND | Description | | | |
| 1 | 4 | DIF_IN/DIF_IN# | | | |
| 8, 17, 24, 41, | 9, 16, 25, 40, | DIF(11:0) | | | |
| 48, 57 | 49, 56 | Dii (11.0) | | | |
| N/A | 63 | IREF | | | |
| 64 | 63 | Analog VDD & GND | | | |
| 04 | 05 | for PLL core | | | |

Note: Please treat pin 1 as an analog VDD.

Pin Descriptions

| PIN # | PIN NAME | TYPE | DESCRIPTION |
|-------|-----------|-------|---|
| 1 | VDD | PWR | Pow er supply, nominal 3.3V |
| 2 | DIF_IN | IN | 0.7 V Differential TRUE input |
| 3 | DIF_IN# | IN | 0.7 V Differential Complementary Input |
| 4 | GND | PWR | Ground pin. |
| 5 | OE0# | IN | Active low input for enabling DIF pair 0. |
| 5 | | IIN | 1 =disable outputs, 0 = enable outputs |
| 6 | DIF_0 | OUT | 0.7V differential true clock output |
| 7 | DIF_0# | OUT | 0.7V differential Complementary clock output |
| 8 | VDD | PWR | Pow er supply, nominal 3.3V |
| 9 | GND | PWR | Ground pin. |
| 10 | OE1# | IN | Active low input for enabling DIF pair 1. |
| | | | 1 =disable outputs, 0 = enable outputs |
| 11 | DIF_1 | OUT | 0.7V differential true clock output |
| 12 | DIF_1# | OUT | 0.7V differential Complementary clock output |
| 13 | OE2# | IN | Active low input for enabling DIF pair 2. |
| | | | 1 =disable outputs, 0 = enable outputs |
| 14 | DIF_2 | OUT | 0.7V differential true clock output |
| 15 | DIF_2# | OUT | 0.7V differential Complementary clock output |
| 16 | GND | PWR | Ground pin. |
| 17 | VDD | PWR | Pow er supply, nominal 3.3V |
| 18 | OE3# | IN | Active low input for enabling DIF pair 3. |
| | | | 1 =disable outputs, 0 = enable outputs |
| 19 | DIF_3 | OUT | 0.7V differential true clock output |
| 20 | DIF_3# | OUT | 0.7V differential Complementary clock output |
| 21 | OE4# | IN | Active low input for enabling DIF pair 4 |
| | | | 1 =disable outputs, 0 = enable outputs |
| 22 | DIF_4 | OUT | 0.7V differential true clock output |
| 23 | DIF_4# | OUT | 0.7V differential Complementary clock output |
| 24 | VDD | PWR | Pow er supply, nominal 3.3V |
| 25 | GND | PWR | Ground pin. |
| 26 | OE5# | IN | Active low input for enabling DIF pair 5. |
| | | | 1 =disable outputs, 0 = enable outputs |
| 27 | DIF_5 | OUT | 0.7V differential true clock output |
| 28 | DIF_5# | OUT | 0.7V differential Complementary clock output |
| 29 | **ADR_SEL | IN | This tri-level input selects one of 3 SMBus addresses. See the SMBus Address Select Table for the addresses. |
| | | + + | 3.3V input for selecting PLL Band Width |
| 30 | HIGH_BW# | IN | 0 = High, 1= Low |
| 31 | VDD | PWR | Pow er supply, nominal 3.3V |
| 32 | SMBCLK | IN IN | Clock pin of SMBUS circuitry, 5V tolerant |
| | | | |

Pin Descriptions (cont.)

| PIN # | PIN NAME | TYPE | DESCRIPTION |
|-------|--------------|------|---|
| 33 | SMBDAT | ٧O | Data pin of SMBUS circuitry, 5V tolerant |
| 34 | GND | PWR | Ground pin. |
| 35 | BYPASS#/PLL | IN | Input to select Bypass(fan-out) or PLL (ZDB) mode 0 = Bypass mode, 1= PLL mode |
| 36 | VTTPWRGD#/PD | IN | VTTPWRGD# is an active low input used to sample latched inputs and allow the device to Pow er Up. PD is an asynchronous active high input pin used to put the device into a low pow er state. The internal clocks and PLLs are stopped. |
| 37 | DIF_6# | OUT | 0.7V differential Complementary clock output |
| 38 | DIF_6 | OUT | 0.7V differential true clock output |
| 39 | OE6# | IN | Active low input for enabling DIF pair 6. 1 =disable outputs, 0 = enable outputs |
| 40 | GND | PWR | Ground pin. |
| 41 | VDD | PWR | Pow er supply, nominal 3.3V |
| 42 | DIF_7# | OUT | 0.7V differential Complementary clock output |
| 43 | DIF_7 | OUT | 0.7V differential true clock output |
| 44 | OE7# | IN | Active low input for enabling DIF pair 7. 1 =disable outputs, 0 = enable outputs |
| 45 | DIF_8# | OUT | 0.7V differential Complementary clock output |
| 46 | DIF_8 | OUT | 0.7V differential true clock output |
| 47 | OE8# | IN | Active low input for enabling DIF pair 8. 1 =disable outputs, 0 = enable outputs |
| 48 | VDD | PWR | Pow er supply, nominal 3.3V |
| 49 | GND | PWR | Ground pin. |
| 50 | DIF_9# | OUT | 0.7V differential Complementary clock output |
| 51 | DIF_9 | OUT | 0.7V differential true clock output |
| 52 | OE9# | IN | Active low input for enabling DIF pair 9. 1 =disable outputs, 0 = enable outputs |
| 53 | DIF_10# | OUT | 0.7V differential Complementary clock output |
| 54 | DIF_10 | OUT | 0.7V differential true clock output |
| 55 | OE10# | IN | Active low input for enabling DIF pair 10. 1 =disable outputs, 0 = enable outputs |
| 56 | GND | PWR | Ground pin. |
| 57 | VDD | PWR | Pow er supply, nominal 3.3V |
| 58 | DIF_11# | OUT | 0.7V differential Complementary clock output |
| 59 | DIF_11 | OUT | 0.7V differential true clock output |
| 60 | OE11# | IN | Active low input for enabling DIF pair 11. 1 =disable outputs, 0 = enable outputs |
| 61 | VDD | PWR | Pow er supply, nominal 3.3V |
| 62 | IREF | ОЛТ | This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value. |
| 63 | AGND | PWR | Analog Ground pin for Core PLL |
| 64 | VDDA | PWR | 3.3V pow er for the PLL core. |

Absolute Maximum Ratings

The absolute maximum ratings are stress ratings only. Stresses greater than those listed below can cause permanent damage to the device. Functional operation of the 9DB1233 at absolute maximum ratings is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|---------------------------|-----------------|----------------------------|---------|-----|----------------|-------|-------|
| 3.3V Core Supply Voltage | VDDA | | | | 4.6 | V | 1,2 |
| 3.3V Logic Supply Voltage | VDD | | | | 4.6 | V | 1,2 |
| Input Low Voltage | V _{IL} | | GND-0.5 | | | V | 1 |
| Input High Voltage | V _{IH} | Except for SMBus interface | | | V_{DD} +0.5V | V | 1 |
| Input High Voltage | VIHSMB | SMBus clock and data pins | | | 5.5V | V | 1 |
| Storage Temperature | Ts | | -65 | | 150 | °C | 1 |
| Junction Temperature | Tj | | | | 125 | °C | 1 |
| Input ESD protection | ESD prot | Human Body Model | 2000 | | | V | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

Electrical Characteristics-Clock Input Parameters

 $T_A = T_{COM}$; Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|---------------------------------------|--------------------|---|-----------------------|-----|------|-------|-------|
| Input High Voltage - DIF_IN | V _{IHDIF} | Differential inputs (single-ended measurement) | 600 | 800 | 1150 | mV | 1 |
| Input Low Voltage - DIF_IN | V _{ILDIF} | Differential inputs (single-ended measurement) | V _{SS} - 300 | 0 | 300 | mV | 1 |
| Input Common Mode Voltage - DIF_IN | V _{COM} | Common Mode Input Voltage | 300 | | 1000 | mV | 1 |
| Input Amplitude - DIF_IN | V _{SWING} | Peak to Peak value | 300 | | 1450 | mV | 1 |
| Input Slew Rate - DIF_IN | dv/dt | Measured differentially | 0.4 | | 8 | V/ns | 1,2 |
| Input Leakage Current | I _{IN} | $V_{IN} = V_{DD}, V_{IN} = GND$ | -5 | | 5 | uA | 1 |
| Input Duty Cycle | d _{tin} | Measurement from differential waveform | 45 | | 55 | % | 1 |
| Input Jitter - Cycle to Cycle | J _{DIFIn} | Differential Measurement | 0 | | 125 | ps | 1 |

¹ Guaranteed by design and characterization, not 100% tested in production.

²Slew rate measured through +/-75mV window centered around differential zero

Electrical Characteristics-Current Consumption

 $T_A = T_{COM}$: Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|--------------------------|-----------------------|--|-----|-----|-----|-------|-------|
| Operating Supply Current | I _{DD3.30P} | All outputs active @100MHz, C_L = Full load; | | 300 | 325 | mA | 1 |
| Powerdown Current | I _{DD3.3PD} | All diff pairs driven | | NA | | mA | 1 |
| r owerdown Carrent | I _{DD3.3PDZ} | All differential pairs tri-stated | | 21 | 30 | mA | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Input/Supply/Common Parameters

 $T_A = T_{COM}$; Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|----------------------------------|-----------------------|---|-----------|--------|-----------------------|--------|-------|
| Ambient Operating | | | | | | | 1 |
| Temperature | Т _{СОМ} | Commmercial range | 0 | | 70 | °C | ' |
| Input High Voltage | V _{IH} | Single-ended inputs, except SMBus, low threshold and tri-level inputs | 2 | | V _{DD} + 0.3 | V | 1 |
| Input Low Voltage | V _{IL} | Single-ended inputs, except SMBus, low threshold and tri-level inputs | GND - 0.3 | | 0.8 | V | 1 |
| | I _{IN} | Single-ended inputs, V_{IN} = GND, V_{IN} = VDD | -5 | | 5 | uA | 1 |
| Input Current | I _{INP} | Single-ended inputs V _{IN} = 0 V; Inputs with internal pull-up resistors V _{IN} = VDD; Inputs with internal pull-down resistors | -200 | | 200 | uA | 1 |
| Innut Fragmanau | F _{iby p} | V _{DD} = 3.3 V, Bypass mode | 10 | | 166 | MHz | 2 |
| Input Frequency | F _{ipll} | V _{DD} = 3.3 V, 100MHz PLL mode | 90 | 100.00 | 110 | MHz | 2 |
| Pin Inductance | L _{pin} | | | | 7 | nH | 1 |
| | C _{IN} | Logic Inputs, except DIF_IN | 1.5 | | 5 | pF | 1 |
| Capacitance | C _{INDIF_IN} | DIF_IN differential clock inputs | 1.5 | | 5 | pF | 1,4 |
| | C _{OUT} | Output pin capacitance | | | 6 | pF | 1 |
| Clk Stabilization | T _{STAB} | From V_{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock | | | 1.8 | ms | 1,2 |
| Input SS Modulation Frequency | f _{MODIN} | Allowable Frequency (Triangular Modulation) | 30 | | 33 | kHz | 1 |
| OE# Latency | t _{LATOE#} | DIF start after OE# assertion DIF stop after OE# deassertion | 4 | | 12 | cycles | 1,3 |
| Tdrive_PD# | t _{DRVPD} | DIF output enable after PD# de-assertion | | | 300 | us | 1,3 |
| Tfall | t _F | Fall time of control inputs | | | 5 | ns | 1,2 |
| Trise | t _R | Rise time of control inputs | | | 5 | ns | 1,2 |
| SMBus Input Low Voltage | VILSMB | | | | 0.8 | V | 1 |
| SMBus Input High Voltage | VIHSMB | | 2.1 | | V _{DDSMB} | V | 1 |
| SMBus Output Low Voltage | V _{OLSMB} | @ I _{PULLUP} | | | 0.4 | V | 1 |
| SMBus Sink Current | I _{PULLUP} | @ V _{OL} | 4 | | | mA | 1 |
| Nominal Bus Voltage | V _{DDSMB} | 3V to 5V +/- 10% | 2.7 | | 5.5 | V | 1 |
| SCLK/SDATA Rise Time | t _{RSMB} | (Max VIL - 0.15) to (Min VIH + 0.15) | | | 1000 | ns | 1 |
| SCLK/SDATA Fall Time | t _{FSMB} | (Min VIH + 0.15) to (Max VIL - 0.15) | | | 300 | ns | 1 |
| SMBus Operating Frequency | f _{MAXSMB} | Maximum SMBus operating frequency | | | 100 | kHz | 1,5 |

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴DIF_IN input

⁵The differential input clock must be running for the SMBus to be active

Electrical Characteristics-DIF 0.7V Current Mode Differential Outputs

 $T_A = T_{COM}$; Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|------------------------|------------------|--|------|-----|------|-------|---------|
| Slew rate | Trf | Scope averaging on | 1 | 2.4 | 4 | V/ns | 1, 2, 3 |
| Slew rate matching | Δ Trf | Slew rate matching, Scope averaging on | | 9.1 | 20 | % | 1, 2, 4 |
| Voltage High | VHigh | Statistical measurement on single-ended signal using oscilloscope math function. (Scope | 660 | 825 | 850 | mV | 1 |
| Voltage Low | VLow | averaging on) | -150 | 0 | 150 | | 1 |
| Max Voltage | Vmax | Measurement on single ended signal using | | 859 | 1150 | mV | 1 |
| Min Voltage | Vmin | absolute value. (Scope averaging off) | -300 | | | IIIV | 1 |
| Vswing | Vswing | Scope averaging off | 300 | | | mV | 1, 2 |
| Crossing Voltage (abs) | Vcross_abs | Scope averaging off | 250 | | 550 | mV | 1, 5 |
| Crossing Voltage (var) | Δ -Vcross | Scope averaging off | | | 140 | mV | 1, 6 |

¹Guaranteed by design and characterization, not 100% tested in production. IREF = VDD/($3xR_R$). For R_R = 475 Ω (1%), I_{REF} = 2.32mA. I_{OH} = 6 x I_{REF} and V_{OH} = 0.7V at Z_O = 50 Ω (100 Ω differential impedance).

² Measured from differential waveform.

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a ±150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a ±75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of V_cross_min/max (V_cross absolute) allowed. The intent is to limit Vcross induced modulation by setting V cross delta to be smaller than V cross absolute.

Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

 $T_A = T_{COM}$: Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|---|-----------------------|--|------|-----|------|-------|-------|
| PLL Bandwidth | BW | -3dB point in High BW Mode | 2 | 3 | 4 | MHz | 1 |
| F EL Dandwidth | BW | -3dB point in Low BW Mode | 0.7 | 1 | 1.4 | MHz | 1 |
| PLL Jitter Peaking | t _{JPEAK} | Peak Pass band Gain | | 1.5 | 2 | dB | 1 |
| Duty Cycle | t _{DC} | Measured differentially, PLL Mode | 45 | | 55 | % | 1 |
| Duty Cycle Distortion t _{DCD} | | Measured differentially, Bypass Mode at 100MHz | -2 | 0 | 2 | % | 1,4 |
| Skew, Input to Output | t _{pdBYP} | Bypass Mode, $V_T = 50\%$ | 2500 | | 4500 | ps | 1 |
| Skew, input to Output | t _{pdPLL} | PLL Mode $V_T = 50\%$ | -250 | | 250 | ps | 1 |
| Skew, Output to Output t _{sk3} | | V _T = 50% | | 47 | 50 | ps | 1 |
| Jitter, Cycle to cycle | t. | PLL mode | | 25 | 50 | ps | 1,3 |
| | t _{jcyc-cyc} | Additive Jitter in Bypass Mode | | 12 | 50 | ps | 1,3 |

¹Guaranteed by design and characterization, not 100% tested in production.

 2 I_{REF} = V_{DD}/(3xR_R). For R_R = 475 Ω (1%), I_{REF} = 2.32mA. I_{OH} = 6 x I_{REF} and V_{OH} = 0.7V at Z_O = 50 Ω .

³ Measured from differential waveform.

⁴ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

Electrical Characteristics-PCIe Phase Jitter Parameters

 $T_A = T_{COM}$; Supply voltage VDD = 3.3V ±5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | Notes |
|------------------------|------------------------|--|-----|------|-----|-------------|---------------|
| | t _{jphPCIeG1} | PCle Gen 1 | | 34 | 86 | ps (p-p) | 1,2,3 |
| | + | PCle Gen 2 Lo Band 10kHz < f < 1.5MHz | | 1.1 | 3 | ps (rms) | 1,2 |
| Phase Jitter, PLL Mode | ljphPCIeG2 | PCle Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | 2.2 | 3.1 | ps (rms) | 1,2 |
| | t _{jphPCIeG3} | PCle Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz) | | 0.4 | 1 | ps (rms) | 1,2,4,5 |
| | t _{jphPCIeG1} | PCle Gen 1 | | 2 | 5 | ps (p-p) | 1,2,3 |
| Additive Phase Jitter, | t | PCle Gen 2 Lo Band 10kHz < f < 1.5MHz | | 0.5 | 0.6 | ps (rms) | 1,2,6 |
| Bypass Mode | t _{jphPCIeG2} | PCle Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | 0.8 | 1 | ps (rms) | 1,2,6 |
| | t _{jphPCIeG3} | PCle Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz) | | 0.35 | 0.5 | ps (rms) | 1,2,4,5, 6 |

¹ Applies to all outputs when driven by 932SQ420DGLF or equivalent.

² See http://www.pcisig.com for complete specs.

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk at 1M cycles for a BER of 1⁻¹².

⁴ Subject to final ratification by PCI SIG.

⁵ Calculated from Intel-supplied Clock Jitter Tool v 1.6.4.

⁶ For RMS figures, additive jitter is calculated by solving the following equation: (Additive jitter) = SQRT{(total jitter)^2 - (input jitter)^2}.

Clock Periods Differential Outputs with Spread Spectrum Enabled

| | urement ndow | 1 Clock | 1us | 0.1s | 0.1s | 0.1s | 1us | 1 Clock | | |
|------|-----------------|---------------------|-----------------------|----------------------|----------|----------------------|-----------------------|----------|-------|-------|
| Syı | mbol | Lg- | -SSC | -ppm error | 0ppm | + ppm error | +SSC | Lg+ | | |
| | | Absolute Period | Short-term Average | Long-Term Average | Period | Long-Term Average | Short-term Average | Period | | |
| Defi | inition | Minimum Absolute | Minimum Absolute | Minim um Absolute | Nominal | Maximum | Maximum | Maximum | | |
| | | Period | Period | Period | | | | | Units | Notes |
| DIF | DIF 100 | 9.87400 | 9.99900 | 9.99900 | 10.00000 | 10.00100 | 10.05130 | 10.17630 | ns | 1,2,3 |

Clock Periods Differential Outputs with Spread Spectrum Disabled

| Measu | urement | | | | | | | | | |
|-------|---------|----------------|------------|--------------------|----------|------------------------------------|---------|-------------------|-------|-------|
| Wir | ndow | 1 Clock | 1us | 0.1s | 0.1s | 0.1s | 1us | 1 Clock | | |
| Sy | mbol | Lg- | -SSC | -ppm error | 0ppm | + ppm error | +SSC | Lg+ | | |
| | | Absolute | Short-term | Long-Term Period I | | Period Long-Term Short-term Period | | Short-term Pariod | | |
| | | Period | Average | Average | renou | Average | Average | renou | | |
| Defi | inition | Minimum | Minimum | Minimum | | | | | | |
| | | Absolute Absol | | Absolute | Nominal | Maximum | Maximum | Maximum | | |
| | | Period | Period | Period | | | | | Units | Notes |
| DIF | DIF 100 | 9.87400 | | 9.99900 | 10.00000 | 10.00100 | | 10.17630 | ns | 1,2,3 |

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK410B+/CK420BQ accuracy requirements. The 9DB1233 itself does not contribute to ppm error.

³ Driven by SRC output of main clock, PLL or Bypass mode.

Terminations

| DIF Reference Cloc | DIF Reference Clock | | | | | | | |
|---|---------------------|------|--------|--|--|--|--|--|
| Common Recommendations for Differential Routing | Dimension or Value | Unit | Figure | | | | | |
| L1 length, route as non-coupled 50ohm trace | 0.5 max | inch | 1 | | | | | |
| L2 length, route as non-coupled 50ohm trace | 0.2 max | inch | 1 | | | | | |
| L3 length, route as non-coupled 50ohm trace | 0.2 max | inch | 1 | | | | | |
| Rs | 33 | ohm | 1 | | | | | |
| Rt | 49.9 | ohm | 1 | | | | | |

| Down Device Differential Routing | | | |
|--|---------------------|------|---|
| L4 length, route as coupled microstrip 100ohm differential trace | 2 min to 16 max | inch | 1 |
| L4 length, route as coupled stripline 100ohm differential trace | 1.8 min to 14.4 max | inch | 1 |

| Differential Routing to PCI Express Connector | | | |
|--|-----------------------|------|---|
| L4 length, route as coupled microstrip 100ohm differential trace | 0.25 to 14 max | inch | 2 |
| L4 length, route as coupled stripline 100ohm differential trace | 0.225 min to 12.6 max | inch | 2 |





| | Alternative Termination for LVDS and other Common Differential Signals (figure 3) | | | | | | | | |
|-------|---|------|----|------|------|-----|--------------------------------|--|--|
| Vdiff | Vp-p | Vcm | R1 | R2 | R3 | R4 | Note | | |
| 0.45v | 0.22v | 1.08 | 33 | 150 | 100 | 100 | | | |
| 0.58 | 0.28 | 0.6 | 33 | 78.7 | 137 | 100 | | | |
| 0.80 | 0.40 | 0.6 | 33 | 78.7 | none | 100 | ICS874003i-02 input compatible | | |
| 0.60 | 0.3 | 1.2 | 33 | 174 | 140 | 100 | Standard LVDS | | |

R1a = R1b = R1

R2a = R2b = R2



| Termination for Cable AC Coupled Application (figure 4) | | | | | | | |
|---|-------------|------|--|--|--|--|--|
| Component | Value | Note | | | | | |
| R5a, R5b | 8.2K 5% | | | | | | |
| R6a, R6b | 1K 5% | | | | | | |
| Сс | 0.1 µF | | | | | | |
| Vcm | 0.350 volts | | | | | | |



General SMBus Serial Interface Information

How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a stop bit

| | Index Block Write Operation | | | | | | | |
|-----------|-----------------------------|--------|----------------------|--|--|--|--|--|
| Controll | er (Host) | | IDT (Slave/Receiver) | | | | | |
| Т | starT bit | | | | | | | |
| Slave A | Slave Address | | | | | | | |
| WR | WRite | | | | | | | |
| | | | ACK | | | | | |
| Beginning | g Byte = N | | | | | | | |
| | | | ACK | | | | | |
| Data Byte | Count = X | | | | | | | |
| | | | ACK | | | | | |
| Beginnin | g Byte N | | | | | | | |
| | | | ACK | | | | | |
| 0 | | | | | | | | |
| 0 | | X Byte | 0 | | | | | |
| 0 | | fe | 0 | | | | | |
| | | | 0 | | | | | |
| Byte N | + X - 1 | | | | | | | |
| | | | ACK | | | | | |
| Р | stoP bit | | | | | | | |

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

| | Index Block | Read C | Dperation |
|-----|-----------------|--------|----------------------|
| Co | ntroller (Host) | | IDT (Slave/Receiver) |
| Т | starT bit | - | |
| S | ave Address | | |
| WR | WRite | | |
| | | | ACK |
| Beg | inning Byte = N | | |
| | | | ACK |
| RT | Repeat starT | | |
| | ave Address | | |
| RD | ReaD | | |
| | | | ACK |
| | | | |
| | · | | Data Byte Count=X |
| | ACK | | |
| | | | Beginning Byte N |
| | ACK | | |
| | | e | 0 |
| | 0 | X Byte | 0 |
| | 0 | × | 0 |
| | 0 | | |
| | 1 | | Byte N + X - 1 |
| N | Not acknowledge | | |
| Р | stoP bit | | |

SMBus Table: Frequency Select Register

| Byt | e 0 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|------------|-------|-------------|-----------------------------------|------|----------|----------|---------|
| Bit 7 | - HIGH_BW# | | HIGH_BW# | High or Low BW | | High BW | Low BW | Latch |
| Bit 6 | | - | BYPASS#/PLL | Bypass (non-PLL Mode) or PLL Mode | RW | Bypass | PLL | Latch |
| Bit 5 | | - | Reserved | Reserved | RW | Rese | Reserved | |
| Bit 4 | | - | Reserved | Reserved | RW | Reserved | | Х |
| Bit 3 | | - | Reserved | Reserved | RW | Res | erved | Х |
| Bit 2 | | - | Reserved | Reserved | RW | Res | erved | 1 |
| Bit 1 | | - | Reserved | Reserved | RW | Reserved | | 0 |
| Bit 0 | | - | Reserved | Reserved | RW | Reserved | | 1 |

SMBus Table: Output Control Register

| Byt | e 1 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----|-------|-------|---------------------------------|------|---------|--------|---------|
| Bit 7 | 43 | 3,42 | DIF_7 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 6 | 38 | 3,37 | DIF_6 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 5 | 27 | 7,28 | DIF_5 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 4 | 22 | 2,23 | DIF_4 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 3 | 19 | 9,20 | DIF_3 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 2 | 14 | l,15 | DIF_2 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 1 | 11 | ,12 | DIF_1 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 0 | 6 | ô,7 | DIF_0 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |

SMBus Table: Output Control Register

| Byte | e 2 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----|-------|----------|---------------------------------|------|---------|--------|---------|
| Bit 7 | | - | Reserved | Reserved | RW | Res | erved | 0 |
| Bit 6 | | - | Reserved | Reserved | RW | Res | erved | 0 |
| Bit 5 | | - | Reserved | Reserved | RW | Res | erved | 0 |
| Bit 4 | | - | Reserved | Reserved | RW | Res | erved | 0 |
| Bit 3 | 58 | 3,59 | DIF_11 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 2 | 53 | 3,54 | DIF_10 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 1 | 50 |),51 | DIF_9 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |
| Bit 0 | 45 | 5,46 | DIF_8 | Output Control (Disable = Hi-Z) | RW | Disable | Enable | 1 |

SMBus Table: Output Enable Readback

| Byt | e 3 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----|-------|------|------------------|------|---------|----------|---------|
| Bit 7 | 43 | 3,42 | OE7# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 6 | 38 | 3,37 | OE6# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 5 | 27 | 7,28 | OE5# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 4 | 22 | 2,23 | OE4# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 3 | 19 | 9,20 | OE3# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 2 | 14 | 1,15 | OE2# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 1 | 11 | 1,12 | OE1# | OE# Pin Readback | R | Enabled | Disabled | Х |
| Bit 0 | 6 | 6,7 | OE0# | OE# Pin Readback | R | Enabled | Disabled | Х |

SMBus Table: Output Enable Readback

| Byt | Byte 4 Pin # Name | | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-------------------|------|----------|---------------------------------|------|----------|----------|---------|
| Bit 7 | | - | Reserved | Reserved | R | Res | erved | 0 |
| Bit 6 | | - | Reserved | Reserved | R | Res | erved | 0 |
| Bit 5 | | - | Reserved | Reserved | R | Reserved | | 0 |
| Bit 4 | | - | Reserved | Reserved | R | Reserved | | 0 |
| Bit 3 | 58 | 3,59 | OE11# | Output Control (Disable = Hi-Z) | R | Enabled | Disabled | Х |
| Bit 2 | 53 | 3,54 | OE10# | Output Control (Disable = Hi-Z) | R | Enabled | Disabled | Х |
| Bit 1 | 50 |),51 | OE9# | Output Control (Disable = Hi-Z) | R | Enabled | Disabled | Х |
| Bit 0 | 45 | 5,46 | OE8# | Output Control (Disable = Hi-Z) | R | Enabled | Disabled | Х |

Note: For an output to be enabled, BOTH the Output Enable Bit and the OE# pin must be enabled. This means that the Output Enable Bit must be '1' and the corresponding OE# pin must be '0'.

SMBus Table: Vendor & Revision ID Register

| Byte | e 5 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----|-------|------|--------------------|------|---|---|---------|
| Bit 7 | | - | RID3 | | R | - | - | 0 |
| Bit 6 | | - | RID2 | VENDOR ID | R | - | - | 0 |
| Bit 5 | | - | RID1 | | R | - | - | 0 |
| Bit 4 | | - | RID0 | | R | - | - | 1 |
| Bit 3 | | - | VID3 | | R | - | - | 0 |
| Bit 2 | | - | VID2 | REVISION ID | R | - | - | 0 |
| Bit 1 | | - | VID1 | NEVISION ID | R | - | - | 1 |
| Bit 0 | | - | VID0 | | R | - | - | 0 |

SMBus Table: DEVICE ID

| Byte | e 6 | Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----|-------|------|-------------------|------|---|-----------|---------|
| Bit 7 | | - | | Device ID 7 (MSB) | RW | | | 0 |
| Bit 6 | | - | | Device ID 6 | RW | | | 0 |
| Bit 5 | | - | | Device ID 5 | RW | | | 0 |
| Bit 4 | | - | | Device ID 4 | RW | | is 0C Hex | 0 |
| Bit 3 | | - | | Device ID 3 | RW | | | 1 |
| Bit 2 | | - | | Device ID 2 | RW | | | 1 |
| Bit 1 | | - | | Device ID 1 | RW |] | | 0 |
| Bit 0 | | - | | Device ID 0 | RW | | | 0 |

SMBus Table: Byte Count Register

| Byte | e 7 Pin # | Name | Control Function | Туре | 0 | 1 | Default |
|-------|-----------|------|---|------|---|---|---------|
| Bit 7 | - | BC7 | | RW | - | - | 0 |
| Bit 6 | - | BC6 | | RW | - | - | 0 |
| Bit 5 | - | BC5 | | RW | - | - | 0 |
| Bit 4 | - | BC4 | Writing to this register configures how | RW | - | - | 0 |
| Bit 3 | - | BC3 | many bytes will be read back. | RW | - | - | 0 |
| Bit 2 | - | BC2 | | RW | - | - | 1 |
| Bit 1 | - | BC1 | | RW | - | - | 1 |
| Bit 0 | - | BC0 | | RW | - | - | 1 |

Package Outline Drawings

The package outline drawings are appended at the end of this document and are accessible from the link below. The package information is the most current data available.

www.idt.com/us/en/document/psc/64-tssop-package-outline-drawing-610-mm-body-050mm-pitch-pag64d1

Marking Diagram



- Line 1 indicates the lot number.
- Line 2 indicates the following:
 - "YY" is the last two digits of the year; "WW" is the work week number when the part was assembled.
- Line 3 indicates the part number.

Ordering Information

| Orderable Part Number | Package | Carrier Type | Temperature |
|-----------------------|-----------------------|---------------|-------------|
| 9DB1233AGLF | 6.10mm body, 64-TSSOP | Tubes | 0° to +70°C |
| 9DB1233AGLFT | 6.10mm body, 64-TSSOP | Tape and Reel | 0° to +70°C |

"LF" after the package code denotes Pb-free configuration, RoHS compliant.

"A" is the device revision designator (will not correlate with the datasheet revision).

Revision History

| Revision Date | Description of Change |
|-------------------------------|---|
| December 17, 2019 | Updated Byte 5 and 6.Converted datasheet to updated template. |
| November 14, 2010 | Corrected Additive phase jitter calculation in PCIe phase jitter table. Added footnotes 5 and 6 to this table. |
| July 12, 2010 | Changed 'PWD' to 'Default' in SMBus. Updated Electrical Tables. Move to Final. |
| July 7, 2010 Initial release. | |

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64-TSSOP Package Outline Drawing

6.10 mm Body 0.50mm Pitch PAG64D1, PSC-4767-01, Rev 00, Page 1





64-TSSOP Package Outline Drawing

6.10 mm Body 0.50mm Pitch PAG64D1, PSC-4767-01, Rev 00, Page 2

