RZ/N2H Group

Dual Encoder sample program

Summary

This document describes the RZ/N2H Dual Encoder sample program package.

For EnDat 2.2 communication protocol specifications and encoder specifications (EQN1035), contact HEIDENHAIN GmbH.

Functionality Checked Device

RZ/N2H Evaluation Board (RTK9RZN2Hxxxxxxxxx)

Contents

1. Package Contents

This package contains the following contents.
The RZ/N2H encoder interface supports up to 13 axes, but the sample program uses a total of 2 axes, with one axis using A-format and one axis using EnDat. If you use with 3 or more axes simultaneously, modify the sample program to support required axes.
This sample program operation was checked with an A-format Ver.2.0 encoder in a one-to-one connection configuration. Operation with bus connection encoder is not checked. Operation with A-format Ver.1.0 encoder is not supported.

1.1 Software

- Source code

No.	Name	Version number
1	RZ/N2H Dual Encoder sample program (CR52 ver.*)	4.0
2	RZ/N2H Dual Encoder sample program (CA55 ver.*)	4.0

Note: This sample program has a CR52 version that runs on the CPU core Cortex-R52 and a CA55 version that runs on the CPU core Cortex-A55. CR52 ver. and CA55 ver. are descriptions of the respective version.

1.2 Documents

No.	Document name	Version	File name
1	RZ/N2H Group Dual Encoder sample program Release Note	4.00	(j) r11an0999jj0400-rzn2h.pdf (e) r11an0999ej0400-rzn2h.pdf (this document)
2	RZ/N2H Group Dual Encoder sample program Application Note	4.00	(j) r11an0998jj0400-rzn2h-dual.pdf (e) r11an0998ej0400-rzn2h-dual.pdf

2. File Structure

The file structure and contents of this package are detailed below.

```
Top
├── r11an0999jj0400-rzn2h.pdf
├── r11an0999ej0400-rzn2h.pdf
└── workspace
    ├── Software
    │   ├── iccarm
    │   │   ├── RZ_N2H_CR52_dual.zip        : RZ/N2H Dual Encoder sample program set
    │   │   │                                 CR52 ver. (IAR)
    │   │   └── RZ_N2H_CA55_dual.zip        : RZ/N2H Dual Encoder sample program set
    │   │                                     CA55 ver. (IAR)
    │   └── gcc
    │       ├── RZ_N2H_CR52_dual.zip        : RZ/N2H Dual Encoder sample program set
    │       │                                 CR52 ver. (e2 studio)
    │       └── RZ_N2H_CA55_dual.zip        : RZ/N2H Dual Encoder sample program set
    │                                         CA55 ver. (e2 studio)
    └── Documents
        ├── r11an0998jj0400-rzn2h-dual.pdf
        └── r11an0998ej0400-rzn2h-dual.pdf
```

The file structure of the RZ_N2H_CR52_dual.zip and RZ_N2H_CA55_dual.zip is shown below.

```
Top folder
├── configuration.xml                       : FSP Configuration data
├── ( Build Tool Dependent Environment File )
└── src
    ├── hal_entry.c                         : Dual Encoder sample program
    ├── dual_main.c                         : Dual Encoder sample program
    ├── siochar.c                           : SCI_UART sample program
    ├── syscalls.c                          : SCI_UART sample program
    ├── sio_char.h                          : SCI_UART sample program
    └── drv
        ├── a_as
        │   ├── iodefine_a_as.h             : A_AS register definition file
        │   ├── r_a_as_rzt2.c               : A_AS driver file
        │   ├── r_a_as_rzt2_config.h        : A_AS driver file
        │   ├── r_a_as_rzt2_dat.h           : A_AS driver file
        │   ├── r_a_as_rzt2_if.h            : A_AS driver file
        │   ├── r_a_as_rzt2_private.h       : A_AS driver file
        │   └── a_format
        │       ├── r_a_format_rzt2.c       : A-format driver file
        │       ├── r_a_format_rzt2_config.h : A-format driver file
        │       └── r_a_format_rzt2_private.h : A-format driver file
        └── endat
            ├── iodefine_endat.h            : EnDat register definition file
            ├── r_endat_rzt2.c              : EnDat driver file
            ├── r_endat_rzt2_config.h       : EnDat driver file
            ├── r_endat_rzt2_dat.h          : EnDat driver file
            └── r_endat_rzt2_if.h           : EnDat driver file
```

3. About Dual Encoder Sample Program

This section contains information necessary to use the complete set of Dual Encoder sample program.

3.1 Software Information

3.1.1 Base OS

This sample program is OS-independent.

3.1.2 Memory Size

The memory size used by this sample program, the A-format driver, and the EnDat driver is shown in the following table. This table does not include the memory size used by the Flexible Software Package or the compiler's C language libraries.

(1) CR52 ver.

Items		Memory Size	
		EWARM [kBytes]	e² studio [kBytes]
A-format driver	Code	5.4	3.9
	Data (with initial value)	0.0	0.0
	Data (without initial value)	6.1	6.1
	Constant Data	0.3	0.2
EnDat driver	Code	5.6	3.8
	Data (with initial value)	0.0	0.0
	Data (without initial value)	0.8	0.8
	Constant Data	0.3	3.3
Sample program	Code	6.5	7.2
	Data (with initial value)	0.1	0.0
	Data (without initial value)	0.9	0.9
	Constant Data	3.1	0.2

(2) CA55 ver.

Items		Memory Size	
		EWARM [kBytes]	e² studio [kBytes]
A-format driver	Code	8.1	6.4
	Data (with initial value)	0.0	0.0
	Data (without initial value)	6.7	6.8
	Constant Data	0.4	0.4
EnDat driver	Code	8.6	5.9
	Data (with initial value)	0.0	0.0
	Data (without initial value)	1.0	1.0
	Constant Data	0.4	4.1
Sample program	Code	9.9	12.7
	Data (with initial value)	0.2	0.0
	Data (without initial value)	0.9	1.0
	Constant Data	3.4	0.3

3.2 Hardware Information

3.2.1 Device

RZ/N2H

3.2.2 Target Board

(1) Board Name

RZ/N2H Evaluation Board (RTK9RZN2Hxxxxxxxxx)

(2) Setting of Target Board

The target board configuration is as follows. Do not push SW4 while using channel AFMT14 / ENDAT_CH14.

DSW2-4: ON, DSW2-6: OFF

DSW5-1: OFF, DSW5-2: OFF, DSW5-7: OFF, DSW5-8: OFF

DSW7-1: OFF, DSW7-2: ON, DSW7-3: OFF, DSW7-4: ON

DSW12-5: ON, DSW12-6: OFF, DSW12-7: ON, DSW12-8: OFF

DSW13-1: OFF, DSW13-2: ON, DSW13-3: OFF, DSW13-4: ON, DSW13-7: ON, DSW13-8: OFF

DSW18-5: OFF, DSW18-6: ON

DSW19-3: OFF, DSW19-4: ON

DSW20-1: OFF, DSW20-3: OFF, DSW20-5: OFF

DSW21-2: OFF, DSW21-3: ON, DSW21-4: OFF, DSW21-5: ON, DSW21-6: OFF

DSW3-1: ON, DSW3-2: OFF, DSW3-3: ON, DSW3-6: OFF (Set xSPI1 boot mode)

JP8: Short between 2-3 pins (Set VDD1833_2 to 3.3 V)

JP9: Short between 2-3 pins (Set VDD1833_3 to 3.3 V)

JP23: Short between 1-2 pins, Open between 3-4 pins, and between 5-6 pins (Set VDD1833_6 to 3.3 V)

(3) Used Pin for Target Board

The correspondence between the pin used as the encoder I/F and the pin header of the target board is as follows. Channels AFMT8 / ENDAT_CH8, AFMT12 / ENDAT_CH12 and AFMT15 / ENDAT_CH15 are not available.

Channel	Pin Name	Pin Header	Input/ Output	Voltage Domain	Description
AFMT0 / ENDAT_CH0	ENCIFCK00 *2	CN44 #3	Output	VDD33	Clock output
	ENCIFOE00	CN44 #5	Output	VDD33	Data output enable
	ENCIFDO00	CN44 #7	Output	VDD33	Data output
	ENCIFDI00	CN44 #9	Input	VDD33	Data input
AFMT1 / ENDAT_CH1	ENCIFCK01 *2	CN44 #2	Output	VDD1833_5	Clock output
	ENCIFOE01	CN44 #4	Output	VDD1833_5	Data output enable
	ENCIFDO01	CN44 #6	Output	VDD33	Data output
	ENCIFDI01	CN44 #8	Input	VDD33	Data input
AFMT2 / ENDAT_CH2 *1	ENCIFCK02 *2	CN43 #25	Output	VDD33	Clock output
	ENCIFOE02	CN43 #27	Output	VDD33	Data output enable
	ENCIFDO02	CN43 #21	Output	VDD33	Data output
	ENCIFDI02	CN43 #23	Input	VDD33	Data input

Channel	Pin Name	Pin Header	Input/ Output	Voltage Domain	Description
AFMT3 / ENDAT_CH3 *1	ENCIFCK03 *2	CN43 #16	Output	VDD1833_6	Clock output
	ENCIFOE03	CN43 #18	Output	VDD1833_6	Data output enable
	ENCIFDO03	CN43 #22	Output	VDD1833_6	Data output
	ENCIFDI03	CN43 #24	Input	VDD1833_6	Data input
AFMT4 / ENDAT_CH4 *1	ENCIFCK04 *2	CN44 #21	Output	VDD33	Clock output
	ENCIFOE04	CN44 #23	Output	VDD33	Data output enable
	ENCIFDO04	CN44 #25	Output	VDD33	Data output
	ENCIFDI04	CN44 #27	Input	VDD33	Data input
AFMT5 / ENDAT_CH5 *1	ENCIFCK05 *2	CN43 #8	Output	VDD1833_6	Clock output
	ENCIFOE05	CN43 #10	Output	VDD1833_6	Data output enable
	ENCIFDO05	CN43 #12	Output	VDD1833_6	Data output
	ENCIFDI05	CN43 #14	Input	VDD1833_6	Data input
AFMT6 / ENDAT_CH6 *1	ENCIFCK06 *2	CN42 #12	Output	VDD1833_3	Clock output
	ENCIFOE06	CN42 #14	Output	VDD1833_3	Data output enable
	ENCIFDO06	CN42 #16	Output	VDD1833_3	Data output
	ENCIFDI06	CN42 #18	Input	VDD1833_3	Data input
AFMT7 / ENDAT_CH7 *1	ENCIFCK07 *2	CN42 #22	Output	VDD1833_3	Clock output
	ENCIFOE07	CN42 #24	Output	VDD1833_3	Data output enable
	ENCIFDO07	CN42 #34	Output	VDD1833_3	Data output
	ENCIFDI07	CN42 #36	Input	VDD1833_3	Data input
AFMT9 / ENDAT_CH9 *1	ENCIFCK09 *2	CN51 #12	Output	VDD1833_2	Clock output
	ENCIFOE09	CN51 #14	Output	VDD1833_2	Data output enable
	ENCIFDO09	CN51 #16	Output	VDD1833_2	Data output
	ENCIFDI09	CN51 #18	Input	VDD1833_2	Data input
AFMT10 / ENDAT_CH10 *1	ENCIFCK10 *2	CN51 #21	Output	VDD1833_2	Clock output
	ENCIFOE10	CN51 #23	Output	VDD1833_2	Data output enable
	ENCIFDO10	CN51 #25	Output	VDD1833_2	Data output
	ENCIFDI10	CN51 #27	Input	VDD1833_2	Data input
AFMT11 / ENDAT_CH11 *1	ENCIFCK11 *2	CN51 #20	Output	VDD1833_2	Clock output
	ENCIFOE11	CN51 #22	Output	VDD1833_2	Data output enable
	ENCIFDO11	CN51 #24	Output	VDD1833_2	Data output
	ENCIFDI11	CN51 #26	Input	VDD1833_2	Data input
AFMT13 / ENDAT_CH13 *1	ENCIFCK13 *2	CN43 #26	Output	VDD1833_6	Clock output
	ENCIFOE13	CN43 #28	Output	VDD1833_6	Data output enable
	ENCIFDO13	CN43 #30	Output	VDD1833_6	Data output
	ENCIFDI13	CN43 #32	Input	VDD1833_6	Data input
AFMT14 / ENDAT_CH14 *1	ENCIFCK14 *2	CN42 #27	Output	VDD33	Clock output
	ENCIFOE14	CN42 #31	Output	VDD33	Data output enable
	ENCIFDO14	CN42 #33	Output	VDD33	Data output
	ENCIFDI14	CN42 #35	Input	VDD33	Data input

Note: 1. The pins are not used in the initial channel configuration. When the channel used is changed, the corresponding pin header is used.

Note: 2. In A-format, the clock pin ENCIFCK is not used.

3.3 Procedures for Development Environments: CR52 ver.

3.3.1 Preparation before Executing the Sample Program

This sample program communicates with a PC. The USB connection terminal on the target board is CN27.
Select higher-numbered port from COM ports that appear when connecting the board with the host PC.

The terminal software of the host PC is set as shown in the following table.

Function	Setting
Communication method	Asynchronous serial transmission/reception
Order of transmission / reception	LSB first
Transfer rate	19200 bps
Character length	8 bits
Stop bit length	1 bit
Parity function	None
Hardware flow control	None

3.3.2 EWARM from IAR Systems

(1) Build Environment

IAR Embedded Workbench for Arm (EWARM)

Version 9.60.3 + patch (EWARM_Patch_for_RZT2H_N2H_rev1.0)

RENESAS FSP Smart Configurator (FSP SC) 2025-12

RENESAS Flexible Software Package (FSP) for RZ v4.0.0

(2) Execution Environment ICE

IAR I-jet

(3) Build Procedure for Sample Programs

The build procedure for the sample program is as follows.

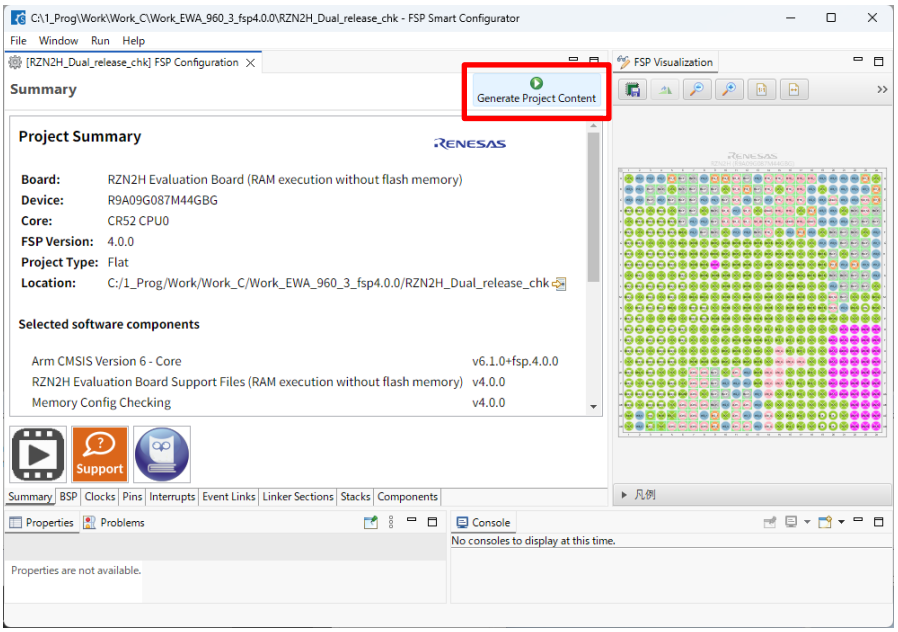
1 Extract RZ_N2H_CR52_dual.zip and copy the extracted source files to the desired location.
2 Activate EWARM.
3 Select [File] menu -> [Open Workspace].
4 Open the extracted source file RZ_N2H_dual.eww.
5 Start the FSP Smart Configurator from the [Tools] menu of the EWARM IDE. *

Note: The following procedure adds an item to launch FSP Smart Configurator to the [Tools] menu of the EWARM IDE. Select [Tools] menu -> [Tool Configuration] in the EWARM IDE. Select the [New] button, specify the strings shown in the table for each field, and press [OK].

Field	String
Menu text	FSP Smart Configurator
Command	$RASC_EXE_PATH$
Argument	--compiler IAR configuration.xml
Initial directory	$PROJ_DIR$

The string for the command is a variable that holds the path to the Smart Configurator execution file, rasc.exe.
If the path written as RASC_EXE_PATH in the buildinfo.ipcf file does not match your rasc.exe installation path, please edit the buildinfo.ipcf to fit with your installation path.
You can also start the FSP Smart Configurator directly from the command prompt by specifying the folder where it is installed.

6 In the FSP Configuration pane of the Smart Configurator, click Generate Project Content. The rz, rz_cfg, rz_gen, script, and .settings folders will be generated.



7 When project generation is complete, close the Smart Configurator.
8 Select [Rebuild All] from the [Project] menu of EWARM.
The file Debug\Exe\RZ_N2H_dual.out is generated.

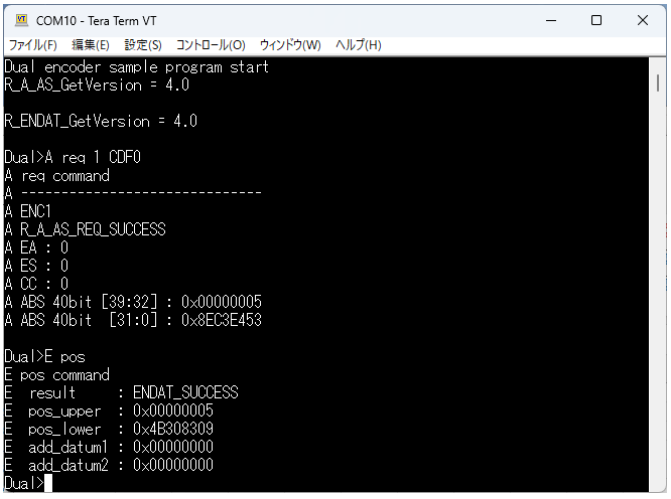
(4) Sample Program Execution Procedure

After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Project] menu -> [Download and Debug].
2 Select [Debug] menu -> [Execute].

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.15.10 console commands in the RZ/N2H Group Dual Encoder Sample Program Application Note.



3.3.3 e² studio from RENESAS

(1) Build Environment

RENESAS e² studio 2025-12

Toolchain version: GNU Arm Embedded 13.3.1.arm-13-24

RENESAS Flexible Software Package (FSP) for RZ v4.0.0

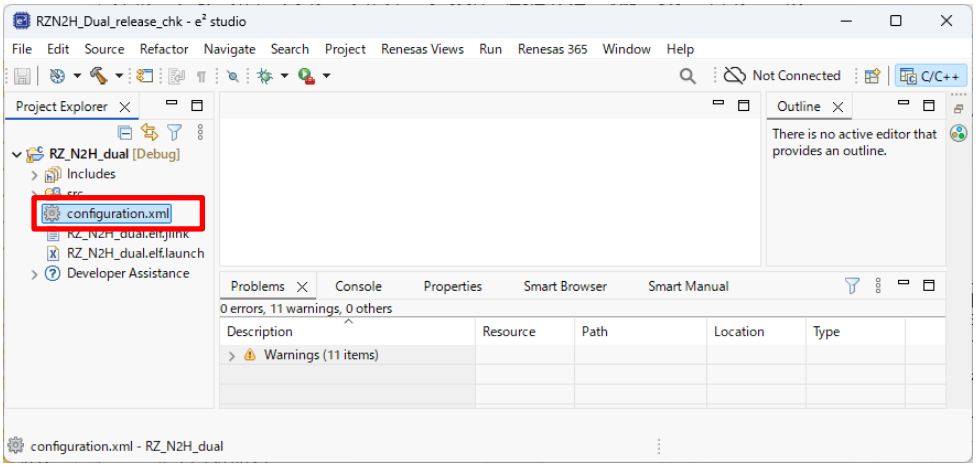
(2) Execution Environment ICE

SEGGER J-Link™ v8.60

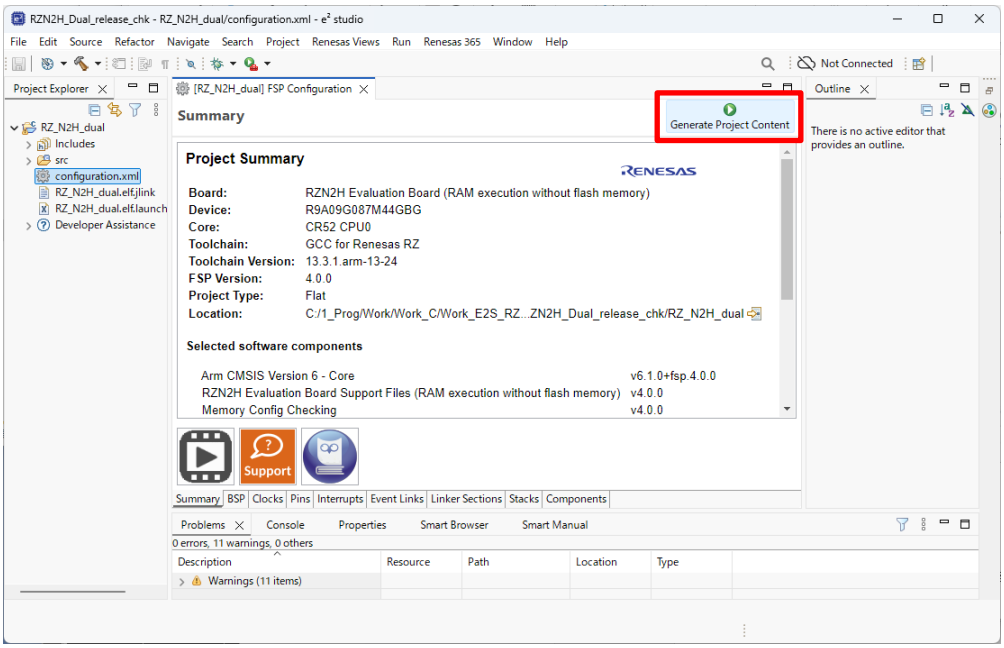
(3) Build Procedure of the Sample Program

The procedure for building the sample program is as follows.

1. Extract RZ_N2H_CR52_dual.zip and copy the extracted source files to the desired location.
2. After launching e² studio and moving to the workspace, click the [File] menu -> [Import] and select Existing Projects into Workspace and click [Next].
3. On the project import screen, select the folder where the sample program was expanded as the root directory.
4. Select a project, check Copy projects into workspace, and click [Finish].
5. Double-click the configuration.xml in the Project Explorer pane of e² studio to open it.



6 Click Generate Project Content in the FSP Configuration pane of e² studio.
The rz, rz_cfg, rz_gen, script, and .settings folders are generated.



7 Select [Project] menu -> [Build All]
The file Debug\RZ_N2H_dual.elf is generated.

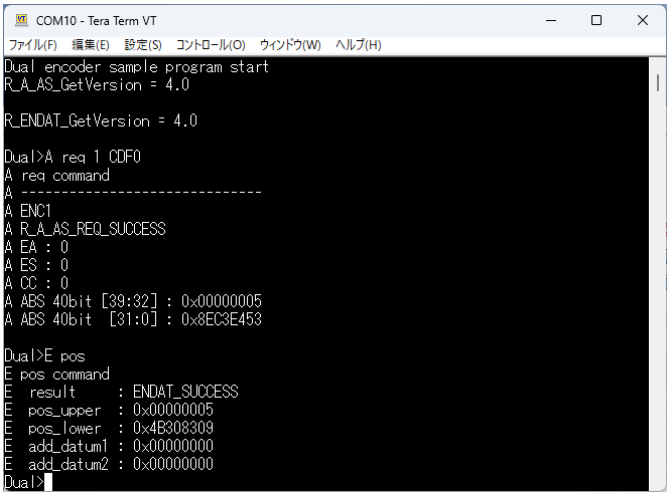
(4) Execution Procedure of the Sample Program

After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Run] menu -> [Debug As] -> [Renesas GDB Hardware Debugging].
2 Click [Debug] to start downloading the program to internal RAM.
3 Click [Run] menu -> [Resume] to run the sample program.

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.15.10 console commands in the RZ/N2H Group Dual Encoder Sample Program Application Note.



3.4 Procedures for Development Environments: CA55 ver.

3.4.1 Preparation before Executing the Sample Program

This sample program communicates with a PC. The USB connection terminal on the target board is CN27. Select lower-numbered port from COM ports that appear when connecting the board with the host PC.

The terminal software of the host PC is set as shown in the following table.

Function	Setting
Communication method	Asynchronous serial transmission/reception
Order of transmission / reception	LSB first
Transfer rate	19200 bps
Character length	8 bits
Stop bit length	1 bit
Parity function	None
Hardware flow control	None

3.4.2 EWARM from IAR Systems

(1) Build Environment

IAR Embedded Workbench for Arm (EWARM)

Version 9.60.3 + patch (EWARM_Patch_for_RZT2H_N2H_rev1.0)

RENESAS FSP Smart Configurator (FSP SC) 2025-12

RENESAS Flexible Software Package (FSP) for RZ v4.0.0

(2) Execution Environment ICE

IAR I-jet

(3) Build Procedure for Sample Programs

The build procedure for the sample program is as follows.

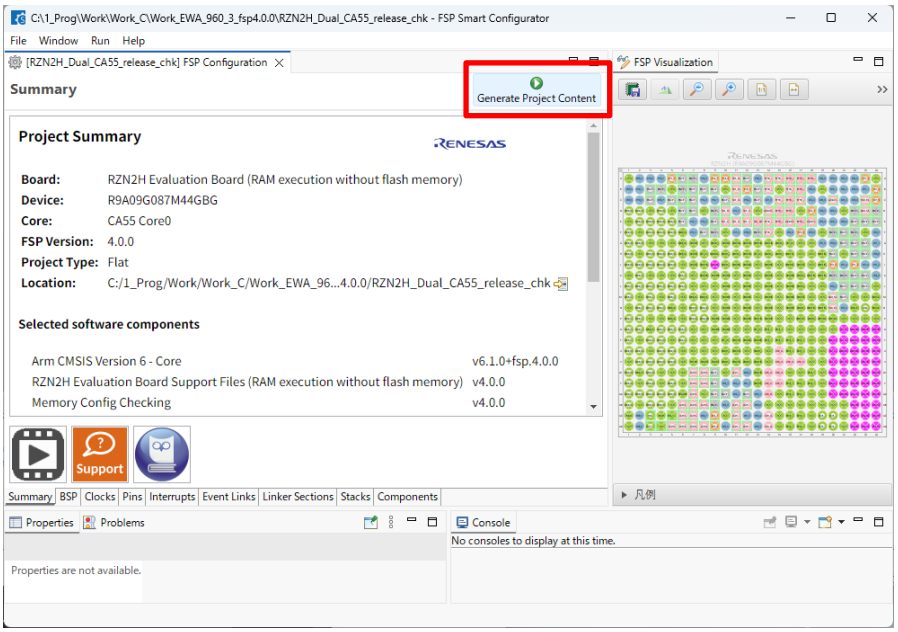
1 Extract RZ_N2H_CA55_dual.zip and copy the extracted source files to the desired location.
2 Activate EWARM.
3 Select [File] menu -> [Open Workspace].
4 Open the extracted source file RZ_N2H_CA55_0_dual.eww.
5 Start the FSP Smart Configurator from the [Tools] menu of the EWARM IDE. *

Note: The following procedure adds an item to launch FSP Smart Configurator to the [Tools] menu of the EWARM IDE. Select [Tools] menu -> [Tool Configuration] in the EWARM IDE. Select the [New] button, specify the strings shown in the table for each field, and press [OK].

Field	String
Menu text	FSP Smart Configurator
Command	$RASC_EXE_PATH$
Argument	--compiler IAR configuration.xml
Initial directory	$PROJ_DIR$

The string for the command is a variable that holds the path to the Smart Configurator execution file, rasc.exe.
If the path written as RASC_EXE_PATH in the buildinfo.ipcf file does not match your rasc.exe installation path, please edit the buildinfo.ipcf to fit with your installation path.
You can also start the FSP Smart Configurator directly from the command prompt by specifying the folder where it is installed.

6 In the FSP Configuration pane of the Smart Configurator, click Generate Project Content. The rz, rz_cfg, rz_gen, script, and .settings folders will be generated.



7 When project generation is complete, close the Smart Configurator.
8 Select [Rebuild All] from the [Project] menu of EWARM.
The file Debug\Exe\RZ_N2H_CA55_0_dual.out is generated.

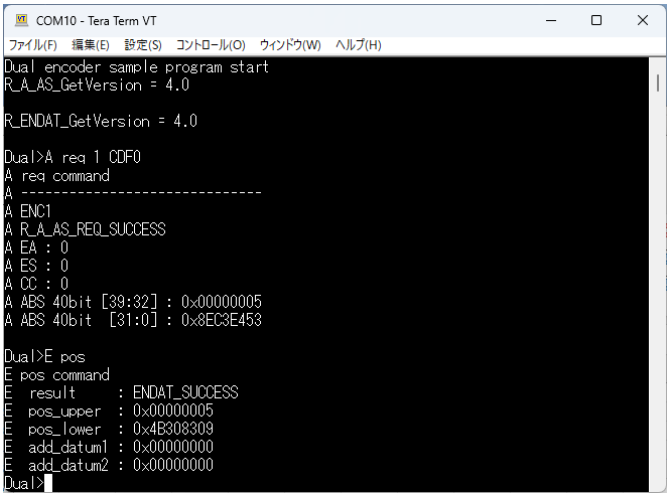
(4) Sample Program Execution Procedure

After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Project] menu -> [Download and Debug].
2 Select [Debug] menu -> [Execute].

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.15.10 console commands in the RZ/N2H Group Dual Encoder Sample Program Application Note.



3.4.3 e² studio from RENESAS

(1) Build Environment

RENESAS e² studio 2025-12

Toolchain version: GCC Arm A-Profile (AArch64 bare-metal) 13.2.1.20231009

RENESAS Flexible Software Package (FSP) for RZ v4.0.0

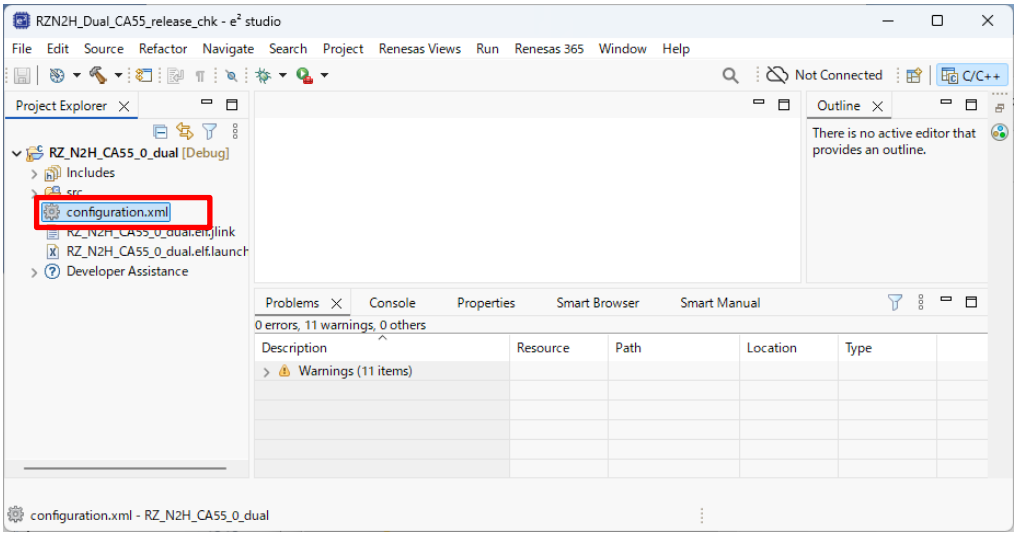
(2) Execution Environment ICE

SEGGER J-Link™ v8.60

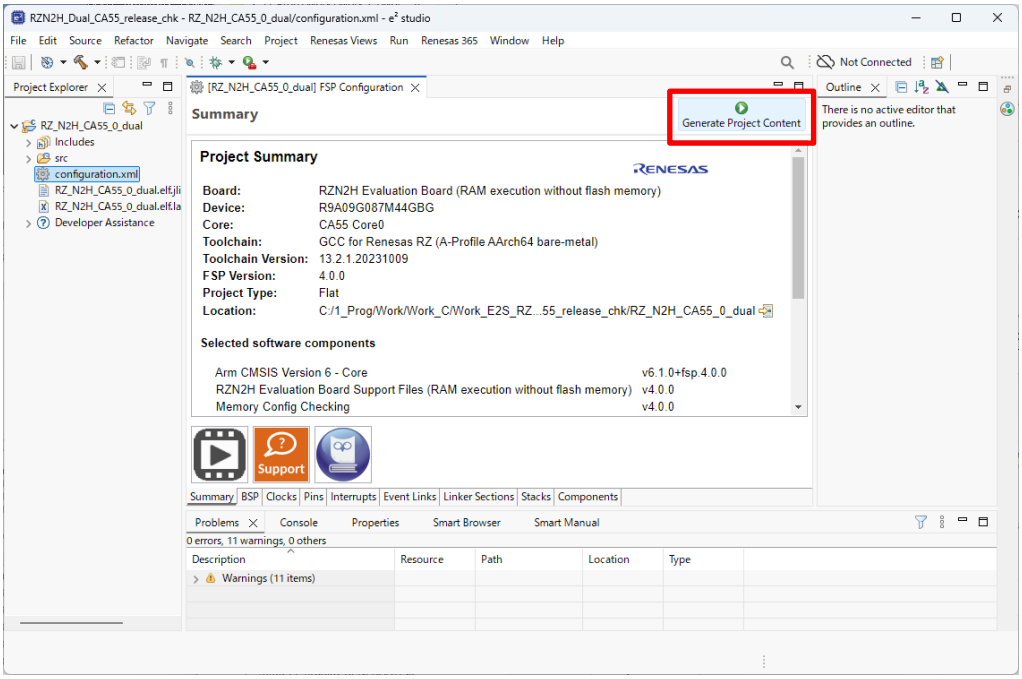
(3) Build Procedure of the Sample Program

The procedure for building the sample program is as follows.

1. Extract RZ_N2H_CA55_dual.zip and copy the extracted source files to the desired location.
2. After launching e² studio and moving to the workspace, click the [File] menu -> [Import] and select Existing Projects into Workspace and click [Next].
3. On the project import screen, select the folder where the sample program was expanded as the root directory.
4. Select a project, check Copy projects into workspace, and click [Finish].
5. Double-click the configuration.xml in the Project Explorer pane of e² studio to open it.



6 Click Generate Project Content in the FSP Configuration pane of e² studio.
The rz, rz_cfg, rz_gen, script, and .settings folders are generated.



7 Select [Project] menu -> [Build All]
The file Debug\RZ_N2H_CA55_0_dual.elf is generated.

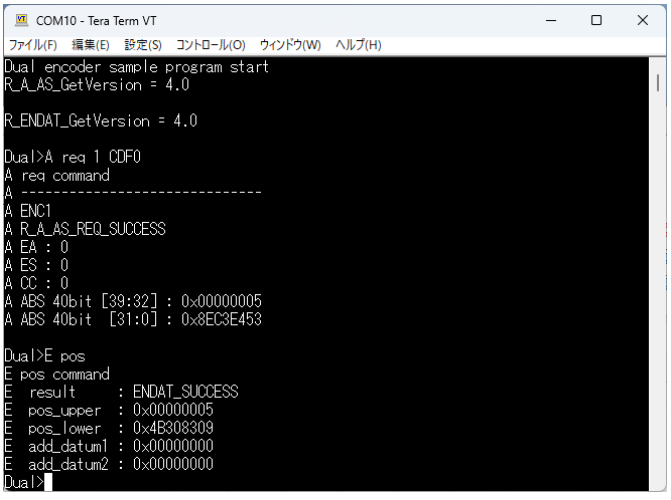
(4) Execution Procedure of the Sample Program

After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Run] menu -> [Debug As] -> [Renesas GDB Hardware Debugging].
2 Click [Debug] to start downloading the program to internal RAM.
3 Click [Run] menu -> [Resume] to run the sample program.

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.15.10 console commands in the RZ/N2H Group Dual Encoder Sample Program Application Note.



Revision History

Rev.	Date	Description	
		Page	Summary
2.00	Mar.28.25	-	First Edition issued.
3.00	Nov 28.25	2, 3	Update revisions of the application note and the release note. Update sample program version to 3.0. (Support FSP v3.0.0.)
		4	Update memory size information.
		7 to 14	Update build environment for FSP v3.0.0. Figures are replaced.
4.00	May 15.26	2, 3	Update revisions of the application note and the release note. Update sample program version to 4.0. (Support FSP v4.0.0.) Update file structure.
		4	Update memory size information.
		6	Correct AFMT13/ENDAT_CH13 pin assignment.
		7 to 14	Update build environment for FSP v4.0.0. Figures are replaced.

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)
   A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.
2. Processing at power-on
   The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.
3. Input of signal during power-off state
   Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.
4. Handling of unused pins
   Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.
5. Clock signals
   After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.
6. Voltage application waveform at input pin
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).
7. Prohibition of access to reserved addresses
   Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.
8. Differences between products
   Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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