

Product Introduction

Concept

The RH850/F1x microcontroller focus on low power and low cost for the body application.

The device is a high-end microcontroller with a 32-bit RH850G3K core for car body control. The features of this device are the low power consumption, the high processing power and the variable peripheral function.

In particular, Low power consumption is achieved by supporting wide stand-by control and the power supply insulation using the port polling, stand-by control of AD conversion and LIN communication which considered body control application.

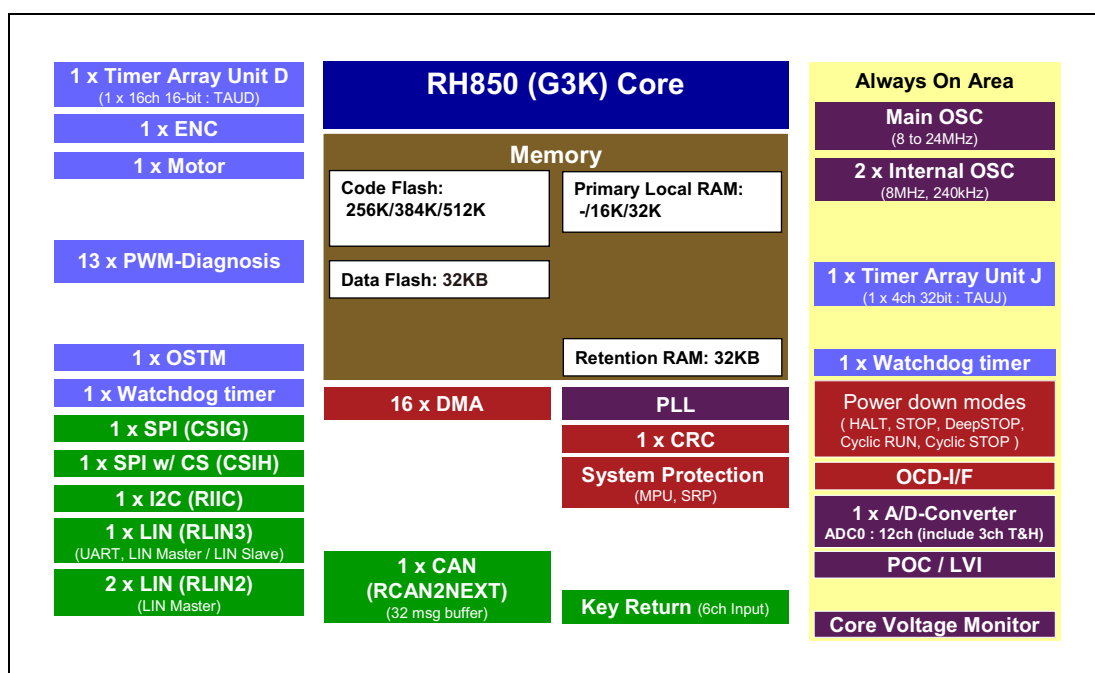
This device supports the security and safety function. And the local area network has been strengthened by upgrading each module of CAN, LIN master/slave.

Function Overview

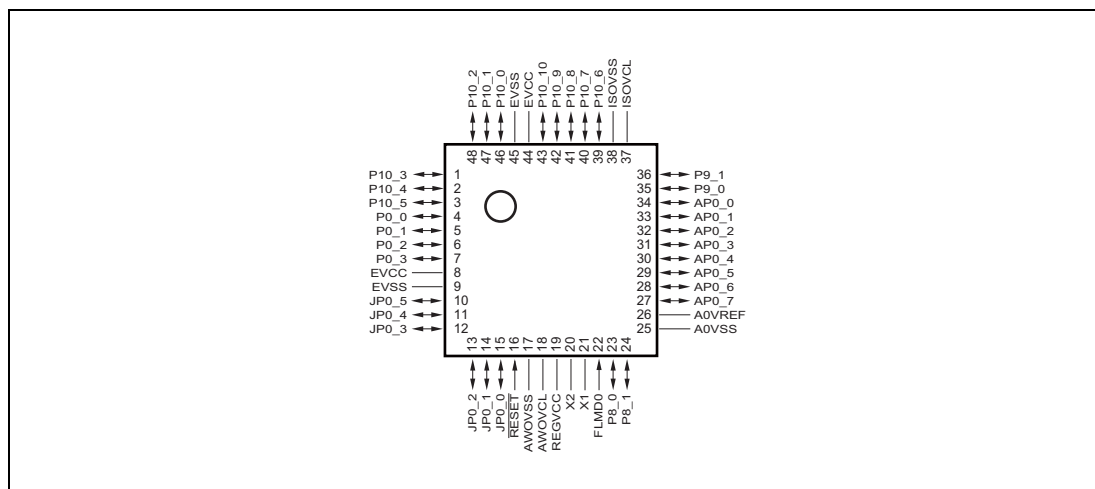
- 32bit single core CPU (V850E3v5-S architecture class)
- The capacity of Code Flash: up to 512 KB
- The capacity of Data Flash: 32 KB
- The capacity of RAM: up to 64 KB
- DMA function
- System protection
- POC/LVI, CVM
- MainOSC which is available for a wide range frequency (8 MHz to 24 MHz)
- External interrupt: 8
- Low Power Sampler watching an outside event in standby mode
- Timer Array Unit D: 1 ch
- Timer Array Unit J: 1 ch
- PWM-Diagnosis function: 13 ch
- Encoder Timer: 1 ch
- Motor control: 1 ch
- OS Timer: 1 ch
- Watchdog Timer: 2 ch
- Asynchronous Serial Interface, LIN Master/Slave Controller: 1 ch
- LIN Master Controller: 2 ch
- CAN Controller: up to 1 ch
- Clocked Serial Interface G: 1 ch

- Clocked Serial Interface H: 1 ch
- Data CRC: 1 ch
- A/D Converter:
 - ADCA0In w/ T&H: 3 ch
 - ADCA0In w/o T&H: 5 ch
 - ADCA0InS: 4 ch
- Key Return: 6 ch

Block Diagram



Pin Map



Product Lineup

Product	Max CPU Frequency	ICUSB	Code Flash	Data Flash	Local RAM (Primary)	Local RAM (Secondary)	Retention RAM (RRAM)	Operationing Temperature (Ta)	
								–40°C to +105°C ^{Caution}	–40°C to +125°C ^{Caution}
ECO	80 MHz	No	256 KB	32 KB	0 KB	0 KB	32 KB	R7F7010083AFP	R7F7010084AFP
			384 KB		16 KB			R7F7010093AFP	R7F7010094AFP
			512 KB		32 KB			R7F7010103AFP	R7F7010104AFP

Caution: It must be ensured that the junction temperature in the Ta range remains below Tj (**Section 1.2.4, Temperature Condition**) and does not exceed its limit under application conditions (thermal resistance, power supply current, peripheral current (if not included in power supply current), port output current and injection current).

Section 1 Electrical Specifications

1.1 Overview

The electrical spec of this device is guaranteed by the following operational condition. But, this condition is different depends on each characteristics, so refer to each chapter for more detail.

1.1.1 Pin Groups

Symbol	Pin Group Supplied by	Related Pins/Ports
PgR	REGVCC, AWOVSS	X1, X2
PgE	EVCC, EVSS	Related ports: JP0, P0, P8, P9, P10 Related pins: RESET, FLMD0
PgA0	A0VREF, A0VSS	Related port: AP0

1.1.2 General Measurement Conditions

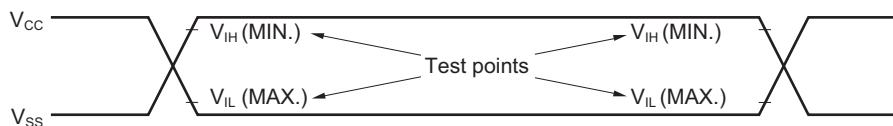
1.1.2.1 Common Conditions

- Power supply
 - REGVCC = EVCC = VPOC*¹ to 5.5 V
 - A0VREF = 3.0 V to 5.5 V
 - AWOVSS = ISOVSS = EVSS = A0VSS = 0 V
- Capacitance of the internal regulator
 - CAWOVCL: 0.1 μ F $\pm$ 30%
 - CISOVCL: 0.1 μ F $\pm$ 30%
- Operating temperature
 - Ta:
 - 40 to (depend on the product) $^{\circ}$ C
 - Tj:
 - R7F7010xx3AFP : -40 to 130° C
 - R7F7010xx4AFP : -40 to 150° C
- Load conditions
 - CL = 30 pF

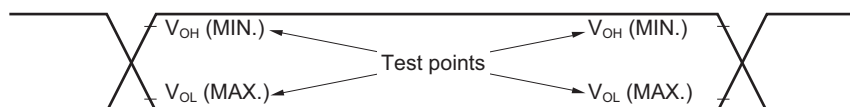
Note 1. “VPOC” means POC (power on clear) detection voltage. For more detail, refer to **Section 1.8.2, Voltage Detector (POC, LVI, VLVI, CVM) Characteristics.**

1.1.2.2 AC Characteristic Measurement Condition

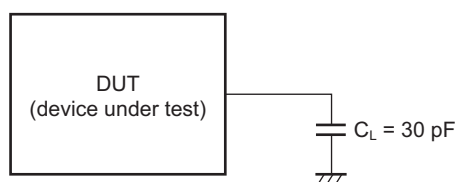
(1) AC test input measurement points



(2) AC test output measurement points



(3) Load conditions



CAUTION

If the load capacitance exceeds 30pF due to the circuit configuration, it is recommended to insert a buffer in order to reduce capacitance till less than 30pF.

1.2 Absolute Maximum Ratings

CAUTIONS

1. Do not directly connect outputs (or input/outputs) to each other, power supply and ground.
2. Even momentarily exceeding the absolute maximum rating for just one item creates a threat of failure in the reliability of the products. That is, the absolute maximum ratings are the levels that raise a threat of physical damage to the products. Be sure to use the products only under conditions that do not exceed the ratings. The quality and normal operation of the product are guaranteed under the standards and conditions given as DC and AC characteristics.
3. When designing an external circuit ensure that the connections don't conflict with the port state of this device.

1.2.1 Supply Voltages

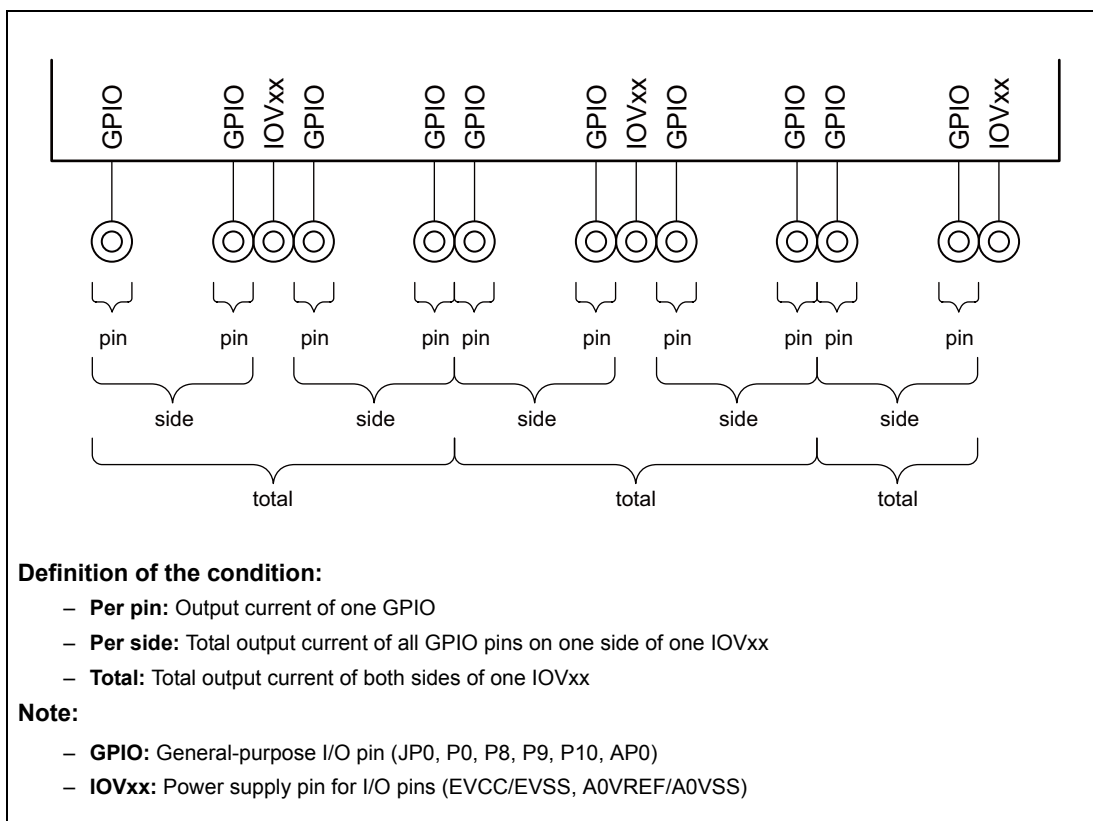
Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
System supply voltage	REGVCC		-0.5		6.5	V
	AWOVSS		-0.5		0.5	V
	ISOVSS		-0.5		0.5	V
Port supply voltage	EVCC		-0.5		6.5	V
	EVSS		-0.5		0.5	V
A/D-converter supply voltage	A0VREF		-0.5		6.5	V
	A0VSS		-0.5		0.5	V

1.2.2 Port Voltages

Item	Pin Group*1	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input voltage	PgR	VI		-0.5		REGVCC + 0.5 (Do not exceed 6.5 V)	V
	PgE			-0.5		EVCC + 0.5 (Do not exceed 6.5 V)	V
	PgA0			-0.5		A0VREF + 0.5 (Do not exceed 6.5 V)	V

Note 1. The characteristics of the alternative-function pins are the same as those of the port pins unless otherwise specified.

1.2.3 Port Current



Item	Symbol	Pin Group	Condition	MIN.	TYP.	MAX.	Unit
High-level output current	IOH	PgE	Per pin			–10	mA
			Per side (Total of P9_0, P9_1, P10_6 to P10_10)			–48	mA
			Per side (Total of P10_0 to P10_2)			–30	mA
			Per side (Total of P0_0 to P0_3, P10_3 to P10_5)			–48	mA
			Per side (Total of JP0_0 to JP0_5, P8_0, P8_1)			–48	mA
			Total (EVCC)			–60	mA
		PgA0	Per pin			–10	mA
			Total (A0VREF)			–48	mA
Low-level output current	IOL	PgE	Per pin			10	mA
			Per side (Total of P9_0, P9_1, P10_6 to P10_10)			48	mA
			Per side (Total of P10_0 to P10_2)			30	mA
			Per side (Total of P0_0 to P0_3, P10_3 to P10_5)			48	mA
			Per side (Total of JP0_0 to JP0_5, P8_0, P8_1)			48	mA
			Total (EVSS)			60	mA
		PgA0	Per pin			10	mA
			Total (A0VSS)			48	mA

1.2.4 Temperature Condition

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Storage temperature	Tstg		−55		170	°C
Junction temperature	Tj	R7F7010xx3AFP	−40		130	°C
		R7F7010xx4AFP	−40		150	°C

xx = 08, 09, 10

Regarding operation temperature of each product, refer to “**Product Lineup**”.

1.3 Capacitance

Condition: REGVCC = EVCC = A0VREF = AWOVSS = ISOVSS = EVSS = A0VSS = 0 V, Ta = 25°C

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input capacitance	CI*1	f = 1 MHz			10	pF
Input/output capacitance	CIO*2	0 V for non measurement pins			10	pF

Note 1. CI: Capacitance between the input pin and ground

Note 2. CIO: Capacitance between the input/output pin and ground

1.4 Operational Condition

ECO Line

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
CPU clock frequency	f _{CPUCLK}				80	MHz
Peripheral clock (clock domain) frequency* ¹	f _{CKSCLK_AWDTA}	for WDTA0			240* ²	kHz
	f _{CKSCLK_ATAUJ}	for TAUJ0			40	MHz
	f _{CKSCLK_AADCA}	for ADCA0			40	MHz
	f _{CKSCLK_AFOUT}	for CSCXFOUT			24	MHz
	f _{CKSCLK_IPERI1}	for TAUD0			80	MHz
		for ENCA0				
		for TAPA				
		for PIC				
	f _{CKSCLK_IPERI2}	for PWM-diag			40	MHz
	f _{CKSCLK_ILIN}	for RLIN2			40	MHz
		for RLIN3				
	f _{CKSCLK_ICAN}	for RS-CAN (pclk)			80	MHz
	f _{CKSCLK_ICANOSC}	for RS-CAN (clk_xincan)			24	MHz
	f _{CKSCLK_ICSI}	for CSIG			80	MHz
		for CSIH				
	f _{RL}	for WDTA1			240* ²	kHz
	f _{CPUCLK2}	for OSTM			40	MHz
		for RIIC				
	f _{EMCLK}	for LPS			8	MHz
Power supply	REGVCC	REGVCC = EVCC	VPOC* ³		5.5	V
	EVCC					
	A0VREF		3.0		5.5	V

Note 1. For clock specification of peripherals, refer to *Section 10, Clock Controller*, in the *RH850/F1L Group User's Manual: Hardware*.

Note 2. This frequency depends on the internal oscillator (LS IntOSC).

Note 3. "VPOC" means POC (power on clear) detection voltage (typ. 2.95 V@at power-on, typ. 2.9 V@after (except) power-on). For detail, refer to **Section 1.8.2, Voltage Detector (POC, LVI, VLVI, CVM) Characteristics**.

In addition, the guaranteed operation in DC characteristic.

And AC characteristic is guaranteed when more than 3.0 V.

When the power supply voltage is VPOC to 3.0 V, the device does not malfunction.

1.5 Oscillator Characteristics

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AVOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
MainOSC frequency	f_{MOSC}	Crystal/Ceramic	8		24	MHz
MainOSC Current consumption	I_{MOSC}	After stabilization		1.9*2	2.3*2	mA
MainOSC oscillation start point	V_{MOSCSP}	Crystal/Ceramic	VPOC			V
MainOSC oscillation operating point	V_{MOSCOP}			$0.5 \times \text{REGVCC}^{*2}$		V
MainOSC oscillation amplitude	V_{MOSCAMP}	Crystal/Ceramic	$0.4 \times \text{REGVCC} - 0.2^{*2}$			V
MainOSC oscillation stabilization time	t_{MSTB}			*1		ms

Note 1. Oscillator stabilization time is time until being set ("1") in MOSCS.MOSCCLKACT bit after MOSCE.MOSCENTRG bit is written "1", and depends on the setting value of MOSCST register. Please decide appropriate oscillation stabilization time by matching test with resonator and oscillation circuit.

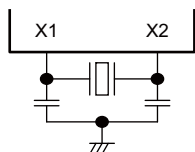
Note 2. This is reference value.

CAUTION

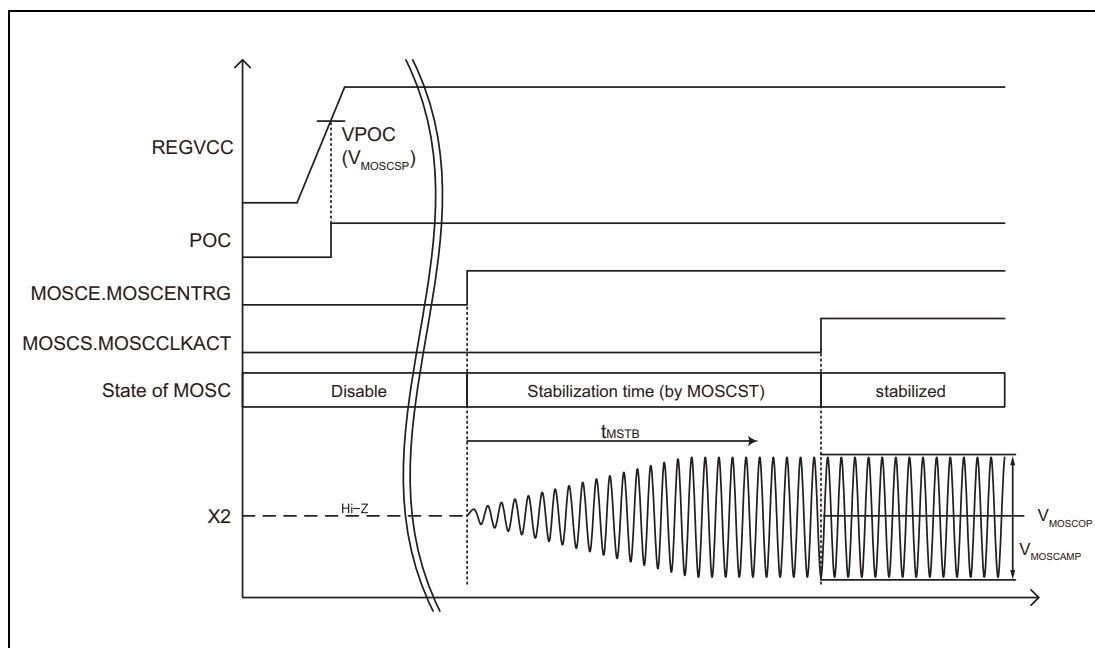
The oscillation stabilization time differs according the matching with the external resonator circuit. It is recommended to determine the oscillation stabilization time by an oscillator matching test.

NOTE

Recommended oscillator circuit is shown below.



MainOSC



1.6 Internal Oscillator Characteristics

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
LS IntOSC frequency	f_{RL}		220.8	240	259.2	kHz
HS IntOSC frequency	f_{RH}		7.36	8	8.64	MHz
		Ta = 25°C	7.6	8	8.4	MHz
HS IntOSC Current consumption	I_{RH}	After stabilization			25* ¹	μ A
HS IntOSC oscillation stabilization time	t_{RHSTB}				54.4	μ s

Note 1. This is reference value.

1.7 PLL Characteristics

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input frequency	f_{PLLCLK}		8		24	MHz
Output frequency (PLL for CPU)	f_{CPLL}	ECO line	25		80	MHz
Output frequency (PLL for Peripheral)	f_{PPLL}		25		80	MHz
Output period jitter* ¹ (PLL for CPU)	t_{CPJ}	PLLC.OUTBSEL = 0	par = 4* ²	-150	150	ps
			par = 6* ² (f_{CPLL} = 80 MHz)	-150	150	ps
			par = 6* ² (f_{CPLL} < 80 MHz)	-200	200	ps
			par = 8* ²	-250	250	ps
			par = 16* ²	-300	300	ps
Output period jitter* ¹ (PLL for Peripheral)	t_{PPJ}		par = 4* ²	-150	150	ps
			par = 6* ² (f_{PPLL} = 80 MHz)	-150	150	ps
			par = 6* ² (f_{PPLL} < 80 MHz)	-200	200	ps
			par = 8* ²	-250	250	ps
			par = 16* ²	-300	300	ps
Long term jitter* ¹ (Both PLL for CPU and PLL for Peripheral)	t_{LTJ}	term = 1 μ s	-500		500	ps
		term = 10 μ s	-1		1	ns
		term = 20 μ s	-2		2	ns
Lock time* ³	t_{LCKP}		104	112.3	122.1	μ s

Note 1. This is reference value.

Note 2. "par" is set by PA[2:0] bit of PLLC register.

Note 3. Lock time is time until being set ("1") in PLLS.PLLCLKACT bit after PLLE.PLLENTRG bit is written "1".

1.8 Power Management Characteristics

1.8.1 Regulator Characteristics

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 Ta = -40 to (depend on the product) °C, CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input voltage	REGVCC		VPOC* ¹		5.5	V
Normal operation voltage	V _{OP}	AWOVCL pin, ISOVCL pin	1.10	1.25	1.35	V
Limited operation voltage	V _{LOP}	AWOVCL pin, ISOVCL pin	1.35		1.43* ³	V
Regulator output voltage	V _{RO}	AWOVCL pin, ISOVCL pin	1.15	1.25	1.35	V
Output voltage	AWOVCL	AWOVCL pin	1.1	1.25	1.35	V
	ISOVCL	ISOVCL pin	1.1	1.25	1.35	V
Capacitance	CAWOVCL	AWOVCL pin	0.07	0.10	0.13	μF
	CISOVCL	ISOVCL pin	0.07	0.10	0.13	μF
Equivalent series resistance for load capacitance	RVRAWO	for CAWOVCL			40* ²	mΩ
	RVRISO	for CISOVCL			40* ²	mΩ
Inrush current during power-on					100* ²	mA

Note 1. "VPOC" means POC (power on clear) detection voltage (typ. 2.95V@at power-on, typ. 2.9V@after (except) power-on).

For detail, refer to **Section 1.8.2, Voltage Detector (POC, LVI, VLVI, CVM) Characteristics**.

Note 2. This is reference value.

Note 3. Reliability restrictions from 1.35 V to 1.43 V.

1.8.2 Voltage Detector (POC, LVI, VLVI, CVM) Characteristics

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition		MIN.	TYP.	MAX.	Unit
Detection voltage (REGVCC)	VPOC	POC	At power-on (Rise)	2.8	2.95	3.1	V
			After power-on (Fall)	2.8	2.9	3.0	V
	VLVI0	LVI	Rise	3.87	4.0	4.13	V
			Fall	3.9	4.0	4.1	V
	VLVI1		Rise	3.57	3.7	3.83	V
			Fall	3.6	3.7	3.8	V
	VLVI2		Rise	3.37	3.5	3.63	V
			Fall	3.4	3.5	3.6	V
	VVLVI	VLVI		1.8	1.9	2.0	V
Detection voltage (AWOVCL, ISOVCL)	VCVMH	CVM	High voltage ^{Caution}	1.40	1.50	1.60	V
	VCVML ^{*8}		Low voltage ^{Caution}	1.1	1.15	1.20	V
Response time	t _{D_POC1} ^{*6}	POC	At power-on (Rise)	*1		2	ms
				*2		6.3	ms
			After power-on (Rise)	*3		2	ms
				*4		5	ms
	t _{D_POC2} ^{*7}		After power-on (Fall)	*5		5	μs
	t _{D_LVI}	LVI				2	ms
	t _{D_VLVI}	VLVI		*3		2	ms
				*4		5	ms
	t _{D_CVM}	CVM			0.2	10	μs
Setup time	t _{S_LVI}	LVI	LVICNT0,1 bits are set to 1 (except 00 _B), then LVI is ready to operate			80	μs
REGVCC minimum width	t _{W_POC}	POC			0.2		ms
	t _{W_LVI}	LVI			0.2		ms
	t _{W_VLVI}	VLVI			0.2		ms

Note 1. Voltage slope (t_{VS}) : 0.02 V/ms ≤ t_{VS} ≤ 0.5 V/ms

Note 2. Voltage slope (t_{VS}) : 0.5 V/ms < t_{VS} ≤ 500 V/ms

Note 3. Voltage slope (t_{VS}) : 0.02 V/ms ≤ t_{VS} ≤ 20 V/ms

Note 4. Voltage slope (t_{VS}) : 20 V/ms < t_{VS} ≤ 500 V/ms

Note 5. Voltage slope (t_{VS}) : 0.02 V/ms ≤ t_{VS} ≤ 500 V/ms

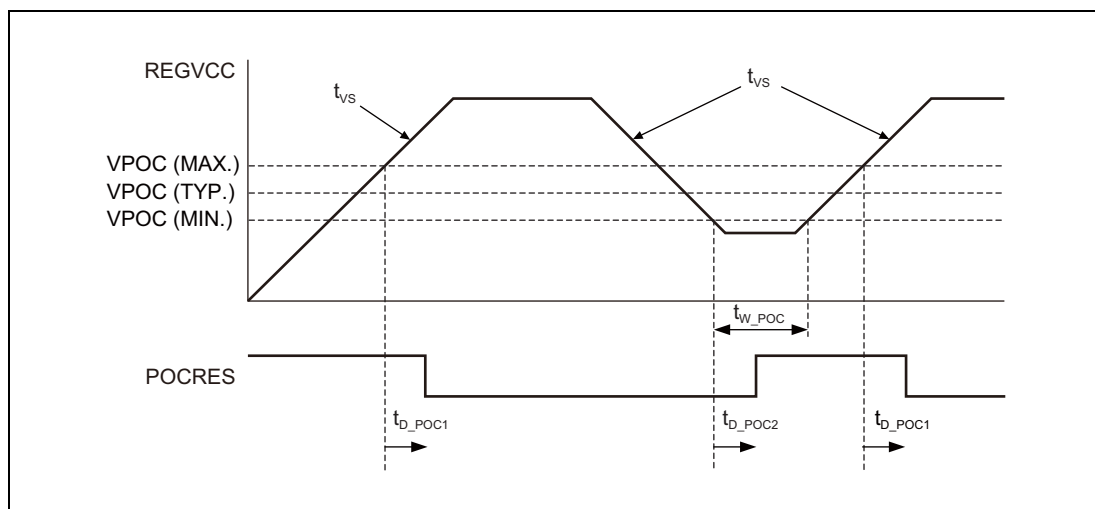
Note 6. t_{D_POC1} is the time from detection voltage to release of reset signal.

Note 7. t_{D_POC2} is the time from detection voltage to occurrence of reset signal.

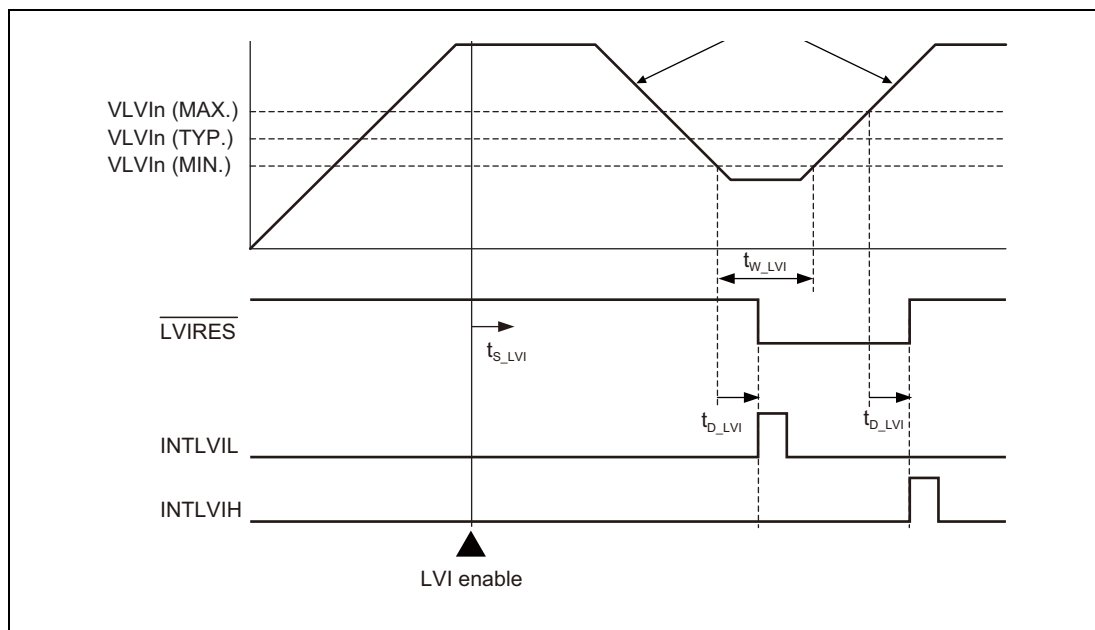
Note 8. The CVM monitors the internal voltage regulator output to ensure that AWOVCL/ISOVCL is upper than specified minimum level.

Caution: A detection of the voltage AWOVCL or ISOVCL outside the specified level of VCVMH and VCVML is not ensured by CVM.

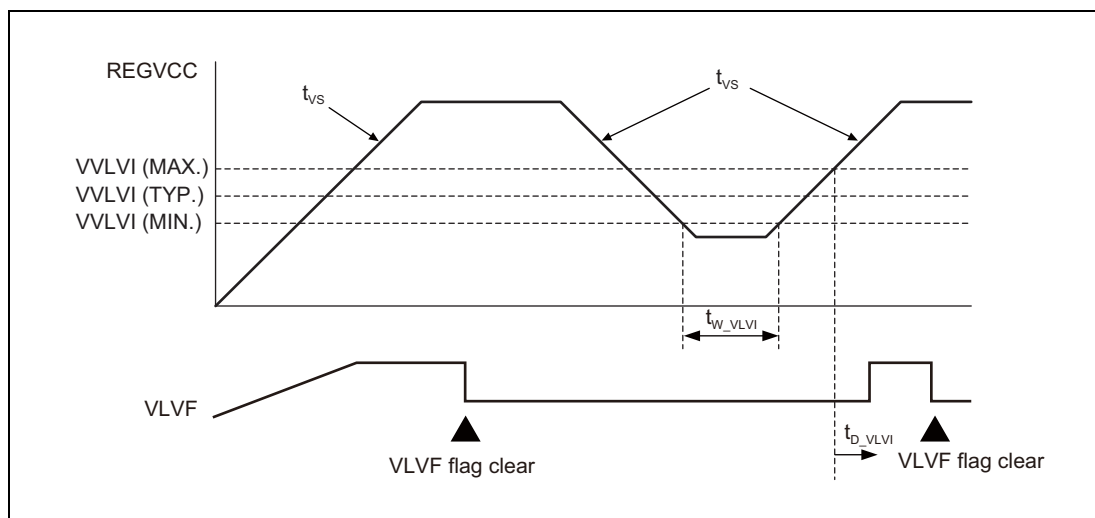
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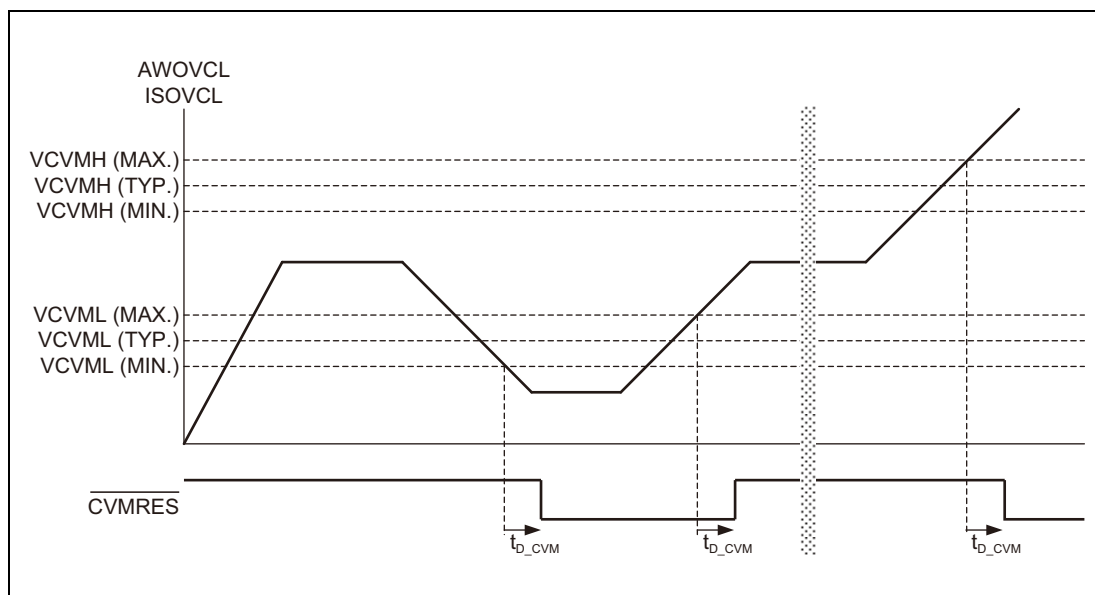
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<VLVI>



<CVM>

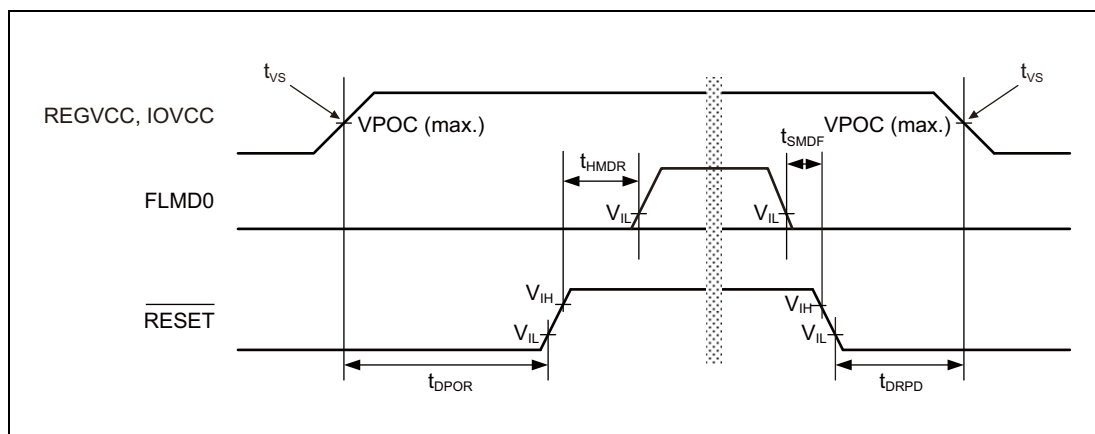


1.8.3 Power Up/Down Timing

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.1 In case the $\overline{\text{RESET}}$ pin is used (except Serial programming mode)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Voltage slope (REGVCC and IOVCC*1)	t_{VS}		0.02 (= 50 ms/V)		500 (= 2 μ s/V)	V/ms
REGVCC $\uparrow$ and IOVCC $\uparrow$ to $\overline{\text{RESET}}$ $\uparrow$ delay time	t_{DPOR}	Voltage slope (t_{VS}) : 0.02 V/ms $\leq t_{VS} \leq$ 0.5 V/ms	2			ms
		Voltage slope (t_{VS}) : 0.5 V/ms $< t_{VS} \leq$ 500 V/ms	6.3			ms
FLMD0 hold time (vs $\overline{\text{RESET}}$ $\uparrow$)	t_{HMDR}		1			ms
FLMD0 setup time (vs $\overline{\text{RESET}}$ $\downarrow$)	t_{SMDF}		0*2			μ s
$\overline{\text{RESET}}$ $\downarrow$ to REGVCC $\downarrow$ and IOVCC $\downarrow$ delay time	t_{DRPD}		0			ms



Note 1. IOVCC means EVCC and A0VREF.

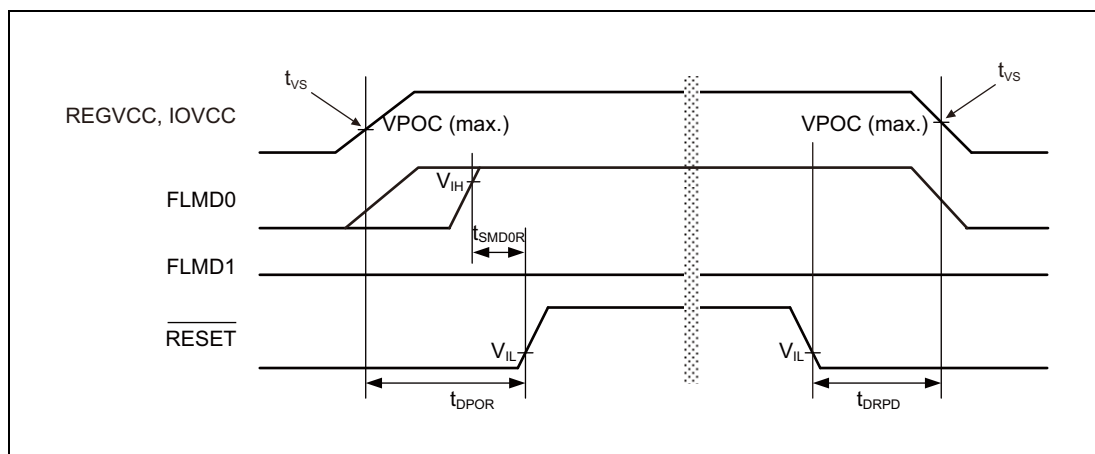
Note 2. When the $\overline{\text{RESET}}$ and FLMD0 pin input low level at same time ($t_{SMDF} = 0\mu$ s) in the device entries on-chip debug mode and operates self-programming, following pins have a possibility to unstable level output for less than 23ns.

P10_0, P0_0, P10_5, P8_1

So, when the device was used in the device entries on-chip debug mode and operates self-programming, please input low level in FLMD0 before $\overline{\text{RESET}}$ pin input.

Table 1.2 In case the $\overline{\text{RESET}}$ pin is used (for Serial programming mode)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Voltage slope (REGVCC and IOVCC* ¹)	t_{VS}		0.02 (= 50 ms/V)		500 (= 2 $\mu\text{s/V}$)	V/ms
REGVCC $\uparrow$ and IOVCC* ¹ $\uparrow$ to $\overline{\text{RESET}}$ $\uparrow$ delay time	t_{DPOR}	Voltage slope (t_{VS}) : $0.02 \text{ V/ms} \leq t_{VS} \leq 0.5 \text{ V/ms}$	2			ms
		Voltage slope (t_{VS}) : $0.5 \text{ V/ms} < t_{VS} \leq 500 \text{ V/ms}$	6.3			ms
FLMD0 setup time (vs $\overline{\text{RESET}}$ $\uparrow$)	t_{SMD0R}		1			ms
$\overline{\text{RESET}}$ $\downarrow$ to REGVCC $\downarrow$ and IOVCC* ¹ $\downarrow$ delay time	t_{DRPD}		0			ms



Note 1. IOVCC means EVCC and A0VREF.

Table 1.3 Boundary scan mode in case of using $\overline{\text{RESET}}$ pin

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Voltage slope (REGVCC and IOVCC*1)	t_{VS}		0.02 (= 50 ms/V)		500 (= 2 $\mu\text{s/V}$)	V/ms
REGVCC $\uparrow$ and IOVCC $\uparrow$ to $\overline{\text{RESET}}$ $\uparrow$ delay time	t_{DPOR}	Voltage slope (t_{VS}) : $0.02 \text{ V/ms} \leq t_{VS} \leq 0.5 \text{ V/ms}$	2			ms
		Voltage slope (t_{VS}) : $0.5 \text{ V/ms} < t_{VS} \leq 500 \text{ V/ms}$	6.3			ms
FLMD0, FLMD1, MODE0, MODE1 setup time (vs $\overline{\text{RESET}}$ $\uparrow$)	t_{SMDR}		1			ms
$\overline{\text{RESET}}$ $\downarrow$ to REGCC $\downarrow$ and IOVCC $\downarrow$ delay time	t_{DRPD}		0			ms
$\overline{\text{DCUTRST}}$ input delay time (vs $\overline{\text{RESET}}$ $\uparrow$)	t_{DRTRST}		1			ms
$\overline{\text{RESET}}$ hold time (vs $\overline{\text{DCUTRST}}$ $\downarrow$)	t_{HRTRST}		0			ms

Note 1. IOVCC means EVCC and A0VREF.

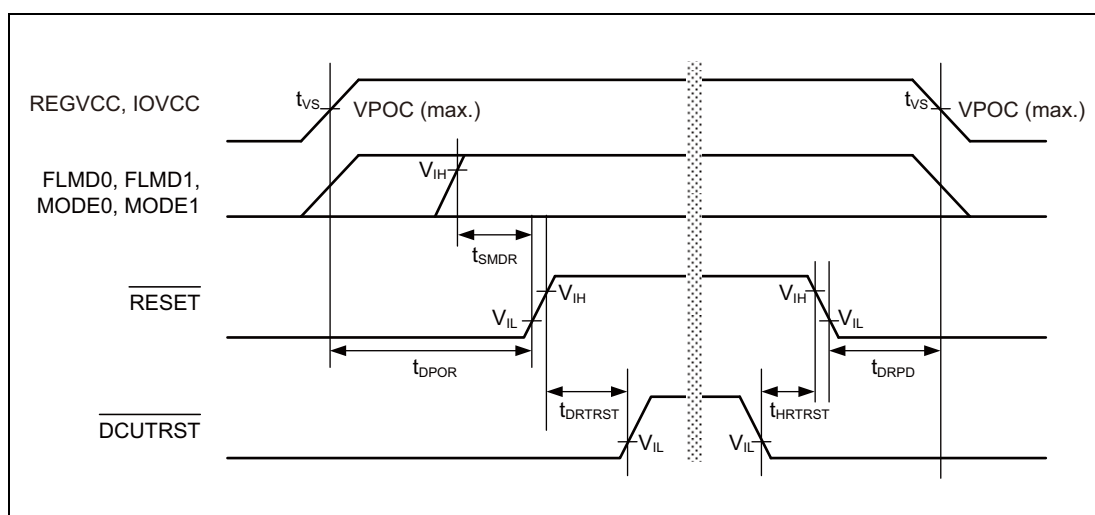
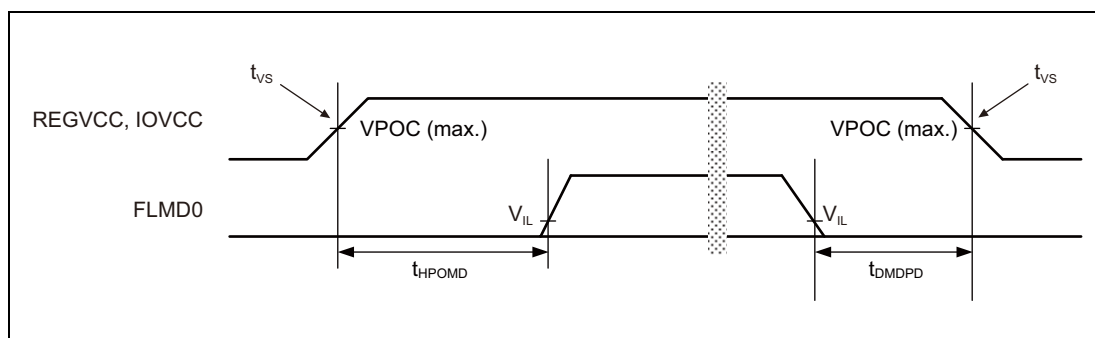


Table 1.4 In case the $\overline{\text{RESET}}$ pin is not used and fixed to high level by pull-up*1

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Voltage slope (REGVCC and IOVCC*2)	t_{VS}		0.02 (= 50 ms/V)		500 (= 2 $\mu\text{s/V}$)	V/ms
REGVCC $\uparrow$ and IOVCC $\uparrow$ to FLMD0 hold time	t_{HPOMD}	Voltage slope (t_{VS}) : $0.02 \text{ V/ms} \leq t_{VS} \leq 0.5 \text{ V/ms}$	2			ms
		Voltage slope (t_{VS}) : $0.5 \text{ V/ms} < t_{VS} \leq 500 \text{ V/ms}$	6.3			ms
FLMD0 $\downarrow$ to REGVCC $\downarrow$ and IOVCC*2 $\downarrow$ delay time	t_{DMDPD}		1			μs

Note 1. This operating condition is available only in normal operation mode (include self-programming mode).
When the device is used in except normal operation mode, please use the $\overline{\text{RESET}}$ pin.

Note 2. IOVCC means EVCC and A0VREF.



1.8.4 CPU Reset Release Timing

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.5 In case the $\overline{\text{RESET}}$ pin is not used

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
REGVCC $\uparrow$ to CPU reset release*1	t_{DPCRR}	Voltage slope (t_{VS}) : 0.02 V/ms $\leq t_{\text{VS}} \leq$ 0.5 V/ms			2.58	ms
		Voltage slope (t_{VS}) : 0.5 V/ms $< t_{\text{VS}} \leq$ 500 V/ms			8.30	ms

Note 1. This is reference value.

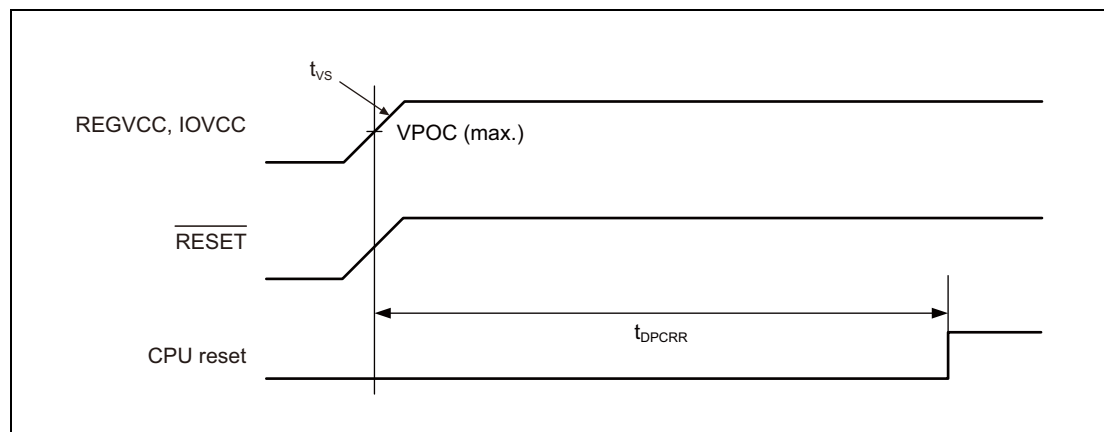
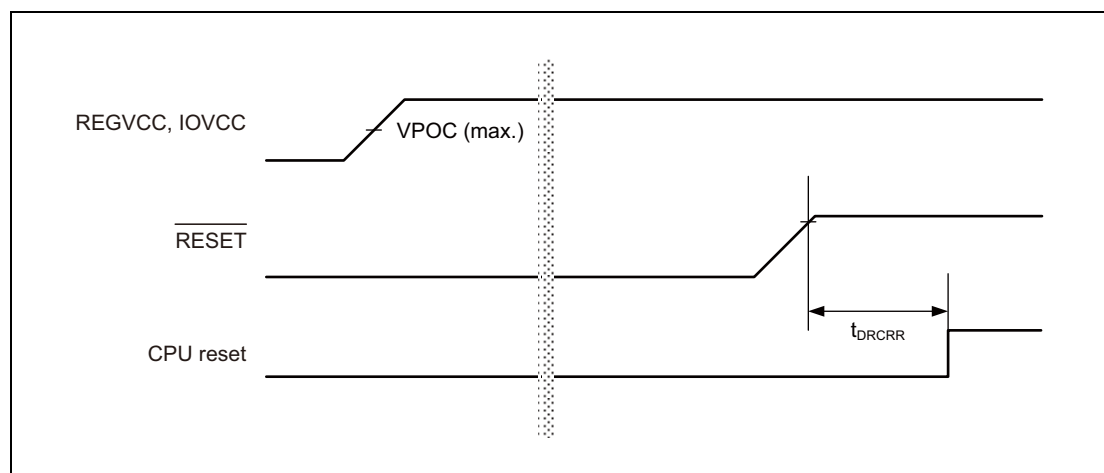


Table 1.6 In case the $\overline{\text{RESET}}$ pin is used

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
$\overline{\text{RESET}} \uparrow$ to CPU reset release*1	t_{DRCRR}				8*2	μ s

Note 1. This is reference value.

Note 2. At least t_{DPCRR} time is necessary reaching from VPOC (max) even if power up sequence is kept shown on **Section 1.8.3, Power Up/Down Timing.**



1.9 Pin Characteristics

Condition: Some of the conditions mentioned in this chapter can be selected by software and described in the hardware user's manual.

Pin Name	Port Input Buffer Function						Port Output Drive Strength Mode	Other Port Function	
	CMOS	SHMT1	SHMT2	SHMT4	TTL	Analog		Pull-up	Pull-down
RESET	—	—	√	—	—	—	—	—	— ^{*3}
FLMD0	—	√	—	—	—	—	—	√	√
AP0_0	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_1	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_2	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_3	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_4	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_5	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_6	√	—	—	—	—	√	Slow	—	√ ^{*1}
AP0_7	√	—	—	—	—	√	Slow	—	√ ^{*1}
JP0_0	—	—	—	√	√	—	Slow	√	√
JP0_1	—	—	—	√	—	—	Slow/Fast	√	√
JP0_2	—	—	—	√	√	—	Slow	√	√
JP0_3	—	—	—	√	√	—	Slow	√	√
JP0_4	—	—	—	√	—	—	Slow	√	√
JP0_5	—	—	—	√	—	—	Slow/Fast	√	√
P0_0	—	√	—	√	—	—	Slow	√	√
P0_1	—	√	—	√	—	—	Slow	√	√
P0_2	—	√	—	√	—	—	Slow/Fast ^{*2}	√	√
P0_3	—	√	—	√	—	—	Slow/Fast ^{*2}	√	√
P10_0	—	√	—	√	—	—	Slow/Fast	√	√
P10_1	—	—	—	√	—	—	Slow/Fast	√	√
P10_2	—	√	—	√	—	—	Slow/Fast	√	√
P10_3	—	√	—	√	—	—	Slow/Fast	√	√
P10_4	—	√	—	√	—	—	Slow/Fast	√	√
P10_5	—	—	—	√	—	—	Slow/Fast	√	√
P10_6	—	√	—	√	—	—	Slow/Fast	√	√
P10_7	—	—	—	√	—	—	Slow/Fast	√	√
P10_8	—	—	—	√	—	—	Slow	√	√
P10_9	—	√	—	√	—	—	Slow	√	√
P10_10	—	—	—	√	—	—	Slow	√	√
P8_0	—	—	—	√	—	√	Slow	√	√ ^{*4}
P8_1	—	—	—	√	—	√	Slow	√	√ ^{*4}
P9_0	—	—	—	√	—	√	Slow	√	√ ^{*4}
P9_1	—	—	—	√	—	√	Slow	√	√ ^{*4}

Note 1. Pull-down resistors for ADC diagnostic purpose. Control via ADC self-diagnostic register.

Note 2. Supports Cload: 100pF

Note 3. At a power-on clear reset, an on-chip pull-down resistor at the RESET pin is enabled until the flash sequence is completed.

Note 4. Pull-down resistors for ADC diagnostic and internal pull-down purposes. For ADC diagnostic, control via ADC self-diagnostic register. For internal pull-down, control via PD register.

Caution: Regarding external pull-up resistor of RESET pin, please connect less than 6.6 kΩ.

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

(1/2)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
High level input voltage	VIH	CMOS	0.65 × IOVCC		IOVCC + 0.3	V
		SHMT1 (except FLMD0 pin)	0.7 × IOVCC		IOVCC + 0.3	V
		SHMT1 (FLMD0 pin)*3	0.66 × EVCC		EVCC + 0.3	V
		SHMT2	0.75 × IOVCC		IOVCC + 0.3	V
		SHMT4	0.8 × IOVCC		IOVCC + 0.3	V
		TTL	EVCC = VPOC to 3.6 V		EVCC + 0.3	V
			EVCC = 3.6 V to 5.5 V		EVCC + 0.3	V
Low level input voltage	VIL	CMOS	-0.3		0.35 × IOVCC	V
		SHMT1	-0.3		0.3 × IOVCC	V
		SHMT2	-0.3		0.25 × IOVCC	V
		SHMT4	-0.3		0.5 × IOVCC	V
		TTL			0.8	V
						V
Input hysteresis for Schmitt	VH	SHMT1	0.3			V
		SHMT2	0.2 × IOVCC			V
		SHMT4	0.1			V
Input leakage current	ILIH	RESET, FLMD0, JP0, P0, P8, P9 pin, VI = EVCC*2			0.5	μA
		P10 pin			0.5	μA
		AP0 pin, VI = A0VREF*2			0.5	μA
	ILIL	RESET, FLMD0, JP0, P0, P8, P9 pin, VI = 0 V*2			-0.5	μA
		P10 pin, VI = 0 V*2			-0.5	μA
		AP0 pin, VI = 0 V*2			-0.5	μA
Internal pull-up resistance	RU	except FLMD0 pin	20 (275 μA)	40	100	kΩ
		FLMD0*3	10 (550 μA)	19	48	kΩ
Internal pull-down resistance	RD	except FLMD0 pin	20 (275 μA)	40	100	kΩ
		FLMD0	10 (550 μA)	19	50	kΩ
High level output voltage	VOH	Fast mode				
			IOH = -5 mA (6 pins)*4	IOVCC - 1.0		V
			IOH = -3 mA (10 pins)*4	IOVCC - 1.0		V
			IOH = -1 mA (16 pins)*4	IOVCC - 0.5		V
			IOH = -0.1 mA (16 pins)*4	IOVCC - 0.5		V
		Slow mode				
			IOH = -1 mA (16 pins)*4	IOVCC - 0.5		V
			IOH = -0.1 mA (16 pins)*4	IOVCC - 0.5		V
Low level output voltage	VOL	Fast mode				
			IOL = 5 mA (6 pins)*4		0.4	V
			IOL = 3 mA (10 pins)*4		0.4	V
			IOL = 1 mA (16 pins)*4		0.4	V
		Slow mode				
			IOL = 1 mA (16 pins)*4		0.4	V
Rise/Fall time	t _{KRP} /t _{KFP}	Fast mode (except below pins)*5	CL = 30 pF		7	ns
			CL = 50 pF		12	ns
			CL = 100 pF		24	ns
		Fast mode (P10_1, P10_2)*6	CL = 50 pF		6	ns
		Fast mode (P0_2, P0_3)*6	CL = 100 pF		6.15	ns
		Slow mode*5	CL = 30 pF		37	ns
			CL = 50 pF		62	ns
			CL = 100 pF		124	ns

(2/2)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Output frequency	f_O	Fast mode	CL = 30 pF		40	MHz
		Slow mode	CL = 30 pF		10	MHz
			CL = 50 pF		6	MHz
			CL = 100 pF		3	MHz

Note 1. "IOVCC" means the pins are assigned to the power supply (EVCC and A0VREF).

Note 2. Not select the analog input function of ADCn.

Note 3. When the internal pull-up resistor of FLMD0 pin is applied by FLMDCNT register, please connect 95 kΩ or more as external pull-down resistor.

Note 4. The number of pin indicates simultaneous ON.

Note 5. Measurement point: $0.1 \times \text{IOVCC}$ to $0.9 \times \text{IOVCC}$

Note 6. Measurement point: $0.2 \times \text{IOVCC}$ to $0.8 \times \text{IOVCC}$

1.9.1 Output Current

Item	Symbol	Pin Group	Condition	MIN.	TYP.	MAX.	Unit
High-level output current	IOH	PgE	Per side (Total of P9_0 to P9_1, P10_6 to P10_10)			-27	mA
			Per side (Total of P10_0 to P10_2)			-15	mA
			Per side (Total of P0_0 to P0_3, P10_3 to P10_5)			-27	mA
			Per side (Total of JP0_0 to JP0_5, P8_0, P8_1)			-8	mA
			Total (EVCC)			-60	mA
		PgA0	Total (A0VREF)			-8	mA
Low-level output current	IOL	PgE	Per side (Total of P9_0, P9_1, P10_6 to P10_10)			27	mA
			Per side (Total of P10_0 to P10_2)			15	mA
			Per side (Total of P0_0 to P0_3, P10_3 to P10_5)			27	mA
			Per side (Total of JP0_0 to JP0_5, P8_0, P8_1)			8	mA
			Total (EVSS)			60	mA
		PgA0	Total (A0VSS)			8	mA

Note 1. For detail of the definition of "side" and "total", refer to **Section 1.2.3, Port Current**.

1.10 Power Supply Currents

Condition: REGVCC, EVCC and A0VREF total current. But the I/O buffer is stopped.

ECO Line

Item	Symbol	Condition				MIN.	TYP.*1	MAX.	Unit
		CPU	PLL	Ta	Peripheral*2				
RUN mode current	IDDR	Run (80 MHz)	Run	-40 to 125°C	Run(#1)		25	60	mA
				25°C	Stop(#1)		19		mA
RUN mode current (During data/code flash programming)	IDDR3	Run (80 MHz)	Run	-40 to 125°C	Run(#2)		36	60	mA
HALT mode current	IDDH	Run (80 MHz)	Run	-40 to 125°C	Run(#3)		20	56	mA

Item	Symbol	Condition				MIN.	TYP.*1	MAX.	Unit
		CPU	PLL	Ta	Peripheral*2				
STOP mode current	IDDS	Stop	Stop	-40 to 85°C	Stop(#2)		0.35	3.5	mA
				105°C	Stop(#2)			8	mA
				125°C	Stop(#2)			12	mA
DeepSTOP mode current	IDDDS	Power off	Power off	-40 to 85°C	Stop(#3)		35	350	μA
				105°C	Stop(#3)			700	μA
				125°C	Stop(#3)			1000	μA
Cyclic RUN mode current	IDDCR	Run (HS IntOSC)	Stop	-40 to 85°C	Run(#4)		1.6	11	mA
				105°C	Run(#4)			17	mA
				125°C	Run(#4)			24	mA
Cyclic STOP mode current	IDDCS	Stop	Stop	-40 to 85°C	Run(#5)		0.40	6	mA
				105°C	Run(#5)			9	mA
				125°C	Run(#5)			13	mA

Note 1. The condition of "TYP." shows the specification with the following conditions. Also, the value is just for reference only.

- Ta = 25°C
- REGVCC = EVCC = A0VREF = 5.0 V
- AWOVSS = EVSS = A0VSS = 0 V

Note 2. Operating condition of each peripheral function is shown in the table of next page.

Caution: It must be ensured that the junction temperature in the Ta range remains below $T_j \leq 150^\circ\text{C}$ and does not exceed its limit under application conditions (thermal resistance, power supply current, peripheral current (if not included in power supply current), port output current and injection current).

Function		Run					Stop		
		(#1)	(#2)	(#3)	(#4)	(#5)	(#1)	(#2)	(#3)
AWO	MainOSC	Run	Run	Run	Stop	Stop	Run	Stop	Stop
	HS IntOSC	Run	Run	Run	Run	Stop	Run	Stop	Stop
	FOUT	Stop	Stop	Stop	Stop	Stop	Stop	Stop	Stop
	LPS	Stop	Stop	Stop	Stop	Stop	Stop	Stop	Stop
	RRAM	Read/Write	Read/Write	No access	Fetch	No access	Read/Write	No access	No access
	WDTA0	Stop	Stop	Stop	Stop	Stop	Stop	Stop	Stop
	TAUJ0	Run	Run	Run	Run (LS IntOSC)	Run (LS IntOSC)	Stop	Stop	Stop
	CLMA0	Run	Run	Run	Run	Stop	Stop	Stop	Stop
	CLMA1	Run	Run	Run	Stop	Stop	Stop	Stop	Stop
	ADCA0	Run* ¹	Run* ¹	Run* ¹	Stop	Stop	Stop	Stop	Stop
ISO	CPU	Run (PLL)	Run (PLL)	Halt (PLL)	Run (HS IntOSC)	Stop	Run (PLL)	Stop	Power off
	DMA	Run	Run	Run	Stop	Stop	Stop	Stop	
	PLL	Run	Run	Run	Stop	Stop	Run	Stop	
	Code flash	Fetch	Fetch	No access	No access	No access	Fetch	No access	
	Data flash	Read	Write/Erase	No access	No access	No access	Read	No access	
	PLRAM	Read/Write	Read/Write	No access	No access	No access	Read/Write	No access	
	SLRAM	Read/Write	Read/Write	No access	No access	No access	Read/Write	No access	
	OSTM0	Run	Run	Run	Stop	Stop	Stop	Stop	
	WDTA1	Stop	Stop	Stop	Stop	Stop	Stop	Stop	
	TAUD0	Run	Run	Run	Stop	Stop	Stop	Stop	
	TAPA, PIC	Stop	Stop	Stop	Stop	Stop	Stop	Stop	
	ENCA0	Run	Run	Run	Stop	Stop	Stop	Stop	
	PWM-diag	Run	Run	Run	Stop	Stop	Stop	Stop	
	RLIN3n	Run	Run	Run	Stop	Stop	Stop	Stop	
	RLIN2n	Wait	Wait	Wait	Stop	Stop	Stop	Stop	
	RS-CANn	Wait	Wait	Wait	Stop	Stop	Stop	Stop	
	CSIGn	Run	Run	Run	Stop	Stop	Stop	Stop	
	CSIHn	Run	Run	Run	Stop	Stop	Stop	Stop	
	RIIC0	Wait	Wait	Wait	Stop	Stop	Stop	Stop	
	CLMA2	Run	Run	Run	Stop	Stop	Stop	Stop	

Note 1. T&H used.

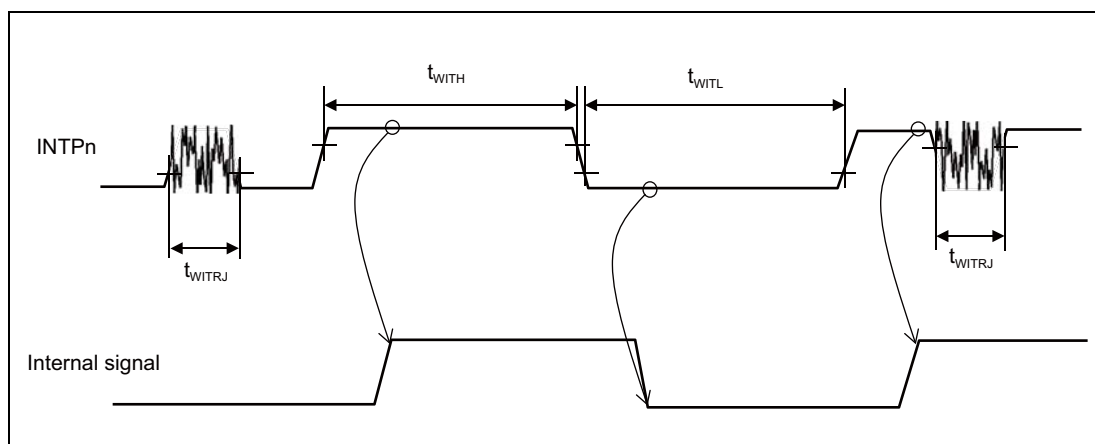
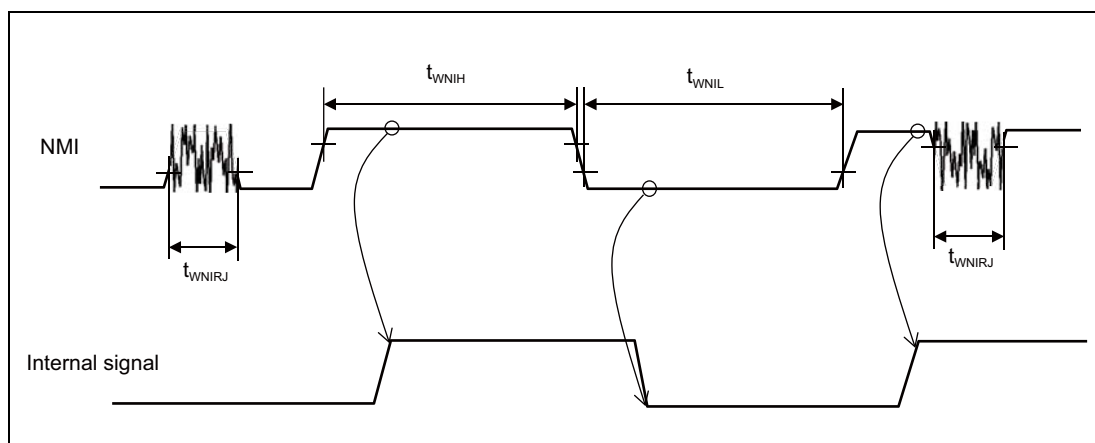
1.11 Interrupt Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) $^{\circ}$ C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
NMI input high/low level width*1	t_{WNIH}/t_{WNIL}	Edge detection mode	600			ns
		Level detection mode (EMCLK is operated by HS IntOSC)	756			ns
		Level detection mode (EMCLK is operated by LS IntOSC)	5.13			μ s
NMI pulse rejection*2	t_{WNIRJ}		100			ns
INTPn input high/low level width*1	t_{WITH}/t_{WITL}	Edge detection mode	600			ns
		Level detection mode (EMCLK is operated by HS IntOSC)	756			ns
		Level detection mode (EMCLK is operated by LS IntOSC)	5.13			μ s
INTPn pulse rejection*2	t_{WITRJ}		100			ns

Note 1. NMI and INTPn input width is needed to ensure that the internal interrupt signal is activated.

Note 2. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered.



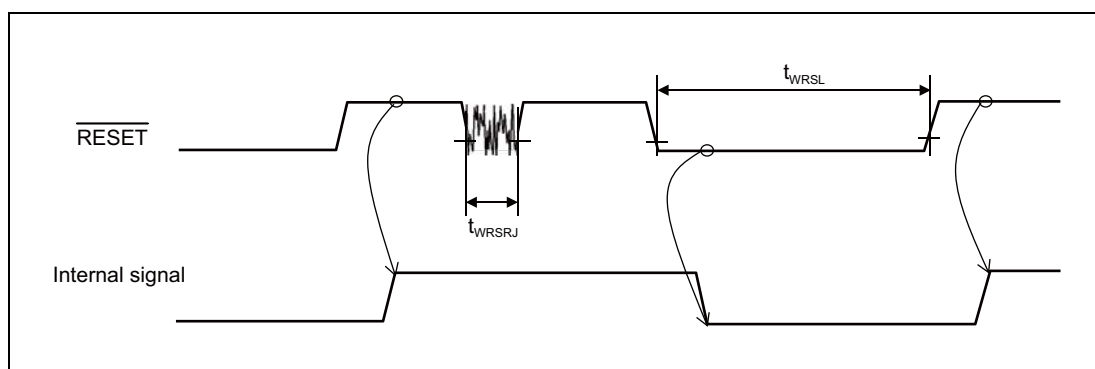
1.12 RESET Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
RESET input low level width	t_{WRSL}	*3	0.6			μ s
		*4	5.0			μ s
		*5	600			μ s
RESET pulse rejection*2	t_{WRSRJ}		0.1			μ s

Note 1. RESET input width is needed to ensure that the internal reset signal is activated.

Note 2. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered.



Note 3. After RESET is asserted there will be a period where GPIO output could become an undefined status and after 600 μ s will become Hi-z. (figure (a))

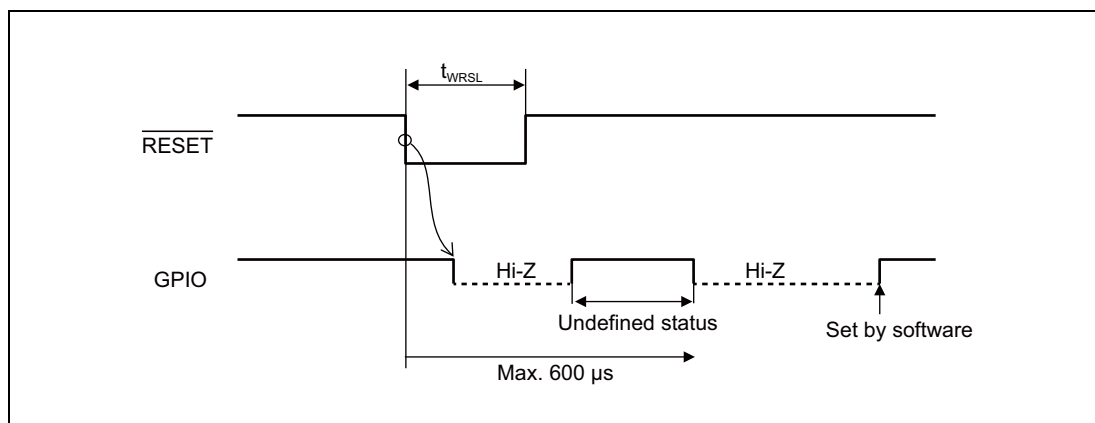
Note 4. If during RUN mode or HALT mode, after RESET is asserted GPIO pin will become Hi-z. For other modes, after RESET is asserted there will be a period where GPIO output could become an undefined status and after 600 μ s will become Hi-z. (figure (a) and (b))

Note 5. GPIO output states will become Hi-z after RESET is asserted. (figure (b))

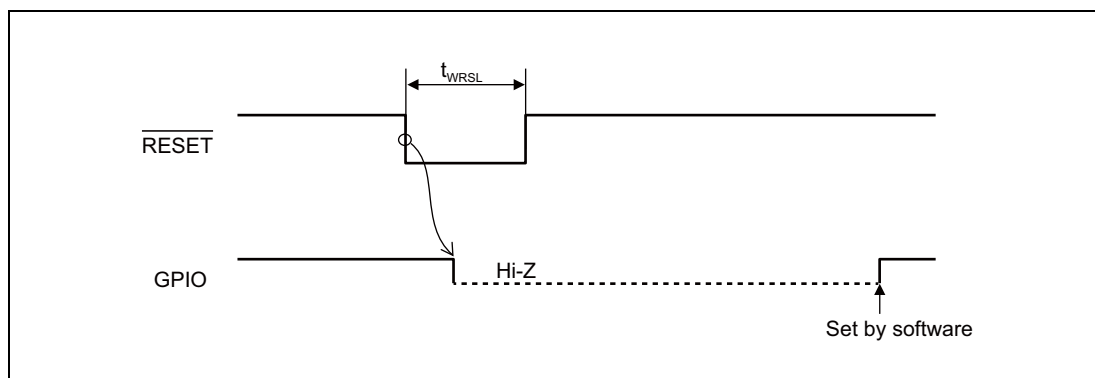
(a) In case of either

$t_{WRSL} < 5 \mu$ s, any mode or

$t_{WRSL} < 600 \mu$ s, any mode except for RUN and HALT mode.



- (b) In case of either
 $5\ \mu\text{s} \leq t_{\text{WRSL}}$, RUN and HALT mode or
 $600\ \mu\text{s} \leq t_{\text{WRSL}}$, any mode.



1.13 CSCXFOUT Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AVOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

<Output driver strength>

CSCXFOUT: Slow or fast mode (refer to the condition in the following table)

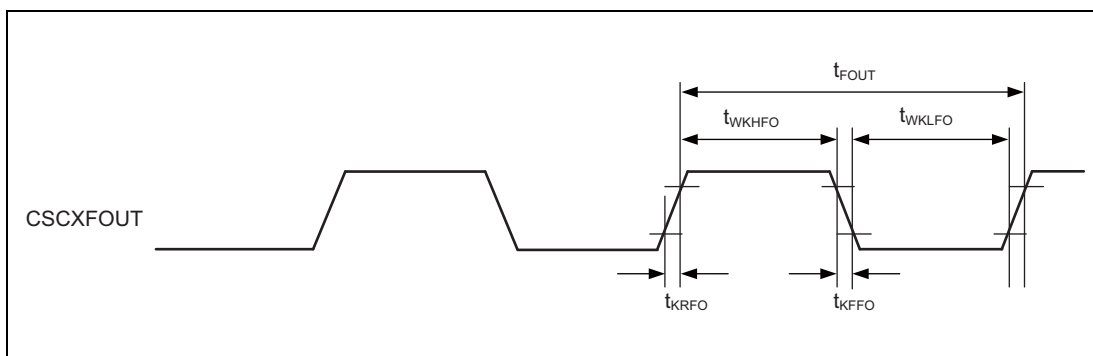
Item	Symbol	Condition	MIN.	MIN.	TYP.	MAX.	Unit
CSCXFOUT output cycle	t_{FOUT}	Slow mode		100 (max. 10 MHz)			ns
		Fast mode (Except JP0_3 pin)*1		41.6 (max. 24 MHz)			ns
CSCXFOUT high level width	t_{WKHF0}	Slow mode	N: 1*2 or even value*3	$t_{FOUT} / 2 - 37$			ns
			N: Odd value (N ≥ 5)*3, *4	$t_{FOUT} \times (N+1) / 2N - 37$			ns
		Fast mode (Except JP0_3 pin)*1	N: 1*2 or even value*3	$t_{FOUT} / 2 - 10$			ns
			N: Odd value (N ≥ 3)*3	$t_{FOUT} \times (N+1) / 2N - 10$			ns
CSCXFOUT low level width	t_{WKLFO}	Slow mode	N: 1*2 or even value*3	$t_{FOUT} / 2 - 37$			ns
			N: Odd value (N ≥ 5)*3, *4	$t_{FOUT} \times (N-1) / 2N - 37$			ns
		Fast mode (Except JP0_3 pin)*1	N: 1*2 or even value*3	$t_{FOUT} / 2 - 10$			ns
			N: Odd value (N ≥ 3)*3	$t_{FOUT} \times (N-1) / 2N - 10$			ns
CSCXFOUT rise/fall time	t_{KRFO} / t_{KFFO}	Slow mode				37	ns
		Fast mode (Except JP0_3 pin)*1				10	ns

Note 1. JP0_3 does not support fast mode.

Note 2. When MainOSC, HS IntOSC or LS IntOSC is selected as source clock with the condition of N=1, the characteristics of output signal depends on the selected source clock. It is recommended to use output signal after evaluation on an actual environment.

Note 3. "N" is the value of "Clock divisor N" defined by FOUTDIV register.

Note 4. The selection of N = 3 is prohibited when slow mode is used.



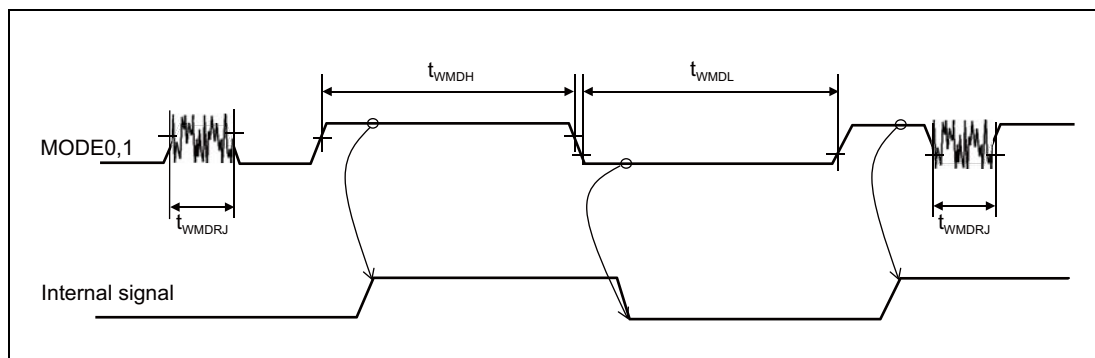
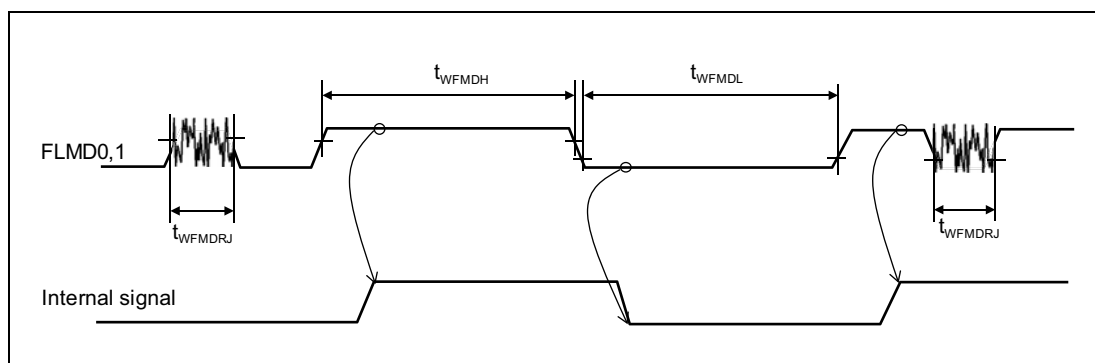
1.14 Mode Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
FLMD0,1 input high/low level width*1	$t_{WFMDH}/$ t_{WFMDL}		600			ns
FLMD0, 1 pulse rejection*2	t_{WFMDRJ}		100			ns
MODE0, 1 input high/low level width*1	$t_{WMDH}/$ t_{WMDL}		600			ns
MODE0, 1 pulse rejection*2	t_{WMDRJ}		100			ns

Note 1. FLMD0,1 and MODE0,1 input width is needed to ensure that the internal mode signal is activated.

Note 2. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered.

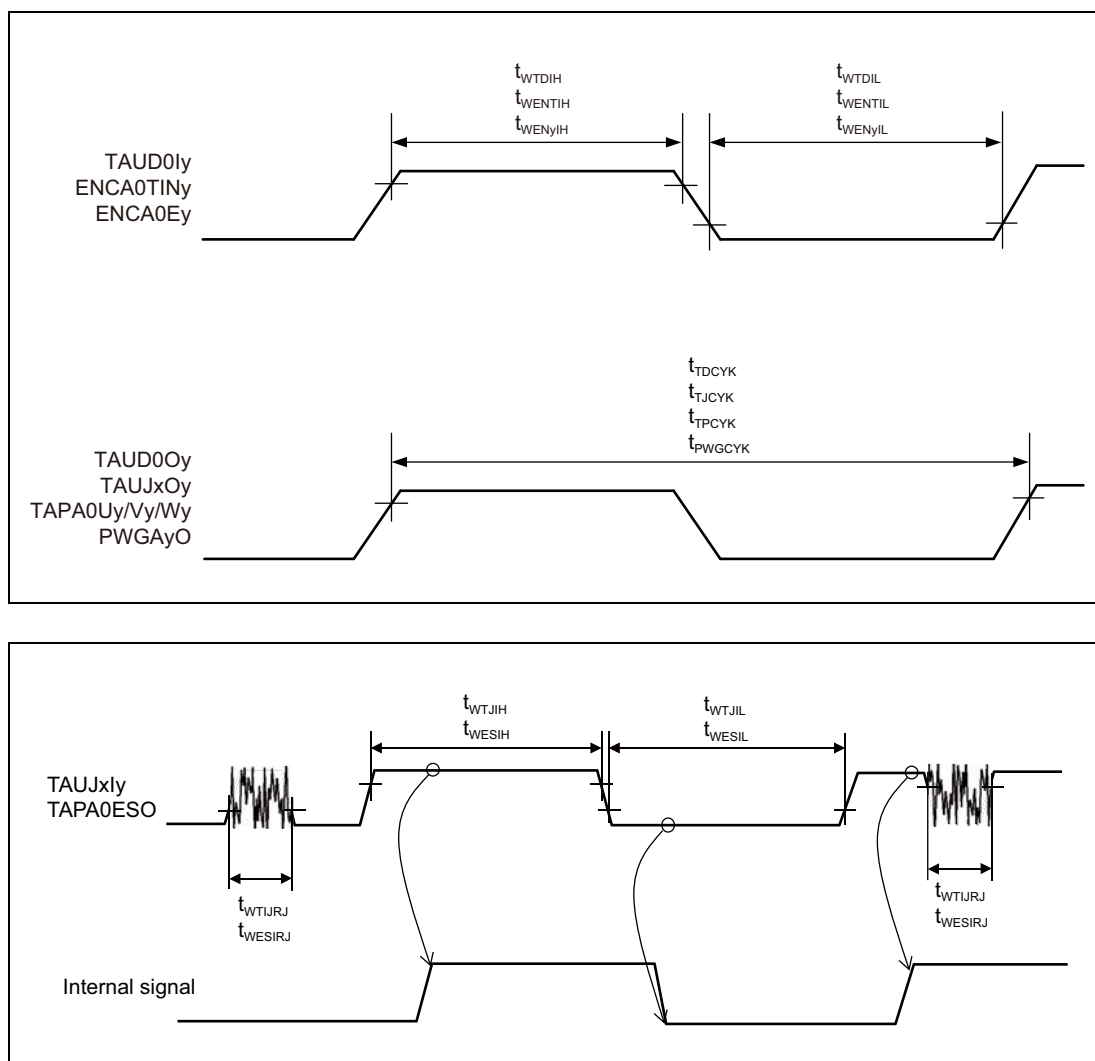


1.15 Timer Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
TAUD0Iy input high/low level width (y = 0 to 15)	t _{WTDIH} / t _{WTDIL}		n × Tsamp + 20 ^{*1, *2}			ns
TAUD0Oy output cycle (y = 0 to 15)	t _{TDCYK}	Slow mode			10	MHz
TAUJxIy input high/low level width ^{*3} (x = 0, y = 0 to 3)	t _{WTJIH} / t _{WTJIL}		600			ns
TAUJxIy pulse rejection ^{*4}	t _{WTIJRJ}		100			ns
TAUJxOy output cycle (x = 0, y = 0 to 3)	t _{TJCYK}	Slow mode			10	MHz
TAPA0ESO input high/low level width ^{*3}	t _{WESIH} / t _{WESIL}		600			ns
TAPA0ESO pulse rejection ^{*4}	t _{WESIRJ}		100			ns
TAPA0Uy/Vy/Wy output cycle (y = P, N)	t _{TPCYK}	Slow mode			10	MHz
ENCA0TINy input high/low level width (y = 0, 1)	t _{WENTIH} / t _{WENTIL}		n × Tsamp + 20 ^{*1}			ns
ENCA0Ey input high/low level width (y = 0, 1, C)	t _{WENyIH} / t _{WENyIL}		n × Tsamp + 20 ^{*1}			ns
PWGAYO output cycle (y = 0 to 12)	t _{PWGCYK}	Slow mode			10	MHz

- Note 1. n: Sampling number of the digital noise filter for each input.
 Tsamp: Sampling time of the digital noise filter for each input.
- Note 2. Input more than 1 count clock width of each timer counter channel.
- Note 3. TAUJxIy and TAPA0ESO input width is needed to ensure that the internal timer input signal is activated.
- Note 4. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered



1.16 RLIN2/RLIN3 Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
RLIN3 transfer rate		LIN specification	1		20	kbps
		LIN extended baudrate	1		115.2*1	kbps
		UART function			1.5	Mbps
RLIN2 transfer rate		LIN specification	1		20	kbps

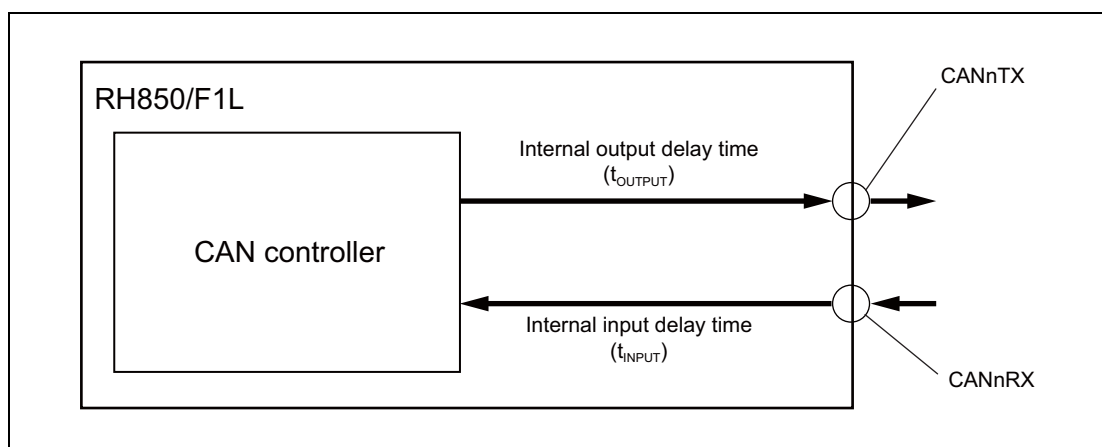
Note 1. The LIN extended baudrate is not part of the LIN standard specification.

1.17 RS-CAN Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Transfer rate					1	Mbps
Internal delay time*1	t_{NODE}				100	ns

Note 1. t_{NODE} = Internal input delay time (t_{INPUT}) + Internal output delay time (t_{OUTPUT})



1.18 CSI Timing

1.18.1 CSIG Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.7 CSIG Timing (Master Mode)

<Output driver strength>

CSIGnSO, CSIGnSC (output): Fast mode

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Macro operation clock cycle time	t_{KCYGn}	ECO line	12.5 (max. 80 MHz)			ns
CSIGnSC cycle time	t_{KCYMGn}		100			ns
CSIGnSC high level width	t_{KWHMGn}		$0.5 \times t_{KCYMGn} - 10$			ns
CSIGnSC low level width	t_{KWLMGn}		$0.5 \times t_{KCYMGn} - 10$			ns
CSIGnSI setup time (vs. CSIGnSC)	t_{SSIMGn}		30			ns
CSIGnSI hold time (vs. CSIGnSC)	t_{HSIMGn}		0			ns
CSIGnSO output delay (vs. CSIGnSC)	t_{DSOMGn}				7	ns
CSIGnRYI setup time (vs. CSIGnSC)	t_{SRYIGn}	CSIGnCTL1.CSIGnSIT = x CSIGnCTL1.CSIGnHSE = 1	$2 \times t_{KCYGn} + 25$			ns
CSIGnRYI High level width	t_{WRYIGn}	CSIGnCTL1.CSIGnHSE = 1	$t_{KCYGn} + 5$			ns

n = 0

Table 1.8 CSIG Timing (Slave Mode)

<Output driver strength>

CSIGnSO: Fast mode

CSIGnRYO: Slow mode

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Macro operation clock cycle time	t_{KCYGn}	ECO line	12.5 (max. 80 MHz)			ns
CSIGnSC cycle time	t_{KCYSGn}		200			ns
CSIGnSC high level width	t_{KWHSGn}		$0.5 \times t_{KCYSGn} - 10$			ns
CSIGnSC low level width	t_{KWLSGn}		$0.5 \times t_{KCYSGn} - 10$			ns
CSIGnSI setup time (vs. CSIGnSC)	t_{SSISGn}		20			ns
CSIGnSI hold time (vs. CSIGnSC)	t_{HSISGn}		$t_{KCYGn} + 5$			ns
CSIGnSO output delay (vs. CSIGnSC)	t_{DSOSGn}				30	ns
CSIGnRYO output delay	t_{SRYOGn}	$t_{KCYSGn} \geq 8 \times t_{KCYGn}$			38	ns
		$t_{KCYSGn} < 8 \times t_{KCYGn}$			$38 + t_{KCYGn}$	ns
CSIGnSSI setup time (vs. CSIGnSC)	t_{SSISGn}		$0.5 \times t_{KCYSGn} - 5$			ns
CSIGnSSI hold time (vs. CSIGnSC)	$t_{HSSISGn}$		$t_{KCYGn} + 5$			ns

n = 0

1.18.2 CSIH Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.9 CSIH Timing (Master Mode)

<Output driver strength>

CSIHnSO, CSIHnSC (output): Fast mode (CL = 100pF)

CSIHnCSSm: Slow mode

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Macro Operation clock cycle time	t_{KCYHn}	ECO line	12.5 (max. 80 MHz)			ns
CSIHnSC cycle time	t_{KCYMHn}		100			ns
CSIHnSC high level width	t_{KWHMHn}		$0.5 \times t_{KCYMHn} - 10$			ns
CSIHnSC low level width	t_{KWLMHn}		$0.5 \times t_{KCYMHn} - 10$			ns
CSIHnSI setup time (vs. CSIHnSC)	t_{SSIMHn}	SI Positive edge mode (CSIHnCTL1.CSIHnSLRS = 0)	19			ns
		SI Negative edge mode (CSIHnCTL1.CSIHnSLRS = 1)	14			ns
CSIHnSI hold time (vs. CSIHnSC)	t_{HSIMHn}	SI Positive edge mode (CSIHnCTL1.CSIHnSLRS = 0)	0			ns
		SI Negative edge mode (CSIHnCTL1.CSIHnSLRS = 1)	$t_{KCYHn}/2$			ns
CSIHnSO output delay (vs. CSIHnSC)	t_{DSOMHn}			7		ns
CSIHnRYI setup time (vs. CSIHnSC)	t_{SRYIHn}	CSIHnCTL1.CSIHnSIT = x CSIHnCTL1.CSIHnHSE = 1	$2 \times t_{KCYHn} + 25$			ns
CSIHnRYI high level width	t_{WRYIHn}	CSIHnCTL1.CSIHnHSE = 1	$t_{KCYHn} + 5$			ns
CSIHnCSS0-1 inactive width	$t_{WSCSBHn}$		$CSIDLE \times t_{KCYMHn} - 15$			ns
CSIHnCSS0-1 setup time (vs. CSIHnSC)	$t_{SSCSBHn0}$	CSIHnCFGx.CSIHnDAP = 0	$CSSETUP \times t_{KCYMHn} - 23$			ns
	$t_{SSCSBHn1}$	CSIHnCFGx.CSIHnDAP = 1	$(CSSETUP + 0.5) \times t_{KCYMHn} - 23$			ns
CSIHnCSS0-1 hold time (vs. CSIHnSC)	$t_{HSCSBHn0}$	CSIHnCTL1.CSIHnSIT = 0	$CSSHOLD \times t_{KCYMHn} - 5$			ns
	$t_{HSCSBHn1}$	CSIHnCTL1.CSIHnSIT = 1	$(CSSHOLD + 0.5) \times t_{KCYMHn} - 5$			ns

n = 0

NOTE

CSIDLE: Setting value of CSIHnCFGx.CSIHnIDx[2:0]

CSSETUP: Setting value of CSIHnCFGx.CSIHnSPx[3:0]

CSSHOLD: Setting value of CSIHnCFGx.CSIHnHDx[3:0]

x: Depends on number of the chip select signals.

CAUTION

When the serial clock level is changed during the communication (CSIHnCFGx.CSIHnCKPx) and the IDLE has a setting of 0.5 transmission clock period an inactive width time $t_{WSCSBHn}$ of " $0.5 \times t_{KCYMHn}$ " is added.

Table 1.10 CSIH Timing (Slave Mode)

<Output driver strength>

CSIHnSO, CSIHnSC (output): Fast mode

CSIHnRYO: Slow mode

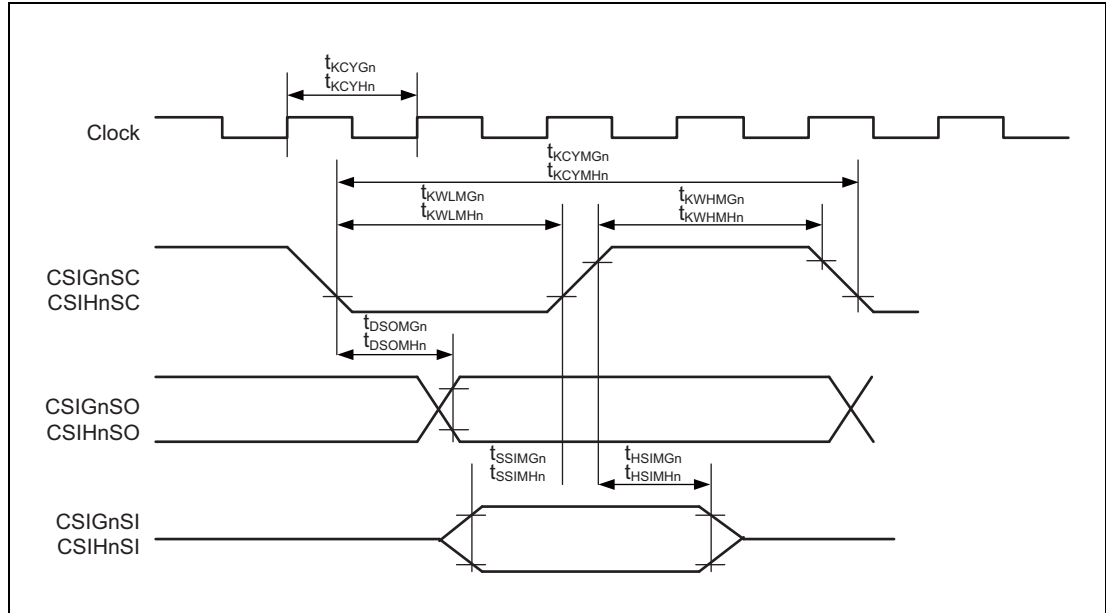
Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Macro Operation clock cycle time	t_{KCYHn}	ECO line	12.5 (max. 80 MHz)			ns
CSIHnSC cycle time	t_{KCYSHn}		200			ns
CSIHnSC high level width	t_{KWHSHn}		$0.5 \times t_{KCYSHn} - 10$			ns
CSIHnSC low level width	t_{KWLSHn}		$0.5 \times t_{KCYSHn} - 10$			ns
CSIHnSI setup time (vs. CSIHnSC)	t_{SSISHn}		20			ns
CSIHnSI hold time (vs. CSIHnSC)	t_{HSISHn}		$t_{KCYHn} + 5$			ns
CSIHnSO output delay (vs. CSIHnSC)	t_{DSOSHn}				30	ns
CSIHnRYO output delay	t_{SRYOHn}	$t_{KCYSHn} \geq 8 \times t_{KCYHn}$			38	ns
		$t_{KCYSHn} < 8 \times t_{KCYHn}$			$38 + t_{KCYHn}$	ns
CSIHnSSI setup time (vs. CSIHnSC)	$t_{SSSISHn}$		$0.5 \times t_{KCYSHn} - 5$			ns
CSIHnSSI hold time (vs. CSIHnSC)	$t_{HSSISHn}$		$t_{KCYHn} + 5$			ns

n = 0

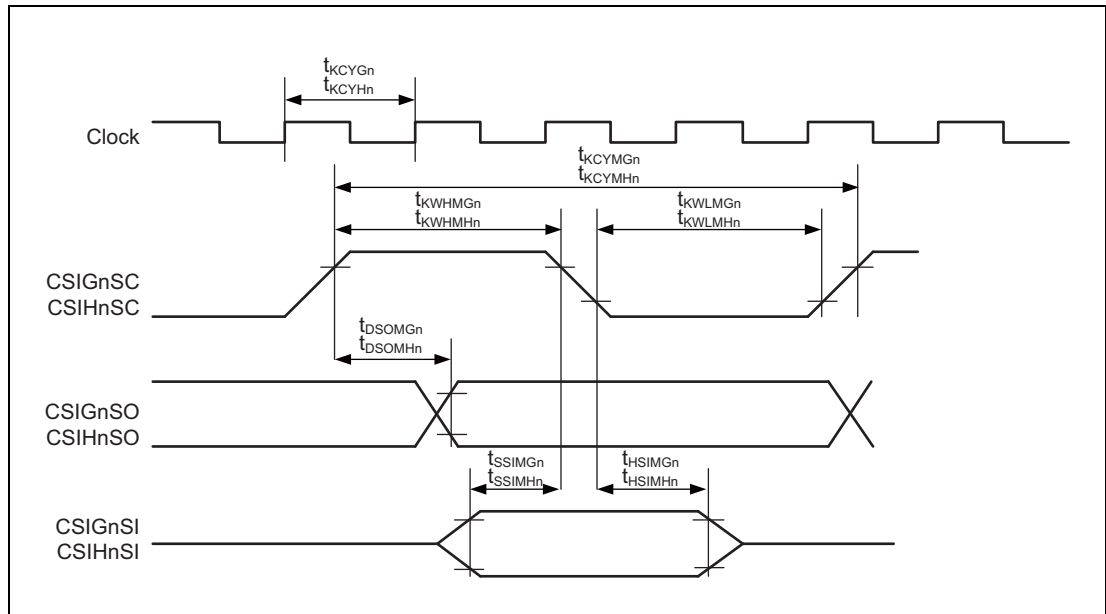
(1) SCKO/SI/SO

Master Mode:

- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 0/0 or 1/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 0/0 or 1/1)

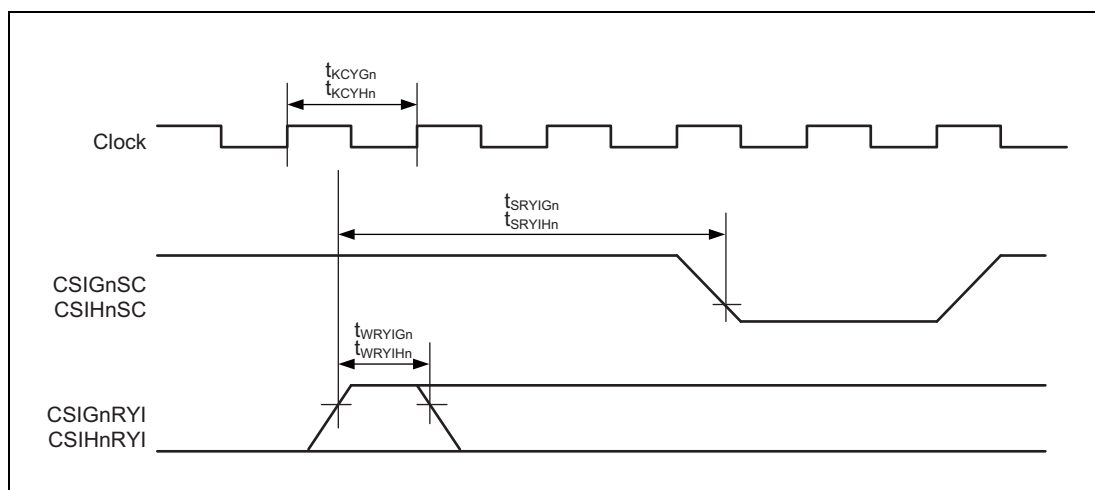


- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 1/0 or 0/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 1/0 or 0/1)

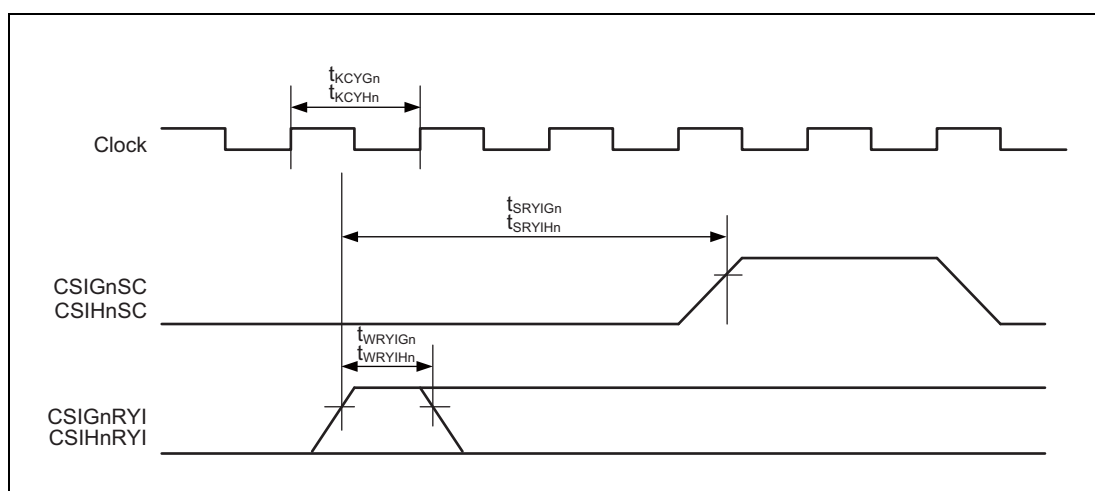


(2) RYI

- CSIG: Only master mode (CSIGnCTL1: CSIGnHSE = 1, CSIGnCTL1: CSIGnSIT = 0)
 - CSIH: Only master mode (CSIHnCTL1: CSIHnHSE = 1, CSIHnCTL1: CSIHnSIT = 0)
- CSIG (CSIGnCTL1: CSIGnCKR = 0)
 - CSIH (CSIHnCFGm: CSIHnCKPm = 0)

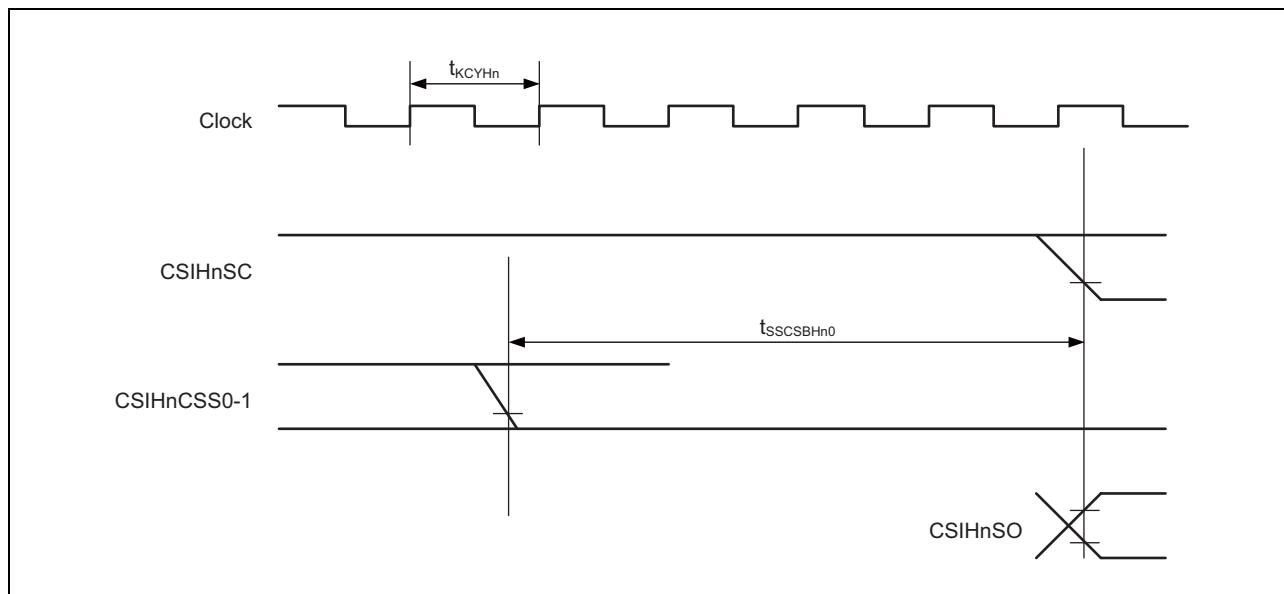


- CSIG (CSIGnCTL1: CSIGnCKR = 1)
- CSIH (CSIHnCFGm: CSIHnCKPm = 1)

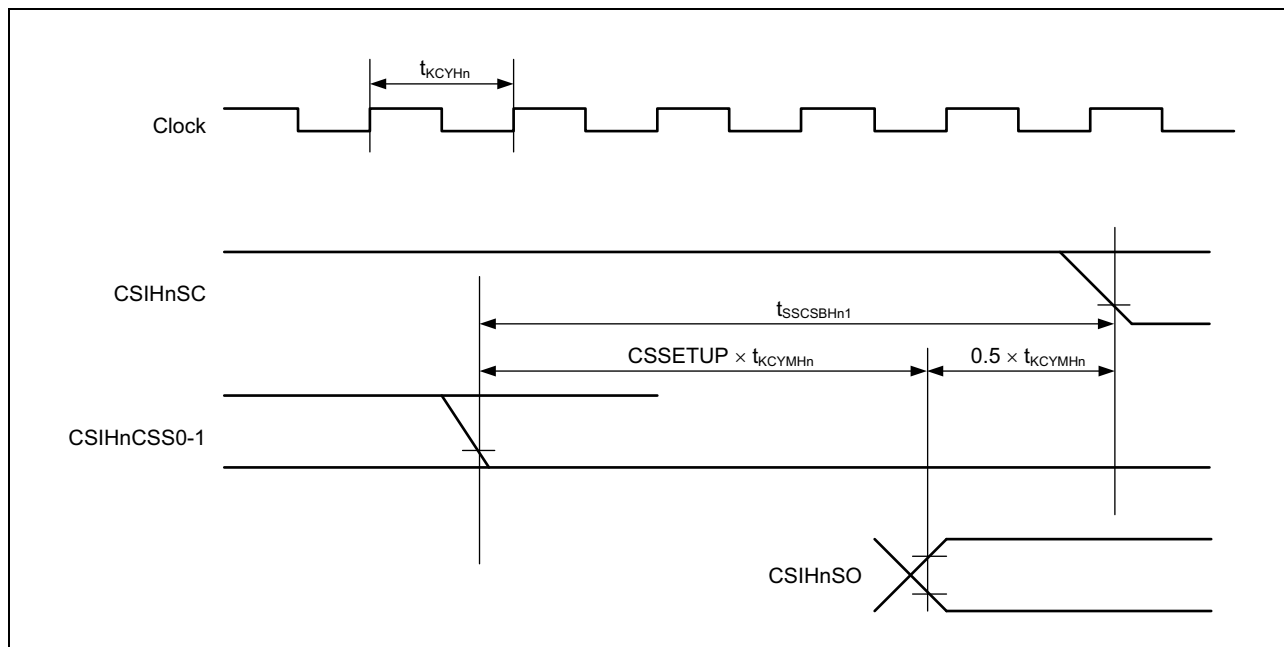


(3) CSSn**Only Master Mode (Setup Time):**

- CSIHnCFGm: CSIHnCKPm = 0, CSIHnCFGm: CSIHnDAPm = 0

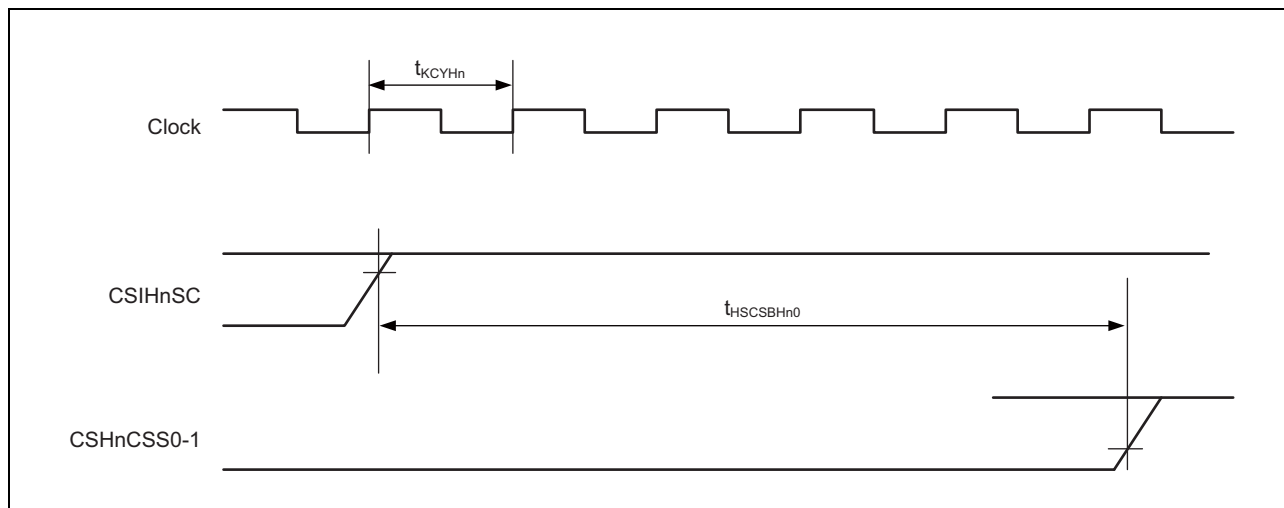


- CSIHnCFGm: CSIHnCKPm = 0, CSIHnCFGm: CSIHnDAPm = 1

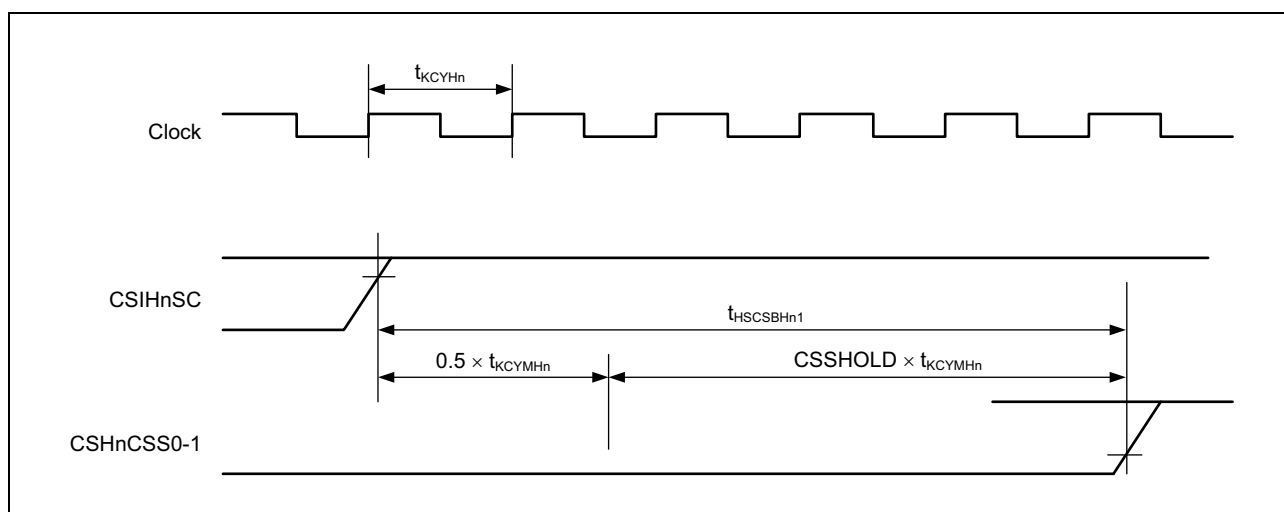


Only Master Mode (Hold Time):

- CSIHnCTL1: CSIHnSIT = 0, CSIHnCFGm: CSIHnCKPm = 0, CSIHnCFGm: CSIHnDAPm = 0

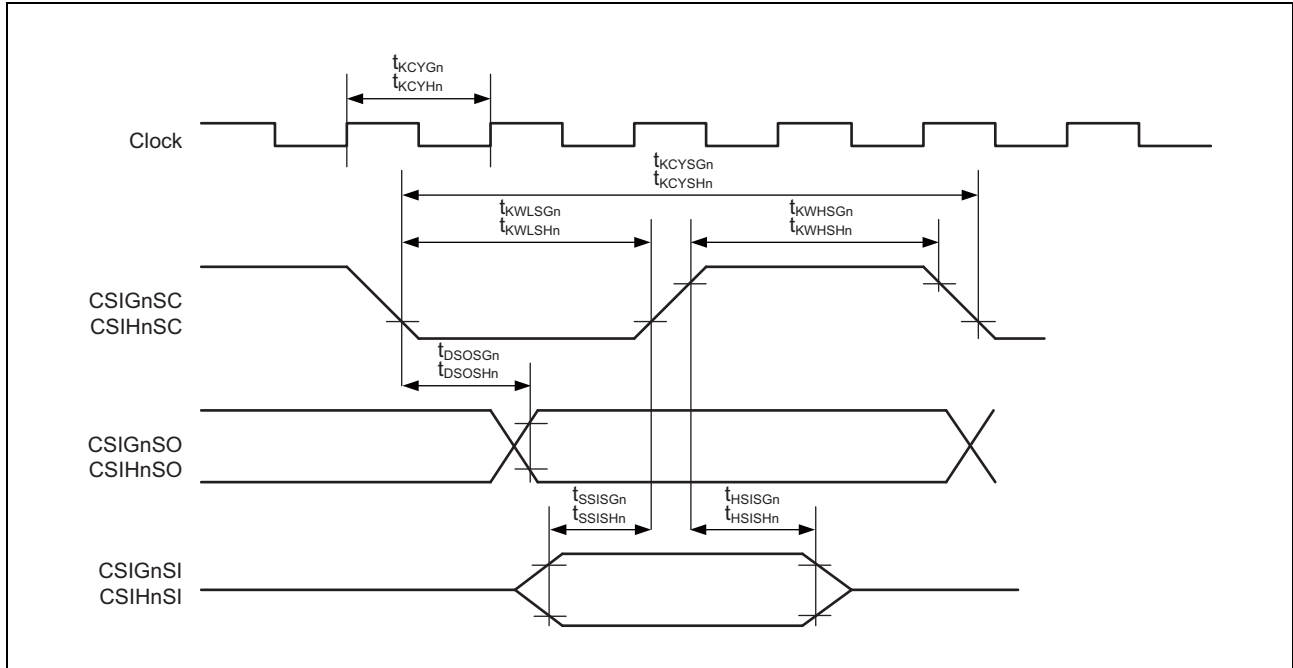


- CSIHnCTL1: CSIHnSIT = 1, CSIHnCFGm: CSIHnCKPm = 0, CSIHnCFGm: CSIHnDAPm = 0

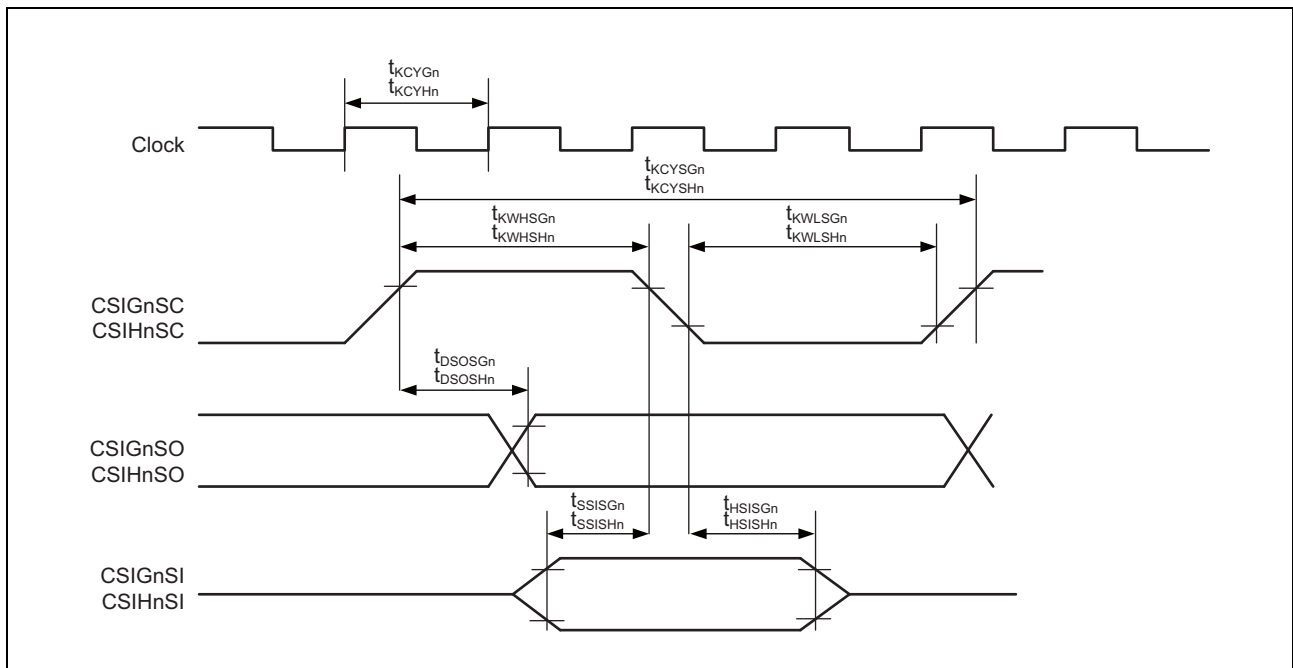


(4) SCKO/SI/SO**Slave Mode:**

- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 0/0 or 1/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 0/0 or 1/1)

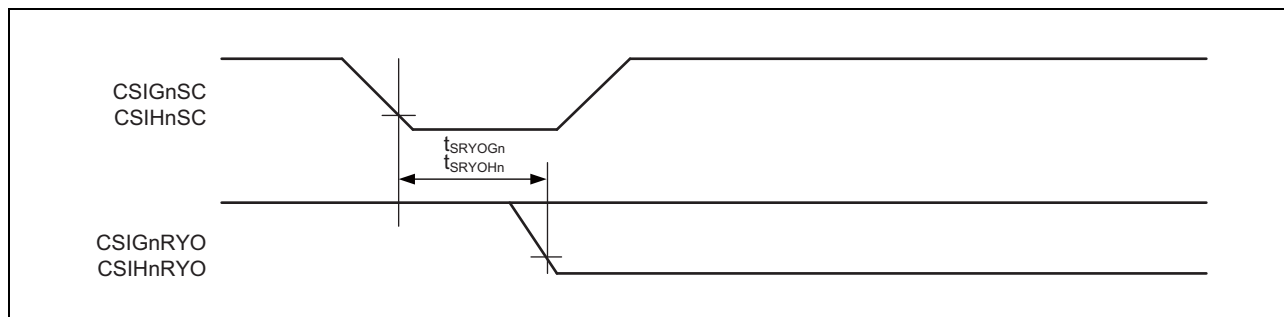


- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 1/0 or 0/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 1/0 or 0/1)

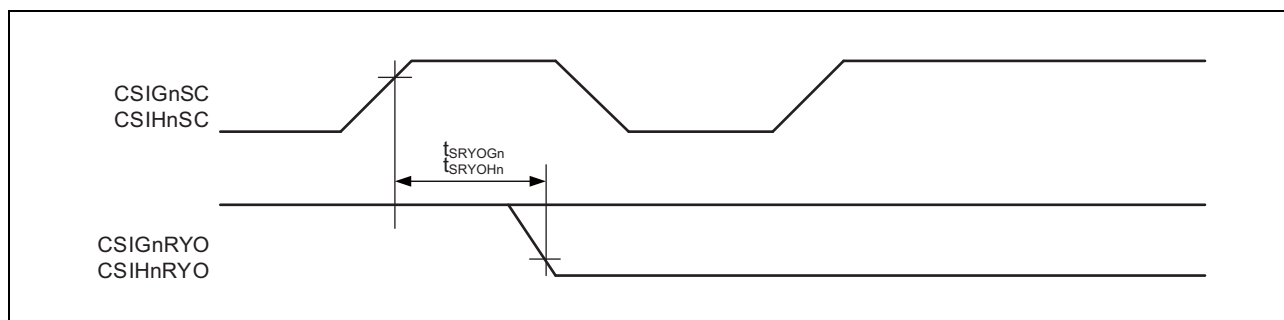


(5) RYO

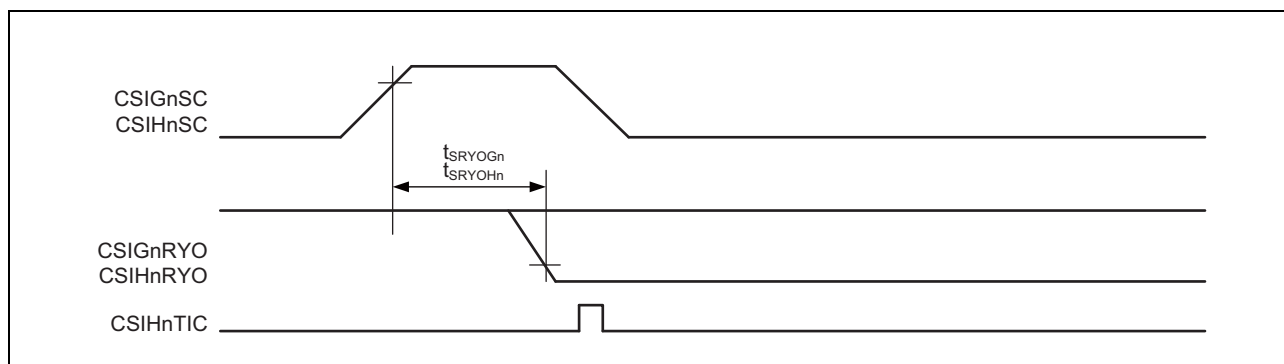
- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 0/0)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 0/0)



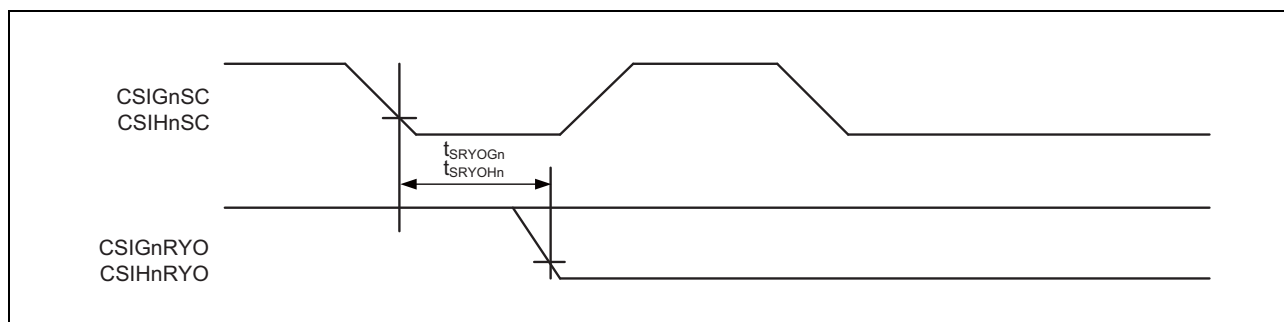
- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 0/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 0/1)



- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 1/0)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 1/0)

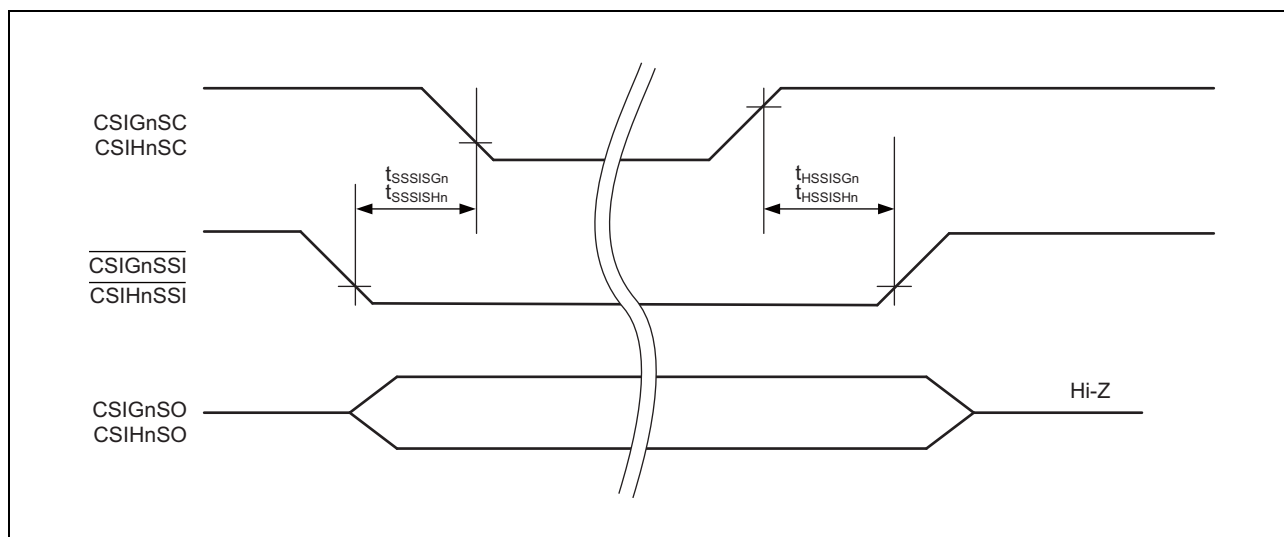


- CSIG (CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 1/1)
- CSIH (CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 1/1)

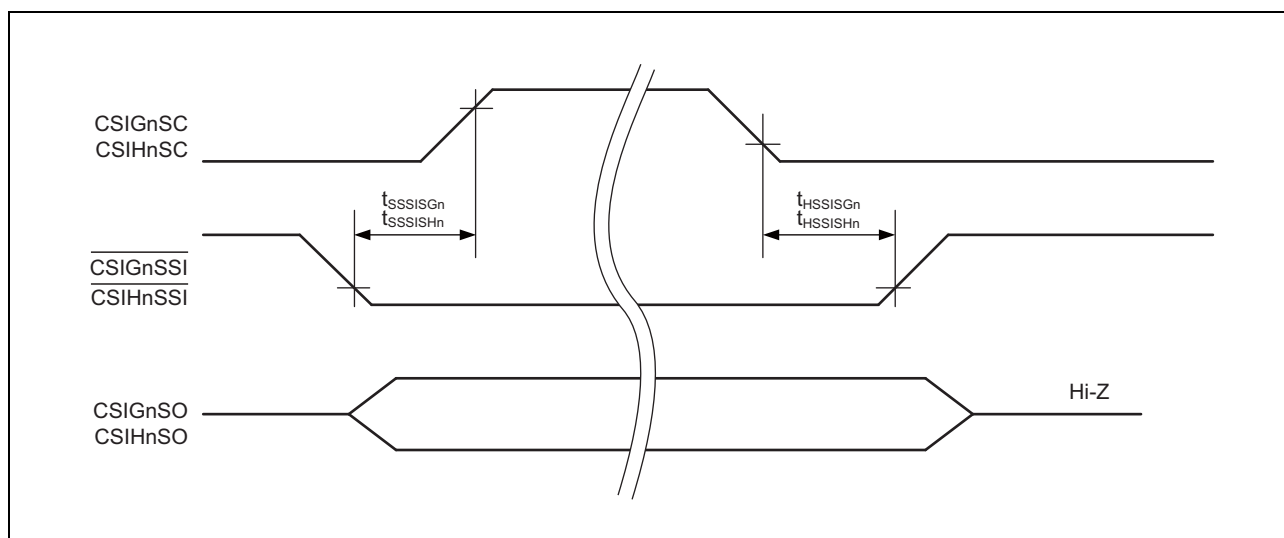


(6) SSI**Slave Mode:**

- CSIG (CSIGnCTL1: CSIGnSSE=1, CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 0/0 or 1/1)
- CSIH (CSIHnCTL1: CSIHnSSE=1, CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 0/0 or 1/1)



- CSIG (CSIGnCTL1: CSIGnSSE=1, CSIGnCTL1: CSIGnCKR/CSIGnCFG0: CSIGnDAP0 = 1/0 or 0/1)
- CSIH (CSIHnCTL1: CSIHnSSE=1, CSIHnCFGm: CSIHnCKPm/CSIHnCFGm: CSIHnDAPm = 1/0 or 0/1)



1.19 IIC Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C

Table 1.11 IIC Timing (Normal Mode)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
IIC0SCL clock period	f_{CLK}				100	kHz
Bus free time (between stop/start condition)	t_{BUF}		4.7			μs
Hold time* ¹	t_{HD} : STA		4.0			μs
IIC0SCL clock low-level width	t_{LOW}		4.7			μs
IIC0SCL clock high-level time	t_{HIGH}		4.0			μs
Setup time for start/restart condition	t_{SU} : STA		4.7			μs
Data hold time	t_{HD} : DAT	CBUS compatible master	5.0			μs
		IIC mode	0* ²			μs
Data setup time	t_{SU} : DAT		250			ns
Stop condition setup time	t_{SU} : STO		4.0			μs
Capacitance load of each bus line	Cb				400	pF

Note 1. At the start condition, the first clock pulse is generated after the hold time.

Note 2. The system requires a minimum of 300 ns hold time internally for the IIC0SDA signal (at VIH min. of IIC0SCL signal). In order to occupy the undefined area at the falling edge of IIC0SCL.

Note 3. If the system does not extend the IIC0SCL signal low hold time (t_{LOW}), only the maximum data hold time (t_{HD} : DAT) needs to be satisfied.

Table 1.12 RIIC Timing (Fast Mode)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
RIIC0SCL clock period	f_{CLK}				400	kHz
Bus free time (between stop/start condition)	t_{BUF}		1.3			μs
Hold time* ¹	t_{HD} : STA		0.6			μs
RIIC0SCL clock low-level width	t_{LOW}		1.3			μs
RIIC0SCL clock high-level time	t_{HIGH}		0.6			μs
Setup time for start/restart condition	t_{SU} : STA		0.6			μs
Data hold time	t_{HD} : DAT	IIC mode	0* ²			μs
Data setup time	t_{SU} : DAT		100* ⁴			ns
Stop condition setup time	t_{SU} : STO		0.6			μs
Pulse width with spike suppressed by input filter	t_{SP}		0		50	ns
Capacitance load of each bus line	C_b				400	pF

Note 1. At the start condition, the first clock pulse is generated after the hold time.

Note 2. The system requires a minimum of 300 ns hold time internally for the RIIC0SDA signal (at VIH min. of RIIC0SCL signal). In order to occupy the undefined area at the falling edge of RIIC0SCL.

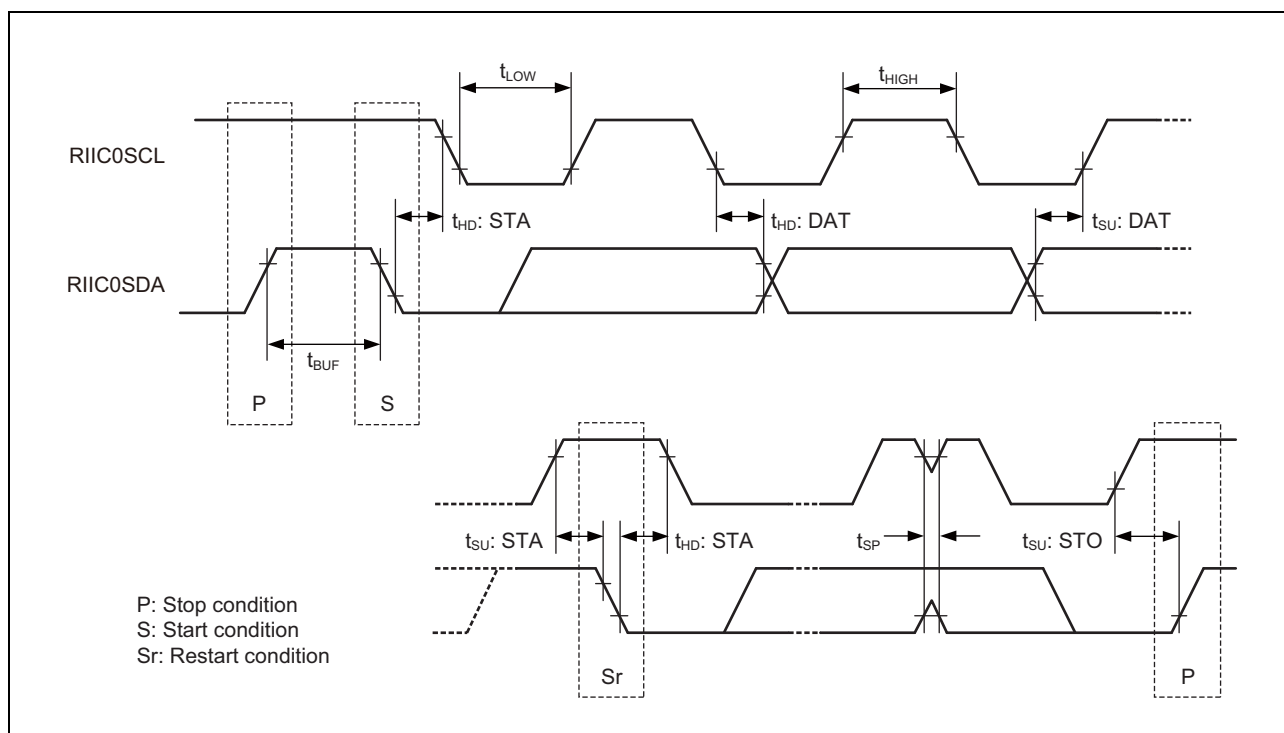
Note 3. If the system does not extend the RIIC0SCL signal low hold time (t_{LOW}), only the maximum data hold time (t_{HD} : DAT) needs to be satisfied.

Note 4. The fast mode IIC bus can be used in normal mode IIC bus system. In this case, set the fast mode IIC bus so that it meets the following conditions.

- If the system does not extend the RIIC0SCL signal's low state hold time: t_{SU} : DAT $\geq$ 250 ns

- If the system extends the RIIC0SCL signal's low state hold time:

Transmit the following data bit to the RIIC0SDA line prior to releasing the RIIC0SCL line (1250 ns: Normal mode IIC bus specification).

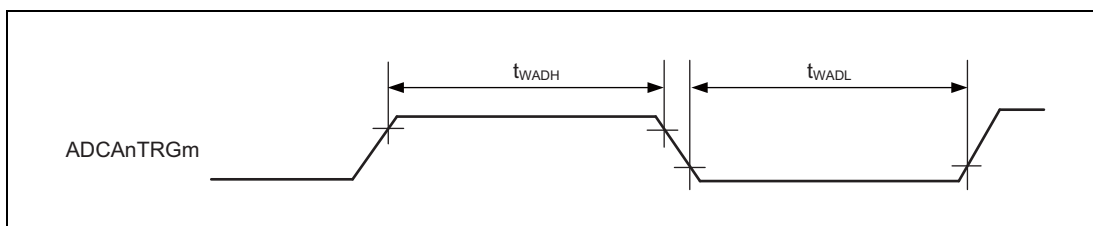


1.20 ADTRG Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
ADCA _n TRG _m input high/ low level width	$t_{WADH}/$ t_{WADL}		$k \times T_{\text{samp}} + 20^{*1}$			ns

Note 1. k: Sampling number of the digital noise filter for each input.
 Tsamp: Sampling time of the digital noise filter for each input.



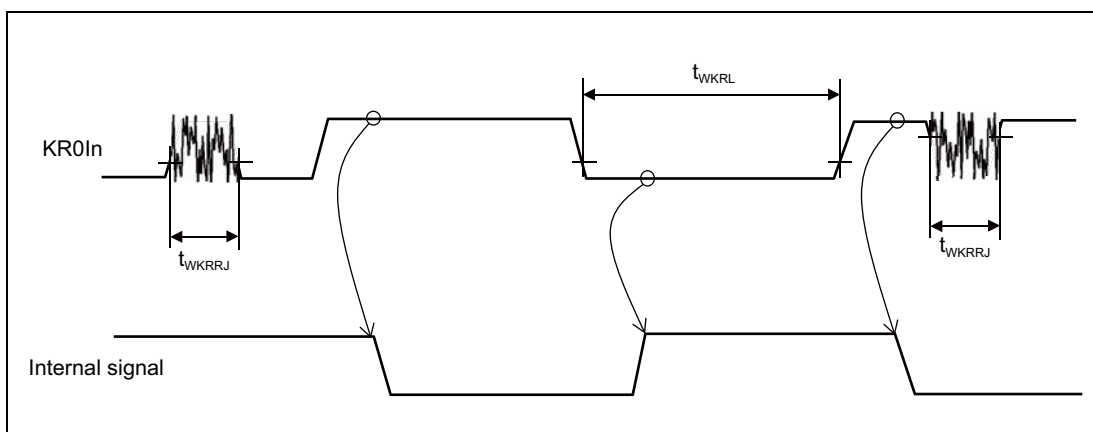
1.21 Key Return Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
KR0In input low level width* ¹	t_{WKRL}		600			ns
KR0In pulse rejection* ²	t_{WKRRJ}		100			ns

Note 1. KR0In input width is needed to ensure that the internal key input signal is activated.

Note 2. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered.



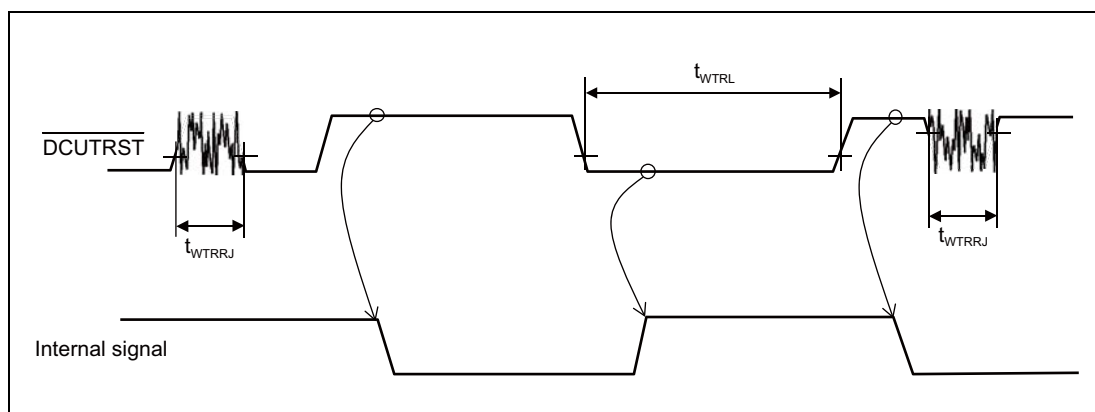
1.22 DCUTRST Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F $\pm$ 30%, CISOVCL: 0.1 μ F $\pm$ 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
DCUTRST input low level width*1	t_{WTRL}		600			ns
DCUTRST pulse rejection*2	t_{WTRRJ}		100			ns

Note 1. $\overline{\text{DCUTRST}}$ input width is needed to ensure that the internal DCU reset input signal is activated.

Note 2. Pulses shorter than this minimum is ignored. This is reference value. Noise such as the figure can be filtered.



1.23 Debug Interface Characteristics

1.23.1 Nexus Interface Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

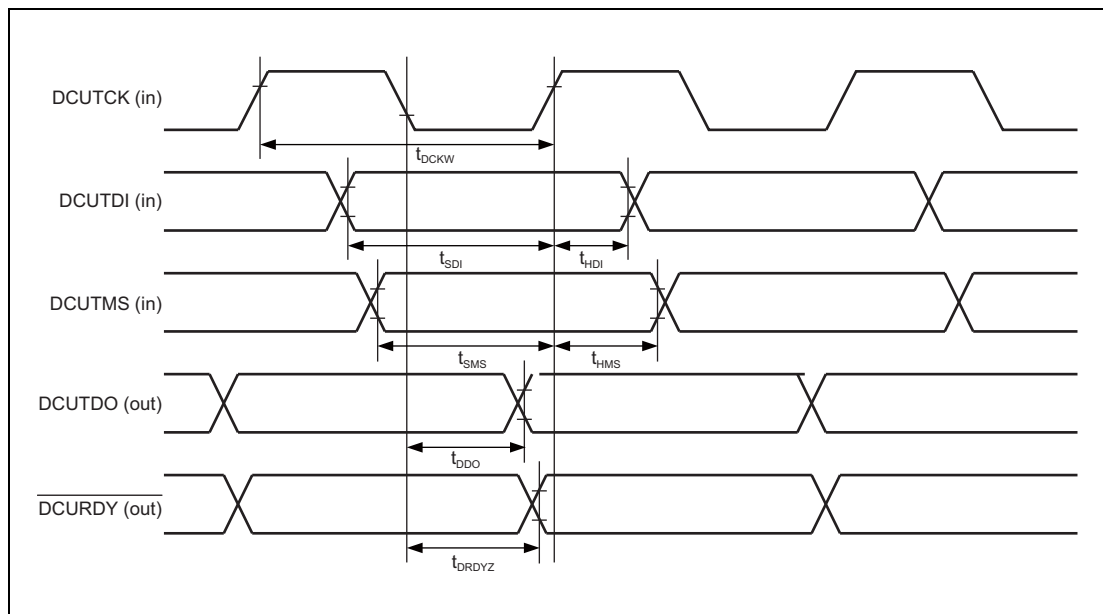
<Input buffer>

DCUTDI, DCUTCK, DCUTMS, $\overline{\text{DCUTRST}}$: TTL

<Output driver strength>

DCUTDO, $\overline{\text{DCURDY}}$: Fast mode

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
DCUTCK cycle width	t_{DCKW}		50			ns
DCUTDI setup time (vs DCUTCK $\uparrow$)	t_{SDI}		12			ns
DCUTDI hold time (vs DCUTCK $\uparrow$)	t_{HDI}		3			ns
DCUTMS setup time (vs DCUTCK $\uparrow$)	t_{SMS}		12			ns
DCUTMS hold time (vs DCUTCK $\uparrow$)	t_{HMS}		3			ns
DCUTDO delay time ($\downarrow$ DCUTCK)	t_{DDO}		0		20	ns
$\overline{\text{DCURDY}}$ delay time ($\downarrow$ DCUTCK)	t_{RDYZ}		0		20	ns



1.23.2 LPD (4 pin) Interface Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 100 pF

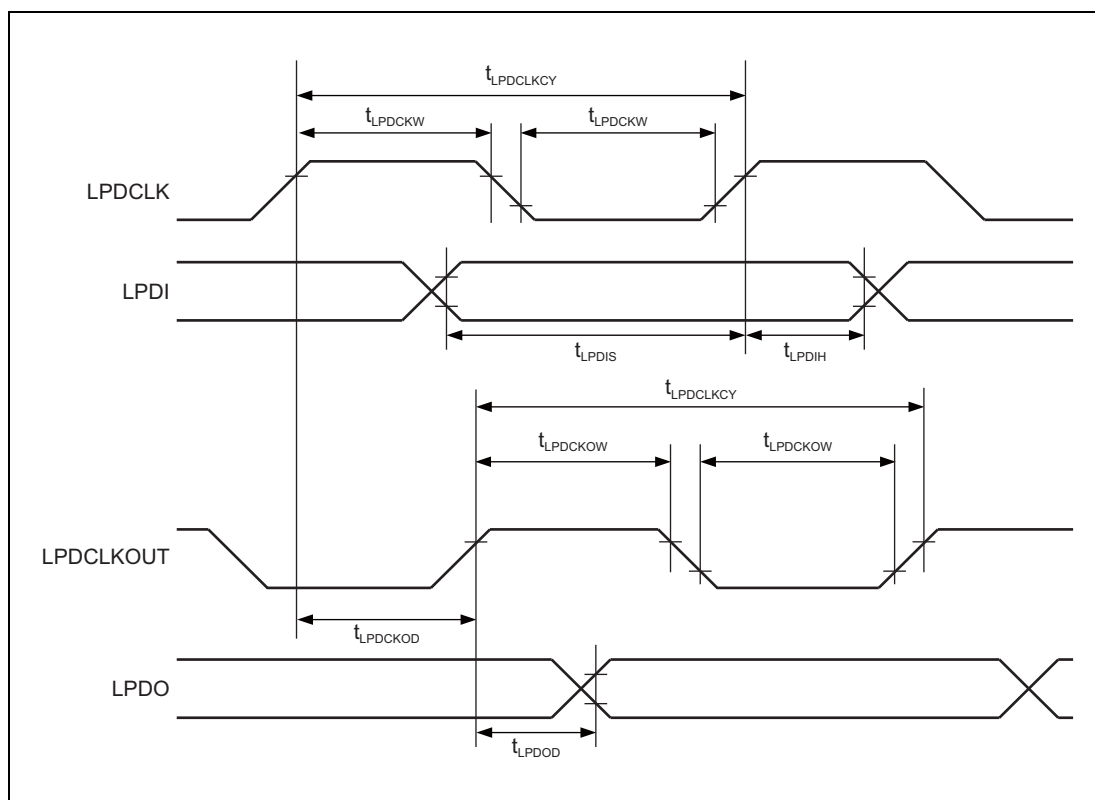
<Input buffer>

LPDCLK, LPDI: TTL

<Output driver strength>

LPDCLKOUT, LPDO: Fast mode

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
LPDCLK cycle time/ LPDCLKOUT cycle time	$t_{LPDCLKCY}$		83.3 (max.12MHz)			ns
LPDCLK High-level width/ LPDCLK Low-level width	t_{LPDCKW}		$0.5 \times t_{LPDCLKCY} - 10$			ns
LPDCLKOUT High-level width/ LPDCLKOUT low-level width	$t_{LPDCKOW}$		$t_{LPDCKW} - 10$			ns
LPDI setup time (LPDCLK ↑)	t_{LPDIS}		41			ns
LPDI hold time (LPDCLK ↑)	t_{LPDIH}		3			ns
LPDCLK to LPDCLKOUT delay time	$t_{LPDCKOD}$				44	ns
LPDO delay time (LPDCLKOUT ↑)	t_{LPDOD}		0		15	ns



1.23.3 LPD (1 pin) Interface Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 50 pF

<Input buffer>

LPDIO: TTL

<Output driver strength>

LPDIO: Fast mode

<External pull-up resistor>

LPDIO: 4.7 k Ω to 10 k Ω

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
LPD (1 pin) Baud rate					2.0	Mbps

1.24 Flash Programming Characteristics

1.24.1 Code Flash

The code flash memory is shipped in the erased state. If the code flash memory is read where it has not been written after erasure (no write condition), an ECC error is generated, resulting in the occurrence of an exception.

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/- 30%, CISOVCL: 0.1μF +/- 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.13 Basic characteristics

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Operation frequency	f _{PCLK} *3	ECO line	4*4		40	MHz
Number of rewrites*1	CWRT	Data retention of 20 years*2	1000			times

Note 1. The number of rewrites is the number of erasures for each block. When the number of rewrites is "n" (n = 1000), the device can be erased "n" times for each block. For example, when a block of 32 KB is erased after 256 bytes of writing have been performed for different addresses 128 times, the number of rewrites is counted as 1. However, multiple writing to the same address is not possible with 1 erasure (overwriting prohibited).

Note 2. Retention period under average Ta = 85°C. This is the period starting on completion of a successful erasure of the code flash memory.

Note 3. f_{PCLK} = 1/2 f_{CPUCLK}: System operating frequency for internal flash.

Note 4. Only for program/erase operation.

Table 1.14 Programming characteristic

Item	Symbol	Condition	Block size	MIN.	TYP.	MAX.	Unit
Programming time	f _{PCLK} ≥ 20 MHz CWRT < 100 times		256 B		0.4*1	6*1	ms
			8 KB		20	90	ms
			32 KB		80	360	ms
			256 KB		0.6	2.7	s
			384 KB		0.9	4.1	s
			512 KB		1.2	5.4	s
	f _{PCLK} ≥ 20 MHz CWRT ≥ 100 times		256 B		0.5*1	7.2*1	ms
			8 KB		24	108	ms
			32 KB		96	432	ms
			256 KB		0.7	3.3	s
			384 KB		1.1	4.9	s
			512 KB		1.4	6.5	s
Erase time	f _{PCLK} ≥ 20 MHz CWRT < 100 times		8 KB		39	120	ms
			32 KB		141	480	ms
			256 KB		1.2	3.5	s
			384 KB		1.7	5.3	s
			512 KB		2.3	7	s
	f _{PCLK} ≥ 20 MHz CWRT ≥ 100 times		8 KB		47	144	ms
			32 KB		169	576	ms
			256 KB		1.4	4.2	s
			384 KB		2.1	6.3	s
			512 KB		2.7	8.4	s

Note 1. Only the processing time of the hardware. The overhead required by the software is not included.

1.24.2 Data Flash

The data flash memory is shipped in the erased state. If the data flash memory is read where it has not been written after erasure (no write condition), an ECC error is generated, resulting in the occurrence of an exception

Condition: REGVCC = EVCC = VPOC to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/- 30%, CISOVCL: 0.1μF +/- 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Table 1.15 Basic characteristics

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Operation frequency	f_{PCLK}^{*3}	ECO line	4 ^{*4}		40	MHz
Number of rewrites ^{*1}	CWRT	Data retention 20 years ^{*2}	125 k			times
		Data retention 3 years ^{*2}	250 k			times

Note 1. The number of rewrites is the number of erasures for each block. When the number of rewrites is "n" (n = 125000), the device can be erased "n" times for each block. For example, when a block of 64 bytes is erased after 4 bytes of writing have been performed for different addresses 168 times, the number of rewrites is counted as 1. However, multiple writing to the same address is not possible with 1 erasure (overwriting prohibited).

Note 2. Retention period under average Ta = 85°C. This is the period starting on completion of a successful erasure of the data flash memory.

Note 3. $f_{PCLK} = 1/2 f_{CPUCLK}$: System operating frequency for internal flash.

Note 4. Only for program/erase operation.

Table 1.16 Programming characteristics

Item	Symbol	Condition	Block size	MIN.	TYP.	MAX.	Unit
Programming time		$f_{PCLK} \geq 20$ MHz	4 B		0.16 ^{*1}	1.7 ^{*1}	ms
		$f_{PCLK} \geq 20$ MHz	32 KB		1.4	6.8	s
Erasure time		$f_{PCLK} \geq 20$ MHz	64 B		1.7 ^{*1}	10 ^{*1}	ms
		$f_{PCLK} \geq 20$ MHz	32 KB		0.9	5.2	s
Blank check time		$f_{PCLK} \geq 20$ MHz	4 B			30 ^{*1}	μs
			64 B			100 ^{*1}	μs
			32 KB			35.2	ms

Note 1. Only the processing time of the hardware. The overhead required by the software is not included.

1.24.3 Serial Programming Interface

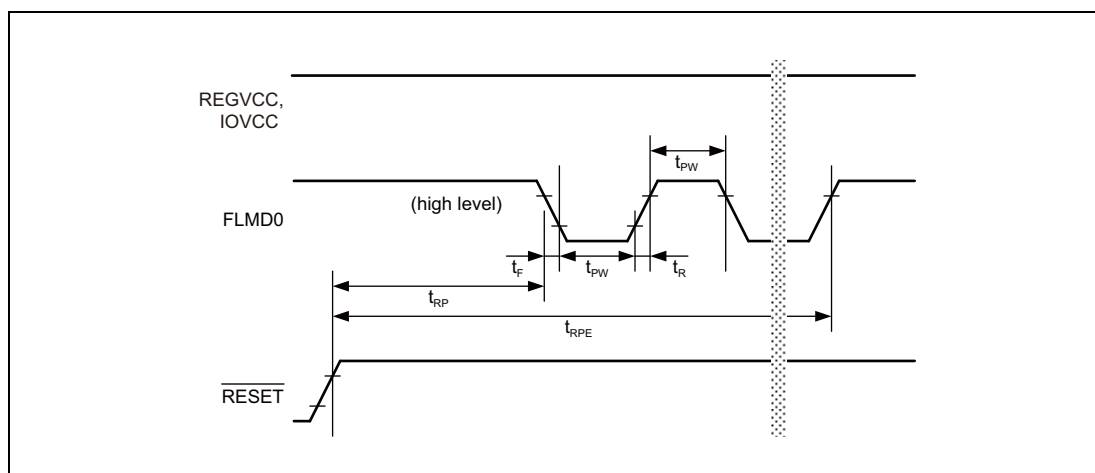
1.24.3.1 Serial Programmer Setup Timing

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/-30%, CISOVCL: 0.1μF +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
FLMD0 pulse input start time	t_{RP}		1.5			ms
FLMD0 pulse input end time	t_{RPE}				11.5	ms
FLMD0 low/high level width	t_{PW}		0.8			μs
FLMD0 rise time	t_R				20	ns
FLMD0 fall time	t_F				20	ns

NOTE

IOVCC: EVCC = A0VREF



1.24.3.2 FLSCI3 Interface

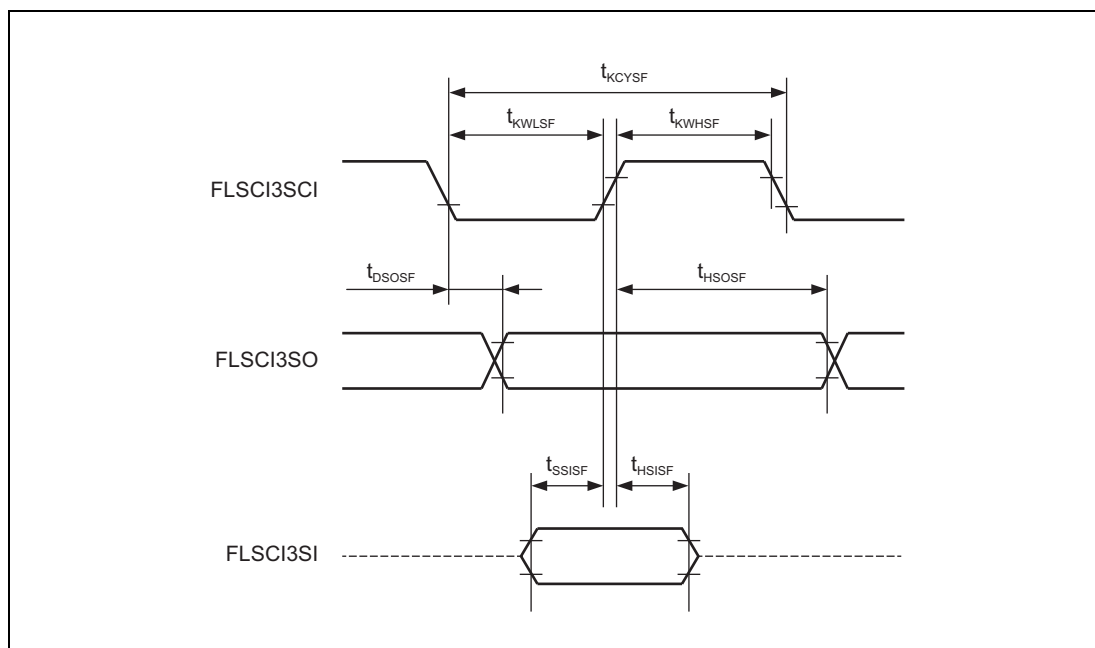
Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1 μ F +/-30%, CISOVCL: 0.1 μ F +/-30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
FLSCI3 transfer rate		1-wired UART mode			1	Mbps
		2-wired UART mode			2	Mbps
FLSCI3SCI cycle time	t_{KCYSF}	3-wired clock sync mode	200*1			ns
FLSCI3SCI high level width	t_{KWHSF}	3-wired clock sync mode	$t_{KCYSF} / 2 - 15$			ns
FLSCI3SCI low level width	t_{KWLSF}	3-wired clock sync mode	$t_{KCYSF} / 2 - 15$			ns
FLSCI3SI setup time (vs. FLSCI3SCI)	t_{SSISF}	3-wired clock sync mode	55			ns
FLSCI3SI hold time (vs. FLSCI3SCI)	t_{HSISF}	3-wired clock sync mode	55			ns
FLSCI3SO output delay (vs. FLSCI3SCI)	t_{DSOSF}	3-wired clock sync mode Not continuous transfer (data: 1st bit)			0	ns
		3-wired clock sync mode Not continuous transfer (data: except 1st bit)			$-t_{KWHSF} + 3$ $\times t_{Pcyc} + 36$	ns
FLSCI3SO hold time (vs. FLSCI3SCI)	t_{HSOSF}	3-wired clock sync mode	$2 \times t_{Pcyc}$			ns

Note 1. Input the external clock that is more than 6 clocks of PCLK.

NOTE

t_{Pcyc} is period of PCLK.



1.25 A/D Converter Characteristics

Condition: REGVCC = EVCC = 3.0 V to 5.5 V, A0VREF = 3.0 V to 5.5 V,
 AWOVSS = ISOVSS = EVSS = A0VSS = 0 V,
 CAWOVCL: 0.1μF +/- 30%, CISOVCL: 0.1μF +/- 30%, Ta = -40 to (depend on the product) °C,
 CL = 30 pF

(1/3)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Conversion clock	ADCLKn	T&H is not used	8 ^{*3}		40	MHz
		T&H used	16		40	MHz
Resolution	RESn	12-bit mode	12	12	12	bit
		10-bit mode	10	10	10	bit
Conversion time	t _{CONn}	ADCA _n SMPCR.SMPT[7:0] = 12 H (40 cycle) (8 MHz ^{*3} × ADCLKn × 32 MHz), External MPX is not used	1.25		5	μs
		ADCA _n SMPCR.SMPT[7:0] = 18 H (46 cycle) (8 MHz ^{*3} × ADCLKn × 40 MHz), External MPX is not used	1.15		5.75	μs
		ADCA _n SMPCR.SMPT[7:0] = 12 H (80 cycle) (8 MHz ^{*3} × ADCLKn × 32 MHz), External MPX is used	2.5 ^{*4}		10	μs
		ADCA _n SMPCR.SMPT[7:0] = 18 H (92 cycle) (8 MHz ^{*3} × ADCLKn × 40 MHz), External MPX is used	2.3 ^{*4}		11.5	μs
Sampling time	t _{SMP}	ADCA _n SMPCR.SMPT[7:0] = 12 H (18 cycle) (8 MHz ^{*3} × ADCLKn × 32 MHz)	0.56		2.25	μs
		ADCA _n SMPCR.SMPT[7:0] = 18 H (24 cycle) (8 MHz ^{*3} × ADCLKn × 40 MHz)	0.6		3	μs
Overall error ^{*1}	TOEn	12-bit mode	AnVREF = 4.5 V to 5.5 V	ADCA _n Im (w/o T&H)	±4.0	LSB
				ADCA0I0,2,4 (w/ T&H)	±6.0	LSB
			AnVREF = 3.6 V to 4.5 V	ADCA _n Im (w/o T&H)	±6.0	LSB
				ADCA0I0,2,4 (w/ T&H)	±8.0	LSB
		10-bit mode	AnVREF = 3.0 V to 3.6 V	ADCA _n Im (w/o T&H)	±8.0	LSB
				ADCA0I0,2,4 (w/ T&H)	±10.0	LSB
			AnVREF = 4.5 V to 5.5 V	ADCA _n Im	±1.0	LSB
				ADCA _n ImS	±2.0	LSB
			AnVREF = 3.6 V to 4.5 V	ADCA _n Im	±1.5	LSB
				ADCA _n ImS	±2.5	LSB
			AnVREF = 3.0 V to 3.6 V	ADCA _n Im	±2.0	LSB
				ADCA _n ImS	±3.0	LSB
Analog input voltage	VAIN0SN	ADCA _n Im	T&H not used	AnVSS	AnVREF	V
		ADCA0I0,2,4	T&H used	0.2	A0VREF - 0.2	V
		ADCA0ImS	A0VREF ≥ EVCC	A0VSS	EVCC	V
			A0VREF < EVCC	A0VSS	A0VREF	V
Operation current	IA0VREF	T&H not used		1.1	3.0	mA
		T&H used (max. 3 pins)			*2	mA
STOP, DeepSTOP, Cyclic STOP current (@LPS is stopped)	IA0VREFS			1	10	μA
T&H current	ITH			0.5	1.3	mA/ ch
T&H sampling time	t _{THSMP}		450			ns
T&H hold time	t _{THHOLD}				10	μs
Set up time of self diagnosis voltage circuit	t _{BOOT}		500			ns
Set up time of self diagnosis voltage level	t _{OUT}		500			ns
Pull-down resistor for discharge mode		ADCA _n Im pins	350	500	650	kΩ
		ADCA _n ImS pins	100	215	800	kΩ

(2/3)

Item	Symbol	Condition			MIN.	TYP.	MAX.	Unit	
Accuracy of self-diagnosis function	TESH0SN	12bit mode	Self-diagnosis voltage level = AnVREF		4015- TOEn		4095	–	
			Self-diagnosis voltage level = 2/3AnVREF		2651- TOEn	2731	2811+ TOEn	–	
			Self-diagnosis voltage level = 1/2AnVREF		1968- TOEn	2048	2128+ TOEn	–	
			Self-diagnosis voltage level = 1/3AnVREF		1285- TOEn	1365	1445+ TOEn	–	
			Self-diagnosis voltage level = AnVSS		0		80+ TOEn	–	
		10bit mode	Self-diagnosis voltage level = AnVREF		1003- TOEn			1023	–
			Self-diagnosis voltage level = 2/3AnVREF		663- TOEn	683	703+ TOEn	–	
			Self-diagnosis voltage level = 1/2AnVREF		492- TOEn	512	532+ TOEn	–	
			Self-diagnosis voltage level = 1/3AnVREF		321- TOEn	341	361+ TOEn	–	
			Self-diagnosis voltage level = AnVSS		0		20+ TOEn	–	
Integral nonlinearity error* ¹	ILEn	12-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm (w/o T&H)			±2.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±3.0	LSB	
			AnVREF = 3.6 V to 4.5 V	ADCAAnIm (w/o T&H)			±3.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±4.0	LSB	
			AnVREF = 3.0 V to 3.6 V	ADCAAnIm (w/o T&H)			±4.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±5.0	LSB	
		10-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm			±1.0	LSB	
				ADCAAnImS			±2.0	LSB	
			AnVREF = 3.0 V to 4.5 V	ADCAAnIm			±1.5	LSB	
				ADCAAnImS			±2.5	LSB	
Differential nonlinearity error* ¹	DLEn	12-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm (w/o T&H)			±1.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±2.0	LSB	
			AnVREF = 3.6 V to 4.5 V	ADCAAnIm (w/o T&H)			±3.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±4.0	LSB	
			AnVREF = 3.0 V to 3.6 V	ADCAAnIm (w/o T&H)			±3.0	LSB	
				ADCA0I0,2,4 (w/ T&H)			±4.0	LSB	
		10-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm			±1.0	LSB	
				ADCAAnImS			±1.5	LSB	
			AnVREF = 3.0V to 4.5V	ADCAAnIm			±1.0	LSB	
				ADCAAnImS			±2.0	LSB	
Zero scale error (offset error)* ¹	ZSEn	12-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm (w/o T&H)			±3.5	LSB	
				ADCA0I0,2,4 (w/ T&H)			±5.5	LSB	
			AnVREF = 3.6 V to 4.5 V	ADCAAnIm (w/o T&H)			±5.5	LSB	
				ADCA0I0,2,4 (w/ T&H)			±7.5	LSB	
			AnVREF = 3.0 V to 3.6 V	ADCAAnIm (w/o T&H)			±7.5	LSB	
				ADCA0I0,2,4 (w/ T&H)			±9.5	LSB	
		10-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAAnIm			±0.5	LSB	
				ADCAAnImS			±1.5	LSB	
			AnVREF = 3.6 V to 4.5 V	ADCAAnIm			±1.0	LSB	
				ADCAAnImS			±2.0	LSB	
AnVREF = 3.0 V to 3.6 V	ADCAAnIm			±1.5	LSB				
	ADCAAnImS			±2.5	LSB				

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Item	Symbol	Condition			MIN.	TYP.	MAX.	Unit
Full scale error* ¹	FSEn	12-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAnIm (w/o T&H)			±3.5	LSB
				ADCA0I0,2,4 (w/ T&H)			±5.5	LSB
			AnVREF = 3.6 V to 4.5 V	ADCAnIm (w/o T&H)			±5.5	LSB
				ADCA0I0,2,4 (w/ T&H)			±7.5	LSB
			AnVREF = 3.0 V to 3.6 V	ADCAnIm (w/o T&H)			±7.5	LSB
				ADCA0I0,2,4 (w/ T&H)			±9.5	LSB
		10-bit mode	AnVREF = 4.5 V to 5.5 V	ADCAnIm			±0.5	LSB
				ADCAnImS			±1.5	LSB
			AnVREF = 3.6 V to 4.5 V	ADCAnIm			±1.0	LSB
				ADCAnImS			±2.0	LSB
			AnVREF = 3.0 V to 3.6 V	ADCAnIm			±1.5	LSB
				ADCAnImS			±2.5	LSB

n = 0

Note 1. This does not include quantization error.

Note 2. $3.0 + 1.3 \times (\text{the number of used T\&H})$

Note 3. Include the oscillation accuracy of HS IntOSC.

Note 4. When the external multiplexer is used, the detail time of A/D conversion is MPX setup time, sampling time and successive approximation time. MPX setup time is same as "sampling time + successive approximation time".

Note 5. Conversion accuracy when ADCA0ImS terminal is converted in 12-bit mode:
Conversion accuracy can be applied if lower 2-bit is ignored from conversion result.**CAUTIONS**

When an external digital pulse is applied to AP0, P8 and P9 pins during an A/D conversion this may lead to an A/D conversion result with a larger conversion error as expected due to the coupling noise of the external digital pulse.

The same behavior may apply when the digital buffer is used as output pin. For the output port the potential degradation increases with the driven total output current of the port. In addition the conversion resolution may drop if the output current fluctuates at adjacent pins due to the coupling effect of the external circuit connected to these port pins.

1.26 Injection Currents

For the injection current, there are two type specifications. These type are depend on Package, Flash size and Product name. These relationships are shown as the following table.

Flash Size	Product Name	Applicable Type
512 KB/ 384 KB/ 256 KB	Except below products	Type 1
	R7F701xxxxAFP#YJ1 R7F701xxxxAFP#YJ2 R7F701xxxxAFP#YK2 R7F701xxxxAFP#YB2 R7F701xxxxAFP#AA2 R7F701xxxxAFP#KA2	Type 2

Table 1.17 Definition of Pin Group

Symbol	Power Supply for Pin Group	Pin for Type 1 Products	Pin for Type 2 Products
PgE	EVCC, EVSS	JP0, P0, P10, P11	JP0, P0, P10, P11
PgE'	EVCC, EVSS	P8, P9	Not Available* ¹
PgA0	A0VREF, A0VSS	AP0	AP0

Note 1. Do not apply an overvoltage on P8 and P9 pins.

1.26.1 Absolute Maximum Ratings

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Positive overload current VIN > VCC	I _{INJPM}	PgE	Per pin		10	mA
			total		60	mA
		PgE'	Per pin		10	mA
			Total		60	mA
		PgA0	Per pin		10	mA
			total		60	mA
Negative overload current VIN < VSS	I _{INJNM}	PgE	Per pin		-10	mA
			total		-60	mA
		PgE'	Per pin		-10	mA
			Total		-60	mA
		PgA0	Per pin		-10	mA
			total		-60	mA

CAUTIONS

1. The DC injection current (total) must satisfy the specifications of the injection current per pin.
2. In case of injected current for PgA0, TESH0SN cannot be kept. Its deviating value will increase sharply with increasing absolute value of injection current.

1.26.2 DC Characteristics for Overload Current

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Positive overload current VIN > VCC	I _{INJP}	PgE	Per pin		2	mA
			Total		50	mA
		PgE'	Per pin		3	mA
			Total		20	mA
		PgA0	Per pin		3	mA
			Total		20	mA
Negative overload current VIN < VSS	I _{INJN}	PgE	Per pin		-2	mA
			Total		-50	mA
		PgE'	Per pin		-3	mA
			Total		-20	mA
		PgA0	Per pin		-3	mA
			Total		-20	mA

NOTE

These specifications are not tested on sorting and are specified based on the device characterization.

1.26.3 DC Characteristics for Pins Influenced by Injected Current on an Adjacent Pin

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Leakage current coupling factor for positive overload current	K _{INJP}	PgE	Per pin		3.0×10^{-6}	—
		PgE'	Per pin		3.0×10^{-6}	—
		PgA0	Per pin		4.8×10^{-6}	—
Leakage current coupling factor for negative overload current	K _{INJN}	PgE	Per pin		7.5×10^{-6}	—
		PgE'	Per pin		7.5×10^{-6}	—
		PgA0	Per pin		2.6×10^{-6}	—

NOTES

1. This is reference value.
2. An overload current through a pin will cause a certain error current in the adjacent pins. This error current must be added to the respective leakage current (ILIH or ILIL) of the adjacent pins.
3. The amount of error leakage current depends on the overload current and is defined by the overload coupling factor K_{INJ}.
The total current through a pin is:

$$|I_{\text{total}}| = |ILIH \text{ or } ILIL| + (|I_{\text{INJn}}| \times K_{\text{INJn}})$$

1.26.4 AD Characteristics for Pins Influenced by Injected Current on an Adjacent

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Degradation of overall error*1	I_{INJP}	3 mA per pin	ADCA _n Im		±1.3	LSB
			ADCA _n ImS		±1.3	LSB
		Total 20 mA	ADCA _n Im		±3.8	LSB
			ADCA _n ImS		±3.8	LSB
	I_{INJN}	-3 mA per pin	ADCA _n Im		±1.4	LSB
			ADCA _n ImS		±1.4	LSB
		Total -20 mA	ADCA _n Im		±4.5	LSB
			ADCA _n ImS		±4.5	LSB

n = 0

Note 1. This value is the degradation by injected current on an adjacent pin. Therefore, this value is added to the specification of A/D converter's overall error defined separately as the electrical specifications.

Note 2. This is reference value.

CAUTION

When there is an increased leakage current on the analog input pins, based on currents injected into the pins adjacent to the converted channel, the effect on the ADC accuracy depends on the external analog source impedance.

[Example] Conditions: A0VREF = 5.0 V, external analog source impedance = 10 kΩ.

If there is a leakage current of 1μA by injected current, the effect on the ADC accuracy is $1 (\mu A) \times 10 \text{ k} (\Omega) / 5 \text{ (V)} = 0.2\% \text{FSR}$

1.27 Thermal Characteristics

1.27.1 Parameters

Item	Symbol	Estimate	Unit	Note
Thermal Resistance	Θ_{ja}	57	°C/W	Conforming to JESD51-7 (4 layers)
Thermal Characterization Parameter	ψ_{jb}	41	°C/W	Conforming to JESD51-7 (4 layers)

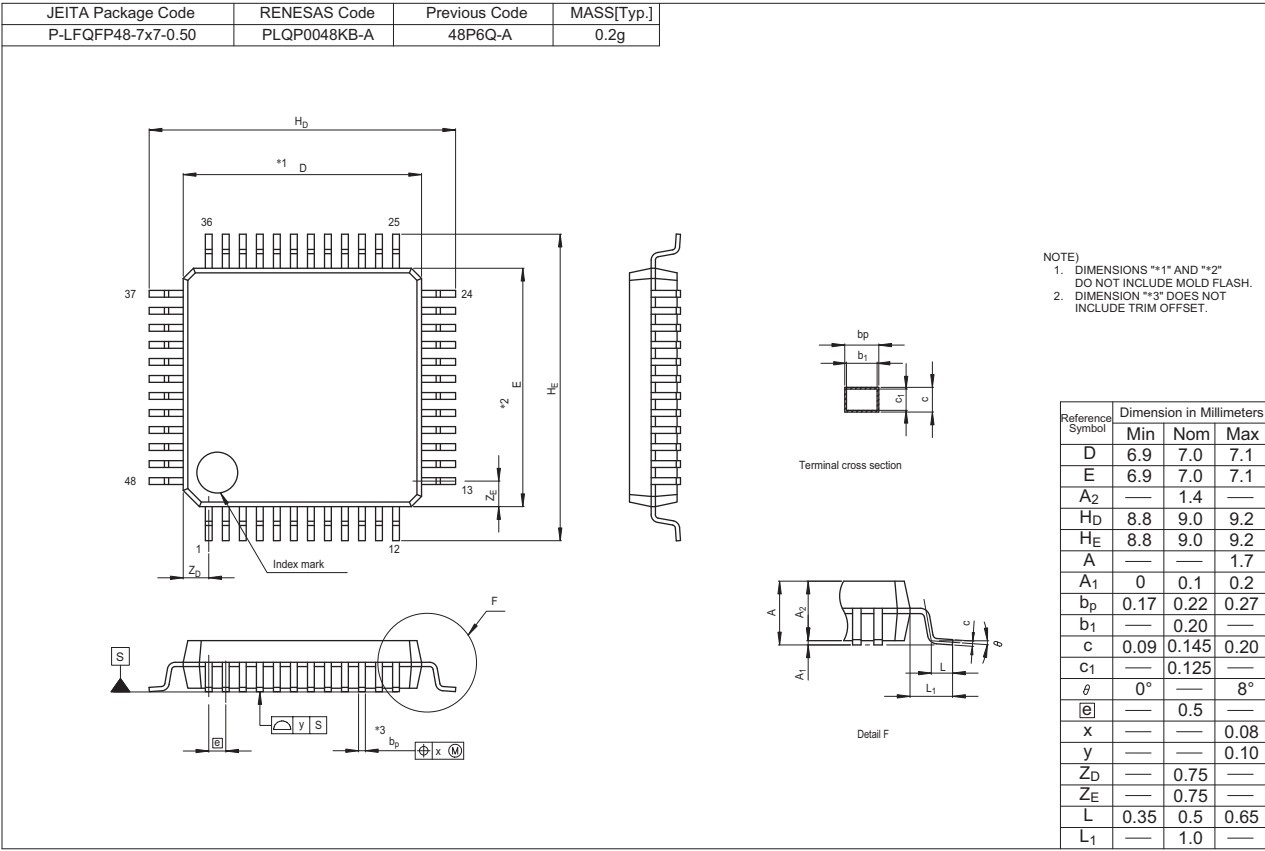
Note: The thermal resistance depend on the usage environment.

1.27.2 Assumed Board

Conforming to JESD51-7 (4 layers)

	Board size (mm)		Area (mm ²)
	X	Y	
Board	76.2	114.3	8709.66
Remaining copper rates	Thickness of conductors		
50-95-95-50%	70-35-35-70 μ m		

Section 2 Package Dimensions



REVISION HISTORY

RH850/F1L (48 pin Version) Datasheet

Rev.	Date	Description	
		Page	Summary
0.10	Jul 11, 2013	—	First Edition issued
0.81	Dec 03, 2013	1	1.1.2.1 Common Conditions, Power supply, Capacitance of the internal regulator changed
		4	1.2.3 Port Current changed
		5	1.3 Capacitance, note 1 and note 2 changed
		5	1.4 Operational Condition, note 2 changed
		6	1.5 Oscillator Characteristics, CAUTION changed
		7	1.7 PLL Characteristics changed
		7	1.8 Regulator Characteristics changed; note 1 changed
		8, 9	1.9 Pin Characteristics changed, note 2 and note 6 changed
		10	1.10 Power Supply Currents changed
		12	1.11 Interrupt Timing changed
		13	1.12 Power Up/Down Timing, timing diagram changed
		19	1.19.2 CSIH Timing, CAUTION changed
		32	1.23 POC Characteristics changed
		33	1.24 LVI Characteristics changed
		33	1.25 VLVI Characteristics changed
		35	1.27 Core Voltage Monitor Characteristics changed
		35, 36	1.28 A/D Converter Characteristics changed
		37	1.29 Flash Characteristics, (1) Code Flash, Table 1.9 Basic Characteristics, note 2 changed
		37	1.29 Flash Characteristics, (1) Code Flash, Table 1.10 Programming Characteristics changed
		38	1.29 Flash Characteristics, (2) Data Flash, Table 1.11 Basic Characteristics, note 2 changed
		38	1.29 Flash Characteristics, (2) Data Flash, Table 1.12 Programming Characteristics, note 2 changed
		39, 40	1.31 Injection Currents, added
1.00	Oct 29, 2014	All	Arrangement of sections
		1 to 4	Product Introduction, added
		5	1.1 Overview, changed
		5	1.1.1 Pin Groups, changed
		5	1.1.2.1 Common Conditions, changed
		7	1.2 Absolute Maximum Ratings, CAUTIONS 1., changed
		7	1.2.2 Port Voltages, changed
		9	1.2.4 Temperature Condition, changed
		9	1.3 Capacitance, changed
		10	1.4 Operational Condition, changed
		11	1.5 Oscillator Characteristics, changed; one figure added
		12	1.6 Internal Oscillator Characteristics, changed
		12	1.7 PLL Characteristics, changed
		13	1.8 Power Management Characteristics, subsection added
		13	1.8.1 Regulator Characteristics, changed
		14 to 16	1.8.2 Voltage Detector (POC, LVI, VLVI, CVM) Characteristics, added

Rev.	Date	Description	
		Page	Summary
1.00	Oct 29, 2014	17 to 19	1.8.3 Power Up/Down Timing, changed; Table 1.2 Boundary scan mode in case of using $\overline{\text{RESET}}$ pin added; two figures added
		20	1.8.4 CPU Reset Release Timing, added
		21	1.9 Pin Characteristics, changed
		23	1.9.1 Output Current, subsection added
		24, 25	1.10 Power Supply Currents, changed
		26	1.11 Interrupt Timing, changed; two figures added
		27	1.12 $\overline{\text{RESET}}$ Timing, changed; figure added
		28	1.13 CSCXFOUT Timing, changed
		29	1.14 Mode Timing, changed; two figures added
		30, 31	1.15 Timer Timing, changed; figure added
		32	1.16 RLIN2/RLIN3 Timing, changed
		32	1.17 RS-CAN Timing, changed
		33	1.18.1 CSIG Timing, changed
		34, 35	1.18.2 CSIH Timing, changed
		44	1.19 RIIC Timing, changed
		47	1.20 ADTRG Timing, changed
		47	1.21 Key Return Timing, changed; figure added
		48	1.22 $\overline{\text{DCUTRST}}$ Timing, added
		49	1.23 Debug Interface Characteristics, added
		49	1.23.1 NEXUS Interface Timing, added
		50	1.23.2 LPD (4 pin) Interface Timing, added
		51	1.23.3 LPD (1 pin) Interface Timing, added
		52, 53	1.24.1 Code Flash, subsection number changed, description changed
		54	1.24.2 Data Flash, subsection number changed, description changed
		55	1.24.3.1 Serial Programmer Setup Timing, changed
		56	1.24.3.2 FLSCI3 Interface, added
		57 to 59	1.25 A/D Converter Characteristics, changed
		60	1.25.1 Equivalent Circuit of the Analog Input Block, changed
		61	1.26 Injection Currents, changed
		61	1.26.1 Absolute Maximum Ratings, changed
		61	1.26.2 DC Characteristics for Overload Current, changed
		62	1.26.3 DC Characteristics for Pins Influenced by Injected Current on an Adjacent Pin, changed
		63	1.26.4 AD Characteristics for Pins Influenced by Injected Current on an Adjacent, subsection added; description changed
		—	1.30.4 A/D Diagnosis Function Influenced by Injected Current, deleted
1.10	Dec 25, 2014	5	1.1.2.1 Common Conditions: Changed
		10	1.4 Operational Condition: Note 3 changed
		11	1.5 Oscillator Characteristics: Changed, figures of "MainOSC" changed
		12	1.7 PLL Characteristics: Changed
		14 to 16	1.8.2 Voltage Detector (POC, LVI, VLVI, CVM) Characteristics: Changed, figures of "POC" changed, and figure of "CVM" added
		17	Table 1.1 In case the $\overline{\text{RESET}}$ pin is used: Changed
		18	Table 1.2 Boundary scan mode in case of using $\overline{\text{RESET}}$ pin: Changed

Rev.	Date	Description	
		Page	Summary
1.10	Dec 25, 2014	19	Table 1.3 In case the $\overline{\text{RESET}}$ pin is not used and fixed to high level by pull-up*1: Changed
		20	Table 1.4 In case the $\overline{\text{RESET}}$ pin is not used: Changed
		21 to 23	1.9 Pin Characteristics: Changed
		30, 31	1.16 Timer Timing: Changed, figure changed
		44	1.20 RIIC Timing: Description of condition changed
		44	Table 1.10 RIIC Timing (Normal Mode): Changed
		45, 46	Table 1.11 RIIC Timing (Fast Mode): Changed, figure changed
		52	1.25.1 Code Flash: Description of condition changed
		52	Table 1.13 Programming characteristic: Changed
		53	1.25.2 Data Flash: Description of condition changed
		53	Table 1.15 Programming characteristics: Changed
		55	1.25.3.2 FLSCI3 Interface: Figure changed
		56	1.26 A/D Converter Characteristics: Changed
		60	1.27 Injection Currents: Changed
		60	1.27.1 Absolute Maximum Ratings: Changed
		61	1.27.2 DC Characteristics for Overload Current: Changed
		61	1.27.3 DC Characteristics for Pins Influenced by Injected Current on an Adjacent Pin: Changed
1.20	Jun 30, 2015	1	typo (master/a slave → master/slave)
		1,11,26,30	description alignment (MainOsc → MainOSC)
		5,11,12,14,17,21,23,27,28,30,3132,34,35,36,46,49,50,51,52,53,54,55,56,57,58	description alignment (AWOVCL → CAWOVCL, ISOVCL → CISOVCL)
		8	correction , listed Port
		10,12,25,26,27,30,60	description alignment (IntOsc → IntOSC)
		11	correction of "MainOSC oscillation operation point" level (MIN:2.4->empty, TYP.:empty->0.5xREGVCC)
		11	Addition of "MainOSC oscillation amplitude"
		11	additon precise conditions (such as "Crystal", "Ceramic")
		11	Improvement of figures (MainOSC)
		13	addition of "Conditon for AWOVCL"(empty → AWOVCL pin)
		13	addition of "Conditon for ISOVCL"(empty → ISOVCL pin)
		13	correction of "Equivalent series resistance ..." (for AWO area → for CAWOVCL)
		13	correction of "Equivalent series resistance ..." (for ISO area → for CISOVCL)
		14	VCVML:1.00 → 1.1 (MIN>), 1.05 → 1.15 (TYP.), 1.10 → 1.20 (MAX.)
		14	correction: (Note 1-5) "=" → "-"
		14	description alignment for "Note 5": "=0.02 V/ms to 500 V/ms" → ":0.02 V/ms ≤ T _{VS} ≤ < 500 V/ms")
		16	correction of name for REGVCC level (VLVI → VVLVI)
		17,18	correction of Power Up/Down timing (FLMD0 hold time, FLMD0 setup time)
		17,18	case separation for timing whether in serial programming mode or except serial programming mode
		17	removed "FLMD0,1 hold time" spec
		17	changed the condition of RESET edge from rise to fall for "FLMD0 setup time"
		17	changed the unit for "FLMD0 setup time" from "ms" to "us"

Rev.	Date	Description	
		Page	Summary
1.20	Jun 30, 2015	17	removed "Note 2" which explained handling of FLMD0 and FLMD1
		18	correction of description for "Condition" of t_{DPOr} ("=" → "·")
		19	correction of description for "Condition" of t_{HPOMD} ("=" → "·")
		19	improvement of figure for mode insertion ($V_{POC(max.)}$, t_{VS})
		20	Improvement of explanation for "Note 1" (added "include self-programming mode")
		21	addition " V_{IL} " in figure
		21	correction of description for "Condition" of t_{DPOr} ("=" → "·")
		22	correction, RESET/SHMT2 : with *4 → w/o *4
		22	Pin Characteristics table have been updated
		22	correction, "resistor" → "resistors" for Note 1.
		22	addition of "Caution"
		25	description alignment, "Deep STOP" → "DeepSTOP"
		26	description alignment LS-IntOSC → LS IntOSC
		27	description alignment High Speed Internal Oscillator → HS IntOSC Low Speed Internal Oscillator → LS IntOSC
		30	description alignment with another F1x products. separation for high level width and low level width. Addition Note 1 to 4.
		35	addition of t_{WENTI} , t_{WENTIL}
		27,28,31,32,49,50	addition for Note 2 (page 27,28,31,49,50), Note 4 (page 32), "Noise such as the figure can be filtered"
		35	changed CSIGNRYO output delay spec
		36	correction of register name which is used as "Condition" CSIHnCTL1.CSIHnDAP → CSIHnCFGx.CSIHnDAP
		36	description alignment of bit number ("CSIHnCFG0-7.CSIHnID2-0" → "CSIHnCFGx.CSIHnID[2:0]") ("CSIHnCFG0-7.CSIHnSP3-0" → "CSIHnCFGx.CSIHnSPx[3:0]") ("CSIHnCFG0-7.CSIHnHD3-0" → "CSIHnCFGx.CSIHnHDx[3:0]")
		36	correction of register name which is used in "CAUTION" CSIHnCFG7-0.CSIHnCKP0-7 → CSIHnCFGx.CSIHnCKPx
		37	changed CSIHnRYO output delay spec
		40	CSSETUP → CSSETUP
		41	CSHOLD → CSHOLD
		46,47	removed "0" as MIN. of RIIC0SCL clock period (Normal Mode) removed "0" as MIN. of RIIC0SCL clock period (Fast Mode)
		53	description alignment 1-pin → 1 pin
		54,55	addition "Note 4. Only for program/erase operation."
		56	removed t_{DPOr} , t_{SMDR} , t_{HMDR}
		56	improvement of time chart
		58	description alignment, "CyclicSTOP" → "Cyclic STOP"
		59	description alignment : (LSB → -)
		60	addition "Note 5", CAUTIONS sentence 2
		61	removed "1.26.1 Equivalent Circuit of the Analog Input Block"
		61	correction of Product Name list and Type
		61	addition of "Note 1" for PgE'
		63	addition of "n = 0"
		67	addition "1.32 Thermal Characteristics"

Rev.	Date	Description	
		Page	Summary
1.30	Dec 09, 2015	12	addition spec: "V _{MOSCSP} " changed spec : 1*3→0.4 x REGVCC - 0.2*3
		12	changed figure: MainOSC: Addition (V _{MOSCSP})
		15	addition of Note 8 for Detection voltage
		18	removed FLMD0 setup time
		18	addition of Note 2 for figure
		23	correction, P10_8 to P10_14/Drive Strength : "Slow/Fast" → "Slow"
		63	correction of CAUTION
		67	description alignment of header "Parameter" → "Symbol"
1.31	Apr 20, 2016	13	addition of Note 3 of 1.8.1 Regulator Characteristics
		17	correction of Note 2 in 1.8.3 Power Up/Down Timing
		22	correction of Port Output Drive Strength Mode of P10_8 to P10_10 in 1.9 Pin Characteristics
		58	correction of ADCLKn spec in 1.25 A/D Converter Characteristics
		60	correction of caution of 1.25 A/D Converter Characteristics

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